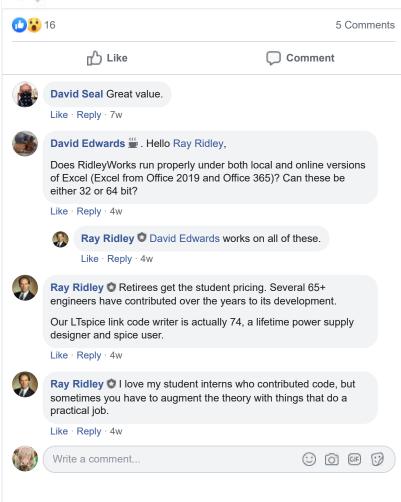


Home



# New RidleyWorks® Software Lifetime License

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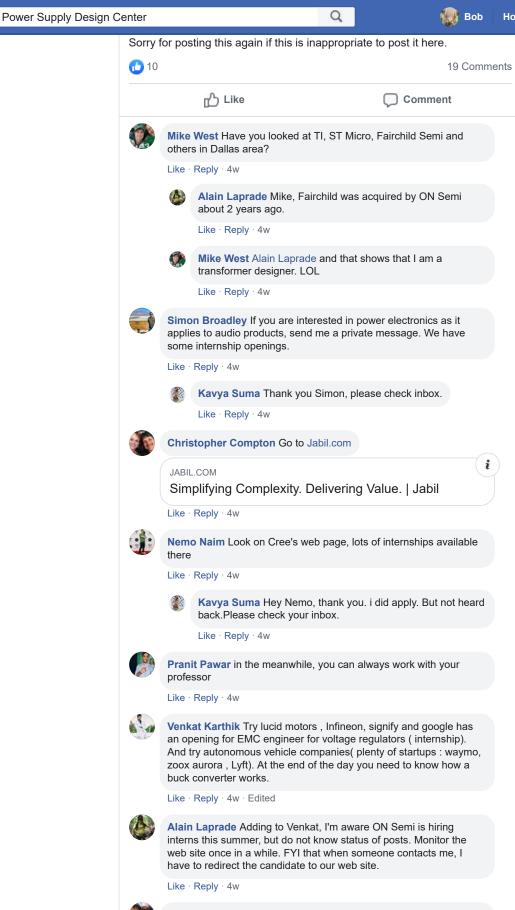




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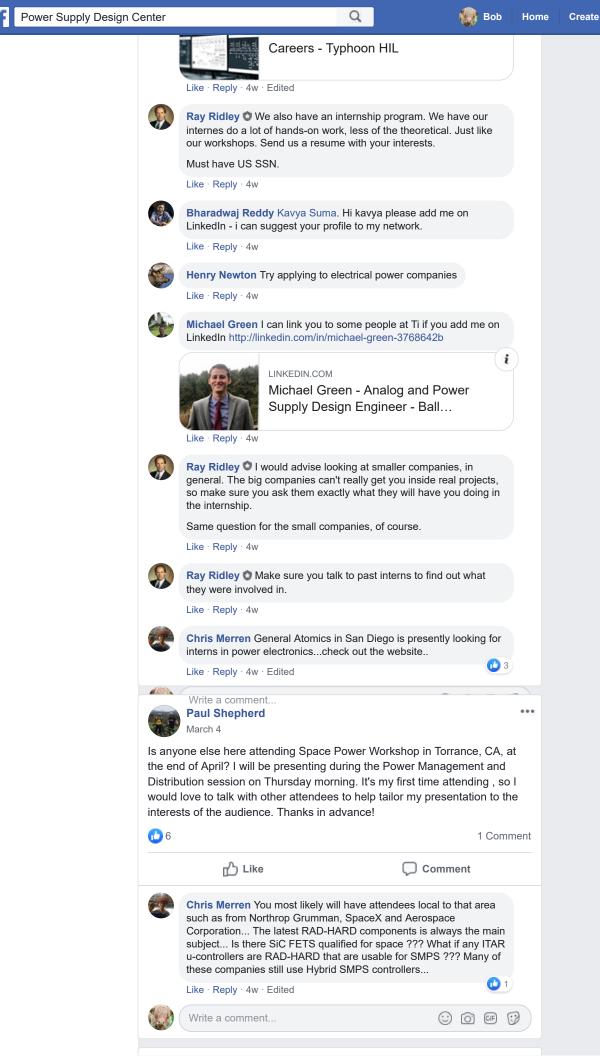
Hi everyone, I know this might be inappropriate to post here, but I think this might be the only group that actually help me.

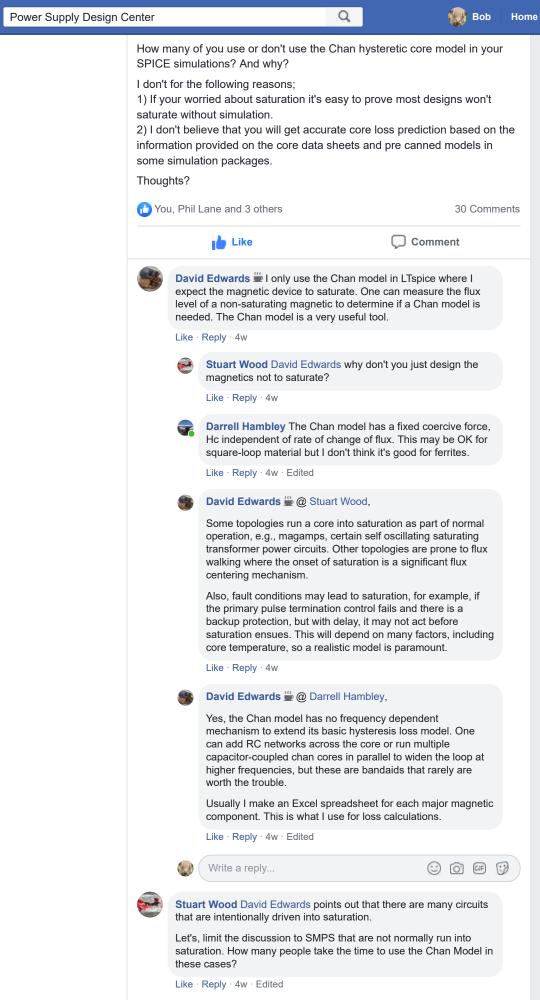
I am a master's student in Electrical Engineering at University of Texas at Austin working in Power electronics field, under Prof.Alex, I am looking for an internship opportunity for this summer and fall 2020 in Power electronics field but not able to find any leads and my sole purpose of doing master's was to be able to switch my field from digital area (NVIDIA, where I have been doing digital work full-time) to work in the area of my interest, but I am disappointed that I am not able to do that even after working hard to get here





Marcus Lim I think Typhoon HIL is a great internship option for you. You have both power and digital electronics background and Typhoon is working on emulating real power electronics systems in the digital realm. https://www.typhoon-hil.com/careers/ You'll have to travel to Europe though.

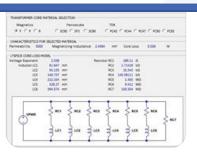






Ray Ridley © Chan is overly complex for a quantity is purely empirical. We use the following simple circuit. Why overcomplicate?

Home



Like · Reply · 4w



Stuart Wood Ray Ridley does this model also contain the leakage inductance, if you generate it from the frequency response of the primary with the secondary winding shorted?

Q

Like · Reply · 4w



Ray Ridley This model is derived directly from the Core

Put in your material, and the circuit model comes out.

The leakage is derived separately from the winding arrangement that is put into the program. We get pretty close, although we don't attempt to model the changing leakage with frequency. The world isn't ready for that yet, apparently.



Like · Reply · 4w



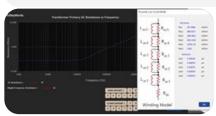
Stuart Wood Ray Ridley I'm sorry I'm ment the LR network for the winding loss. Does that include leakage.

Like · Reply · 4w · Edited



Ray Ridley No, separate component. We have an LR network for leakage too, but haven't activated that in our software yet.

You can see in the model below that the 10 uH leakage is not part of the winding model.



Like · Reply · 4w



Write a reply...











David Edwards . Hello Ray Ridley,

The Chan model captures low frequency hysteresis loss only. Your loss model is better in that it represents total core loss over frequency, but it does not model saturation, which, when needed, is a good reason to use the Chan model.

Like · Reply · 4w



Ray Ridley 1 If you have saturation, you shouldn't be designing power supplies......

Look for it, if you see it, add turns as needed, and stop trying to model it.





Magamps, self oscillating saturating topologies, flux walking?

Like · Reply · 4w



Ray Ridley The needs of the 1% shouldn't drive the model complexity of the 99%.

I know what you are saying, my first ever design depended on saturation. It was just modeled with a single line of PWL code which did fine. Later on we eliminated the need for a saturating inductor since it overheated - as do just about all of

I sincerely doubt any simulation is going to track the realities of flux walking on the bench. That's why we see a lot of examples where a transformer saturates when the designer didn't see it in the simulation.

Like · Reply · 4w



Ray Ridley Our model also captures the extra loss when you have different duty cycles.

Like · Reply · 4w



Stuart Wood I agree, but I'm trying to get a sense of what people generally do. I'm working on a white paper on modeling magnetics. I know what I do but I don't want to speak for the rest of the world.

Like · Reply · 4w



Ray Ridley Tell us what you do, Stuart Wood.

Like · Reply · 4w



Stuart Wood Ray Ridley, I've been heavily influenced by you and others. At the start of a design I don't expect simulations to give me losses. I use them for proof of concept, in the areas of large signal performance, loop stability and rough estimate of losses in my semiconductors. If thing look ok then I move to a prototype. Build my magnetics and measure them. Build my magnetics models based on the measurements. Repeat Sims to see if they reflect the higher order effects on the prototype. Rinse and repeate. I've seen companies that are trying to reduce snubber losses in sim. When they've never properly characterised there magnetics! Only have a DC resistance and an estimate for leakage...

Like · Reply · 4w



Stuart Wood My general opinion is that engineers in Areospace like to latch onto things like the Chan Model or someone's implementation of Steinmetz equation when doing worst case analysis and think they have this great model, but when they don't study these in depth. It becomes garbage in garbage out.

Like · Reply · 4w · Edited



David Edwards @ @ Stuart Wood,

Garbage-in, garbage-out is the bane of injudicious simulation.

Like · Reply · 4w



Ray Ridley Completely agree, but it is not just the aerospace industry.

Like · Reply · 4w



Ray Ridley Core manufacturer's data is often woefully inadequate. But what else can you do?

At best it is typical loss, they explicitly say that. No such thing as worst-case data.

Like · Reply · 4w



Stuart Wood Ray Ridley that's one of the reasons I think it's garbage in, garbage out.





kay kiuley 👽 vveli, not entirely. A loss estimate, even il it typical, is better than nothing. Most simulations call the core loss zero, which is even more garbage.

Q

Our models match the curves, and also move with the duty cycle of the signal. They will overestimate, if anything.

Aerospace designers are really in a tough spot. They have to do WCA to satisfy the contract. We at least help them make an informed guess at it. As long as it is backed up by good thermal data, all is OK.

Like · Reply · 4w · Edited



Nicola Rosano I use similar RL ladder models for core losses and proximity effect. Cauer or Foster syntesis network approach

Like · Reply · 4w



Ray Ridley One day, everyone will do this. Congrats, Nicola Rosano, on being one of the first in our industry to go there.

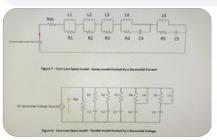
But it will be SLOOOOOW for everyone else to get there, especially as the magnetics companies are providing serious friction

With our software, it is so easy. 5 minutes in, and you have LTspice and PSIM models and circuits automatically generated, ready to run. You have to decide if it is worth spending a little money to move your analysis 100 years ahead of the conventional models.

Like · Reply · 4w · Edited



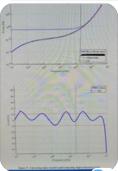
Nicola Rosano Mine. Airbus colleagues in UK confirm they continue to use that approach 😃



Like · Reply · 4w · Edited



Nicola Rosano Modeling error less than 10%. This was for 3C98 material if I'm not wrong



Like · Reply · 4w



Ray Ridley Interesting using Cs instead of Ls. I think I like that.

However the source should not be sinusoidal - has to be raised to a power or the characteristics aren't captured properly.

Like · Reply · 4w



Write a comment...











## **Ahmed Salah** March 1

Could connecting non-invasive current probes (like hall effect or rogowsky coil ) to the power circuit change the circuit performance or reduce the efficiency somehow? And why?



🚹 You and 3 others

14 Comments



Like





Jesus Elias Valdez Resendiz They will always take an small amount of energy to perform the measurment, but it can be considered neglectable in the case of active current probes

Like · Reply · 4w



Bryce Hesterman The data sheets of the Hall effect probes specify the insertion impedance as a function of frequency. The impedance increases significantly above the probe bandwidth. I expect that Rogowski probes would have less effect than Hall probes.



Ahmed Salah Bryce Hesterman ok that makes sense, thank you for the information

Like · Reply · 4w



Brian Faley If you have to lengthen the lead of power device or increase the loop inductance, the act of adding the probe can substantially alter circuit behavior for the worse.

Like · Reply · 4w

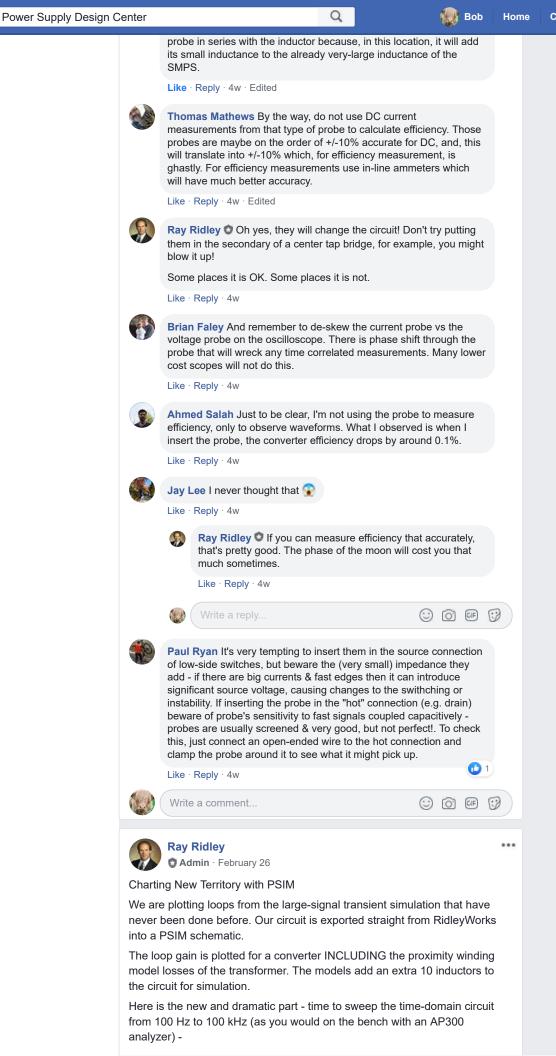


Ahmed Salah Brian Faley yes I understand. But actually even after that when I insert the probe or take it out the efficiency is different

Like · Reply · 4w



Alex Berestov Yes it could, yes it does. Why: due to the nature of things.



Like · Reply · 5w

pricing. I believe they have a lot of optional add on modules

that you probably don't need for most work.



Like · Reply · 5w



Nicola Rosano Ray Ridley I used it for years in 3 different companies. Below 15k is hard (1 network license). Without smartCTRL addon.

Like · Reply · 5w



Albert Dunford Nicola Rosano A permanent PSIM Pro standalone licnese without modules is under \$4k, there is an annual maintenance program that you can elect not to pay and then you don't get updates and low priority support. This will run any of the circuits exported from Ridleyworks. \$15K USD sounds like a network license with a bunch of modules.

Network licenses, modules for digital control, motors, code gen, links to simulink, vhdl, thermal models will add to that.

Like · Reply · 5w



Write a reply...











David Edwards ₩ Wasn't PSIM created expressly for this purpose (to measure loop gain in the transient domain)? How is this charting new territory? That the schematic is automatically generated?

Like · Reply · 5w



Ray Ridley No, it was created for speed and convergence. the sweep came later.

Like · Reply · 5w



**Nicola Rosano** I guess so. The AC sweep multisine function was created time ago and is pretty fast. I use it. The 'mapping procedure' seems to be a new feature.

Like · Reply · 5w · Edited

Hide 14 Replies



Ray Ridley You shouldn't use the multisine injection. theoretically faster if 4 seconds isn't good enough for you, but it is prone to errors.

It's a nonlinear system. You can't superimpose injections.

Like · Reply · 5w



Robert L Rauck Ray Ridley I never use multisine. The sequential sweep method is much slower for complex designs but the results are far superior. Now we are getting high speed.

Like · Reply · 5w



**Nicola Rosano** Nice point. There are two ways to get AC sweep in Psim (two different algorithms). The speed difference between them is huge. Multisine approach needs to be 'tuned' carefully to work properly.

True they are non linear system but one of psim strenght in just this: look at the stage as piecewise linear function block. I verified there is pretty good matching between AC multisine results and power stage equivalent linear model.

Like · Reply · 5w



Riccardo Tinivella Multitone analysis is the only way to get control loop from resonant topology not?

Like · Reply · 5w



Bryce Hesterman Nicola Rosano Not

Experience gained in LTspice was very useful in doing this.

Last few kinks in the fully automated setup schematic and script files are being resolved right now.

Like · Reply · 5w



David Edwards @ Ray Ridley, One of my coworkers used PSIM (I think it was PSIM). About five or so years ago I compared the transient loop-gain analysis of PSIM to SIMPLIS. SIMPLIS was faster and much cleaner, but it seems now that you have helped PSIM soup up their algorithms and programming and improve their performance.

I asked Mike Engelhardt several times to add this as a native feature to LTspice, but he didn't believe it was necessary when designing the compensation for current mode control ICs (pretty much all LTC makes). Now that Mike has left Analog Devices I don't expect LTspice to improve much except perhaps in the user interface.

Like · Reply · 5w · Edited



Albert Dunford Robert L Rauck We re-worked the sweep so that the sequential perturbation injection is much more intelligent. The original AC sweep in PSIM was very much brute force and a lot of time was wasted waiting for steady state

Like · Reply · 5w



**Albert Dunford** Riccardo Tinivella no multi-tone or msine is not the only way to get the open loop response of an LLC

Like · Reply · 5w



Ray Ridley David Edwards don't underestimate what ADI might do with LTspice. Mike was a genius at what he did, no one can ever match him.

However, he was philosophically opposed to doing Bode plots, so I wouldn't be surprised to see some improvements in that area.

ADI and LT have a culture of hiring really bright people. There are lots of PhDs from Virginia Tech and elsewhere, so I think the future is very promising.

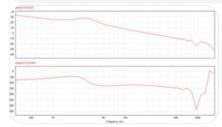
Like · Reply · 5w



Ray Ridley ① On the PSIM algorithms - they were working way too hard at getting convergence to a given error when I starting working with them. The first attempts at the sweep function were only about 2x faster than LTspice.

We have now accelerated that to be 100x faster than LTspice which is what it should always have been capable of. A little bit of bench knowledge goes a long way in speeding up the simulation whiz kids.

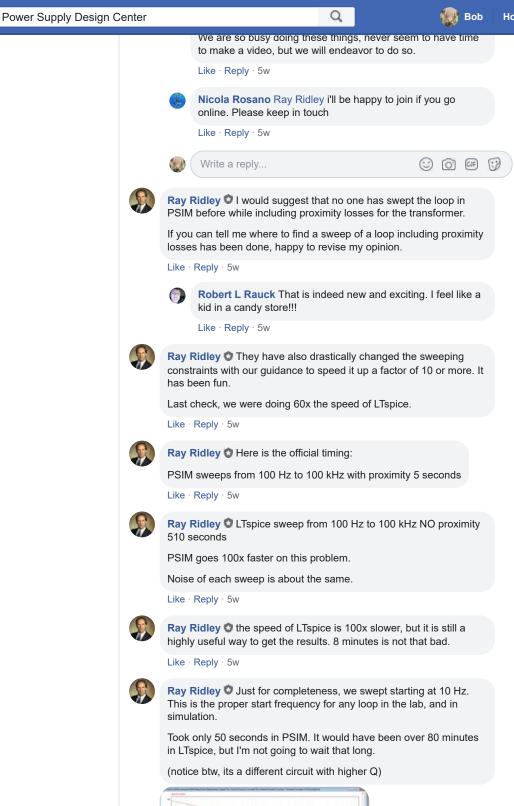
This is the latest sweep while on the phone with them just 5 minutes ago. It is amazingly clean.

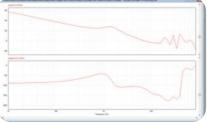


Like · Reply · 5w



Nicola Rosano Is there a video about that?





Like · Reply · 5w



Ray Ridley And here is the result direct from RidleyWorks.



Like · Reply · 5w



Robert L Rauck This is a Godsend!!

Like · Reply · 5w



Nicola Rosano I made a sort of similar comparison time ago for the three basic topologies: buck, boost and buckboost (without proximity). Linear modeling vs AC sweep results were perfectly superimposed for control to output and line to output transfer functions. Some high frequency deviations were present comparing input and output impedances.

Q

I should have 'octave' files somewhere.

Anyway where possible I continue to move for Vorperian solution. With variable frequency stages Psim features (or equivalent) become necessary.

Like · Reply · 5w



**Terence Orr** What's the advantage of running a transient simulation? Is an AC sim with averaged switch model not even faster? Can you plot this on top of AC sim result to show the difference/advantage?

Like · Reply · 5w



Ray Ridley Terence Orr yes we could plot it but you can too

For well behaved systems they align well.

Like · Reply · 5w



Ray Ridley Very often you have a control scheme that has not been modeled so no small signal model exists yet.

Simple CT sense current mode with a filter on the current is one example.

Of course we do Vorperian's model as well. It takes the 5 seconds down to a fraction of a second.

Many other advantages to the small signal approach in addition. But as mentioned the models don't always exist.

Like · Reply · 5w



**Bryce Hesterman** My experience is that transient simulations of current-mode control are much more accurate than averaged simulations because the current ramp gets distorted by things like noise filter, ringing and snubbers.

Like · Reply · 5w



**Norman Elias** Have you tried the DSIM platform that they're now pushing? Al Dunford just ran a Webinar on it. I'd be interested in hearing confirmation of his claims of 2-4 orders of magnitude of speed improvement over other simulators on the market. Pretty impressive.

Like · Reply · 5w



**Albert Dunford** Norman Elias If you are in north america I am happy to set you up with a beta license so you can see for yourself.

Like · Reply · 5w



Norman Elias Thanks Albert Dunford. I'll probably take you up on this offer. Please get back to me in a couple of weeks.

Q



Like · Reply · 5w



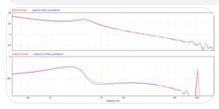
Albert Dunford The AC sweeps in PSIM are based on signal injection. So you can determine loop gains or transfer functions of any topology or control scheme, phase shift with PCMC, LLC, 3 phase with dq control, motor drive. DCM, CCM, etc.....

Like · Reply · 5w



Ray Ridley Learning more about PSIM. Here is the before and after of the transfer function with and without transformer proximity

Not a huge change, just a shift in the damping of the LC filter, as might be expected.



Like · Reply · 5w



Ray Ridley Core loss made no difference to the loop. Does anyone know why?

This is another first - the transfer functions of a converter with both core loss and proximity losses taken into account.

Like · Reply · 5w



Nicola Rosano Ray Ridley intuitively speaking if you model core losses paralleling a RL ladder (high values typically) to the primary inductance, the equivalent impedance of the added branch continues to be much greater respect the primary inductance impedance one on all frequency range. It remains transparent.

Like · Reply · 5w



Colin Tuck presumably core loss is small is the main reason...

Like · Reply · 5w



Ray Ridley Not only that, there is more to the answer.

Like · Reply · 5w



Colin Tuck In the fwd topology the core loss is just a load on the HVDC - so does not participate in any type of loop filter ...?

Like · Reply · 5w



Ray Ridley that's right. It's just a parallel load on the transformer and doesn't affect the duty cycle in any way.

Hence you probably would't include it in the PSIM or LTspice sweeps since it will slow things down.

When you are doing the transient sweeps, of course, that is when it works great. Run the sim, click on the core, and you see the loss. No more tables to look up.

Like · Reply · 5w



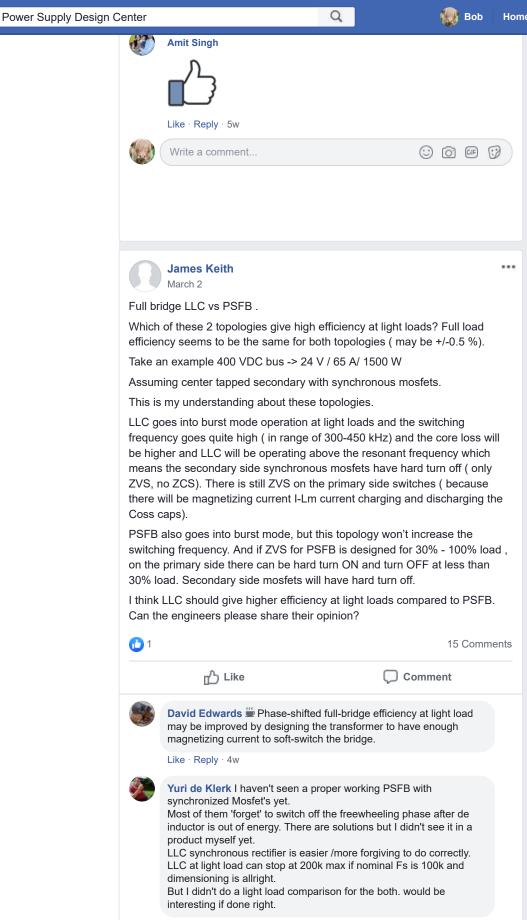
Norman Elias Ray, do you know if the core loss display is a feature of the simulator or is it built into the transformer model.

Like · Reply · 5w



Ray Ridley We provide the simulator with our core loss model. The simulator can then provide the loss numbers to you.

We do the same for the proximity loss elements.









A Practical Approach to the Design of a Highly Efficient PSFB DC-DC...

Like · Reply · 4w



George T. Ottinger 1) Your claim about the secondary rectifiers is not correct - LLC has ZCS on secondary diodes always.

2) Your claim about always going above resonance is also not strictly true. If your input voltage and transformer turns ratio are set properly, you can operate at resonance. Resonance is (ideally) a load independent operating point. Adjust your input voltage (if possible - assuming a front end boost converter) on the fly to keep the LLC at resonance.

3) Like PSFB, the magnetizing current can be designed to give ZVS to the primary switches, but, higher Imag affects conduction losses in the switches.

Like · Reply · 4w · Edited



Manuel Escudero Rodríguez The claim of the LLC synchronous rectifiers it is correct, they are hard commutated through the primary while working above resonance (Qrr loss) even though they can be always ZVS.

Like · Reply · 4w



James Keith George T. OttingerWhat happens to the frequency during burst mode? how do you ensure the secondary side mosfets to have both ZVS and ZCS during burst mode?

Like · Reply · 4w



George T. Ottinger James Keith The LLC is just a form of a series resonant converter. The secondary side currents are sinusoidal in nature, always. Thus, your rectifiers always naturally commutate when the current "rings" to zero.

If you go above resonance, the time of secondary diode commutation is shifted from the gating of the primary FETs.

ZVS is not applicable. At the moment of switching, for ANY synchronous rectifier, whether it be an LLC or PSFB, the channel of the FET better be off and it is only the diode conducting. If the gate is still on when the diodes want to naturally commutate, you better have a good supply of spare FETs and a good soldering iron.

Perhaps you should simulate the basic circuit to see the waveforms.

Like · Reply · 4w · Edited



George T. Ottinger Manuel Escudero Rodríguez The secondary diodes only commutate when the primary side resonant inductor current equals the magnetizing current. At that point, the transformer current is zero, and the rectifiers naturally commutate at zero current on the secondary. If your synchronous FET gate is on at that time, on either FET, then you have a control problem.

Like · Reply · 4w

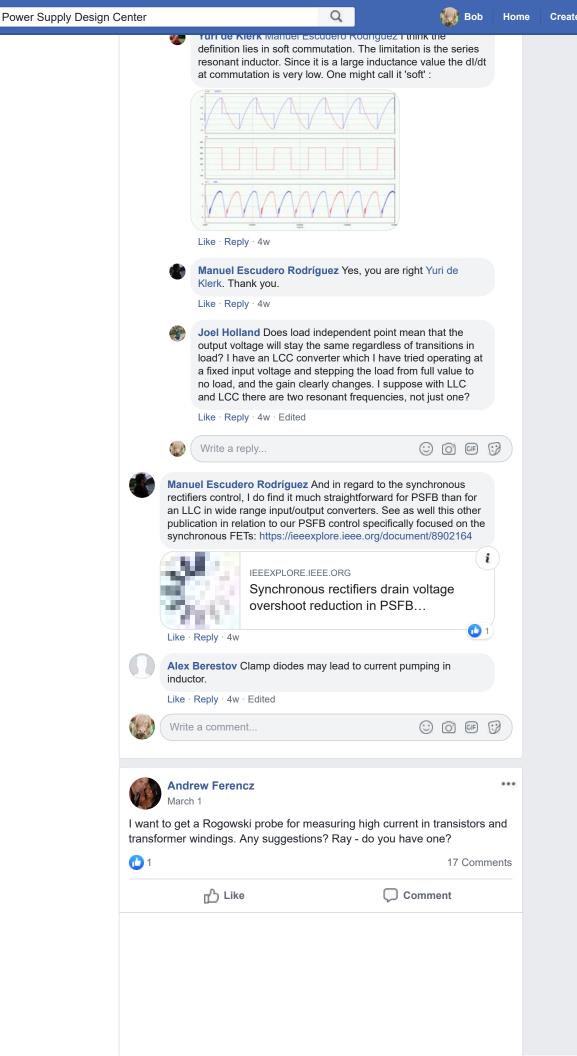


Manuel Escudero Rodríguez Dear George, above resonance the diodes start to COMMUTATE after the primary side devices alternate the polarity of the voltage at the input of the series resonant tank. The channel of the synchronous rectifiers can be SWITCHED on (and off) in ZVS and potentially in Zero Current. However, because they are not soft commutated (the only limitation is the series resonant inductor) there is Qrr loss. The waveforms are not sinusoidal above resonance.

Like · Reply · 4w



Manuel Escudero Rodríguez Thank you for your recommendations, I do have simulated the circuit beyond the basics, build many converters and programmed the control for them. No, I do not have any control problem.



i



gets the most usage in our common applications (3-20kW). http://www.pemuk.com/products/cwt-current-probe.aspx

We've found then accurate and reliable, with the ultra-minis being pretty robust. We have a designated one that gets used when a pair of pliers is needed to force them into odd spots and it's still going strong.

Powering them is the biggest pain in the rear. If using batteries, they do tend to eat them, and they can go a little strange sometimes when the batteries are getting flat.

My preference is to run them off the AC adapters, but that gets unwieldy if you've got 3-4 on the bench, so it helps to have some extra plug-boards mounted somewhere to keep things tidy. The bodies are also a little bit annoying, shape wise, and if you stack them then the power buttons can get pushed, leading to irritating troubleshooting. I haven't quite come up with anything convenient for that yet, but eventually may just open them and bridge the switch to be on permanently. The power LED could do with being a bit brighter, too.



PEMUK.COM

CWT Current Probe | PEM

Like · Reply · 4w



Andrew Mosqueda Before measuring, make sure that the circuit is robust because when the transistor blows, goodbye mr. Rogowski

Like · Reply · 4w



Jonathan Beaver Weird, that has not been my experience at all. We have never killed one, despite using them while testing devices to destruction.

Like · Reply · 4w



Alex Berestov Pretty damn good. It even inspired me to make my own (passive) instead of CT and calibrated it using pemuk. However it has "zeroing noise" by the looks, so if you are to measure 30A buy 30A probe.

P.S. As a student I've made Rogovski coil to control saturation in push-pull converter (What is the proper name: flux wandering??) but it really did not fly.

Like · Reply · 4w



**Brian Faley** PEM. Used the mini and ultra mini. Unless you spring for the extra shielding, they do capacitively couple high dv/dt switching edges, so there are some vertical artifacts. And they do not of course work for dc. The only complaint is that the power switch button sticks out for "on", and is in for "off". Keep spare batteries handy. We never used dc adapters, too much risk of high voltage faults. PEM has a flat rate repair price.

Like · Reply · 4w



Ray Ridley Rogowski coils are quite useful. The only problem I ran into is that the HF ringing and overshoot can be a function of the active compensation that is applied, and not representative of the real waveform.

So it depends on what you are wanting to use it for, but you might as well add it to the toolkit.

Like · Reply · 4w



Charlie Elliott As others have said, PEM. I have been using their parts for 20 years+. If you have the space for a slightly fatter coil then get one of the shielded ones. Without this you will get a bit of capacitive coupling pickup. Especially important with high dv/dts.

Like · Reply · 4w



John Baillie Charlie Elliott absolutely agree with this. Before inserting into you circuit it's interesting to place the (closed) probe close to the node you want to measure to see how much capacitive coupling there is.



Low Value, High Power, Surface...

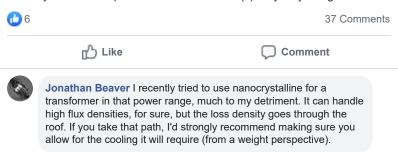
## Q

Weight most important factor - what switching frequency and core material for 20-30kW?

Following on from my optimisation scoring post, I had a new set of scores to me on Friday (1 = most important to customer)

- (Low) Weight = 1
- (Small) Size = 4
- (High) Efficiency = 3
- (Low) Development Cost = 7
- (Fast) Time to Market = 4
- (Low) Unit Cost = 6
- (Good) Robustness/Reliability = 2

Clearly to minimise weight I will want to push switching frequency up and I have the option of using expensive core materials. My gut feel is to look at Nanocrystalline/Amorphous for the transformer(s). Anybody disagree?





Charlie Elliott Jonathan Beaver - Out of interest can you say what type of cores you were using? Did you pot them and if so with what?

Like · Reply · 5w

Like · Reply · 5w · Edited



**Jonathan Beaver** Charlie Elliott MK Magnetics I-bars to create a large custom shape.

We gave up and changed tack to several smaller units. Edit: Smaller ferrites on standard core shapes, rather than something large, expensive and unwieldy.

Our thermal requirements made the cooling of it unlikely, even with liquid cooling directly in contact with the magnetic elements.

Like · Reply · 5w · Edited



Col Johns For 30kW you either make 10 modules @ 3kW at 200kHz (for min size) or skip to 35kHz for the whole thing ...

Like · Reply · 5w



Charlie Elliott 3 x interleaved 10kW blocks at closer to 100kHz with ferrite?

Like · Reply · 5w



Col Johns you can do 10kW at 100kHz ( a lot of forklift chargers do 6kW at 100kHz ) but it can get messy ...

Like · Reply · 5w



**Daniel Pruna** High sw freq. and high power are fully compatible. https://www.iisb.fraunhofer.de/.../200\_kw\_full\_sic\_dcdc...

IISB.FRAUNHOFER.DE

200 kW Full-SiC DC/DC Converter

i

tnese rantastically dense prototype systems. The engineering is plentiful and superb. They often make use of bleeding edge technology to get there. Not sure how realisable it is for a product though?

Seeing that sea of large MLCCs makes me skeptical that it will last very long on the vibration table unless there is some serious mechnical structure and AV mounts employed =

Like · Reply · 5w



Col Johns This sort of thing is great as a spur to new designs and no doubt Fraunhofer is in direct competition with ETH Zurich - so they have to come up with something "good" now and again - but if it is fixed step down then it is a limited "break thru " (from 2014) a real DC/DC needs to be able to operate at near no load and with a fairly wide Vout range - this is why LLC ( CLL ) cannot be used in many apps as it cannot go to 0V Vout ... similarly for PSFB full current at low Vout is a no-no for many designs ...

Like · Reply · 5w



Stephen Berry Col Johns I have designed PSFB converters to drive superconducting magnets. With care they can run all day at full current (8000A in my case) into a perfect short.

Like · Reply · 4w



Col Johns Ah yes - but designed for it, we did an MRI design for 2 quadrant 12V 600A 50ppm way back - using simple H bridge - the main load is the Cu leads to the magnet ...

Like · Reply · 4w



Atish Tailor Stephen Berry for your Interest that particular PSU is still considered successful and still in production. We are now working on a 500A skinnyer version..

Like · Reply · 4w



Write a reply...











Arief Noor Rahman What about the weight for your cooling system?

I made 20kW PFC...around half of the weight is for heatsink+fan

Like · Reply · 5w



Arief Noor Rahman w My PFC just operate at 12kHz Fsw because we use igbt

Like · Reply · 5w



Charlie Elliott Indeed cooling system weight (including any potting compound used) can add a lot on.

Like · Reply · 5w



Alex Berestov My gut feeling is to use soft switching as main volume/weight reduction factor.

Losses are on par with a ferrite, however you can double flux density. This may be beneficial in DC/PFC inductors.

Now bad news

It's hard to get more than 0.5....0.7T from nano at 50...100k. Keep in mind that alloy density is about the same as Fe i.e. 7.8 almost two times of a ferrite. There could be no real incentive weight wise

Cooling is also impeded in tape cores. .

Unless you going to use toroidal X-formers stay away from nanocrystal/amorph even good ones with cobalt Fringe field and shorts at the cut increase losses 5 to 10 times. Cheers

P.S. Nnocrystal/amorph technology should of been more mature (less expensive) after 40 years.

Like · Reply · 5w · Edited

Home

uensity (0.75 1- 1.5 1) showithor the FTG toroids ( powe iron, amorphous Kool mu, Xflux etc) by Magnetics Inc are not practically usable at such high flux densities? Meaning can't I use the kool mu at 0.5 T ( datasheet shows 0.75 T). Although no information of temperature is given. But, seems like the calculations shown by Magnetics Inc for PFC boost show that Bmax of around: 0.5 T is reached. https://www.maginc.com/.../Kool-Mu-Cores/PFC-Boost-Design



Like · Reply · 5w

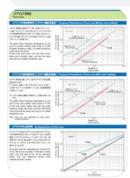


#### Venkat Karthik

1	Material	Alley Companion	Care Sans	Kin	Relative Cost	Setteration Flax Density (Seale)	Carle Imperators	Comparation Suspension	, Serie.
ľ	Andles	1453	fee	Setter	Refer	1.5	MF.C.	-37°C to 133°C	180
	Apt for	5/8	Relates	54	Adm.	15	5801	entwarr.	199
	Sail Sy	1458	law	Sed	liw	- 13	500"1	-01°Ch/30°C	100.600
	87	1486	Series .	Sele	100	875	401	611043810	3.00
	Ret	8/9	N/A	Bet	lav	14	7001	67(6)001(	Stiller
	Set Packs		fighet	And	(ped	13:15	mr.c.	-BPC67PC	500 Mb
	Jank	Special	Level	fee	lined	8.46	10-501	bolk	- Badle

Like · Reply · 5w

Alex Berestov Here is a quote from metglas/hitachi it was referred to:



Like · Reply · 5w



Alex Berestov And yes I did use such materials both cut and uncut, pun intended, since late 80's.

From the pic above FT3 material in container (Permalloy anybody) easily operates at B of 0.5...0.7 @ 50...100kHz. Real material is better BTW. However impregnated is not as good cut core even worse.

P.S. Managed to find old spreadsheet for inductors, PFC inductor, 3.3kVA/phase 50kHz, F3CC0040. H=6680, B=.76, H~=930, B~=0.105, Pcore sin=8.2W, Im=27A, Pcu25=4.6W. In reality, under forced air worked @ 7kW.

Like · Reply · 5w



Write a reply...











Arief Noor Rahman # I cant really say about magnetic material...

another way to make reduce converter weight is by paralleling many switches to reduce the total losses and distribute it over larger surface...reducing cooling requirement...

Modest Fsw at 20~30kHz should be good enough Two phase interleave may help as well



Like · Reply · 5w



**Hamish Laird** If you truly need robustness as a 2 then take really good care of the nanocrystaline core as they have some fantastically weird failure mechanisms from shock and vibration.

Like · Reply · 5w



Colin Tuck In that lineup, assigning reliability (quality) = 2 is a little at odds with unit cost = 6 and dev cost = 7 lowest weight (=1) strongly implies a lowish size which usually requires significant engineering input and testing ...

Like · Reply · 5w · Edited



Charlie Elliott Colin Tuck I should have been clearer. The scores are for Low unit and development cost! The customer is telling me we can put in plenty of engineering and use more expensive parts as those scores have lower priority.

Like · Reply · 5w



**Tony Salsich** Nanocrystalline cores are at their very best as CM chokes. Yes, they are somewhat delicate, but the boxed cores are fairly well protected. In fact high mu (10-15k) Ferrite is also easy to damage with shock. For either type of material the mu drops if stressed.

Like · Reply · 5w · Edited



Alex Berestov Most failures we had were from improper handling, mostly from mechanical stress, magnetization curve becomes like 100 times wider along with huge magnetostriction. Beware of the rust - most amorphs do.

Like · Reply · 5w



Charlie Elliott # I had unexplained significant increase in core loss on a prototype using some VAC cores a number of years ago (20!). I had always wondered whether they had been stressed somehow to cause the problem. They were potted in a reasonably hard material for good thermal conductivity and I was assured there was no magnetostriction to worry about but ....

Like · Reply · 5w



**Alex Berestov** Magnetostriction was a result of damage. Plastic container became deformed during transformer impregnation process: overheated.

Like · Reply · 5w



Charlie Elliott Meanwhile on the flip side of mechanical stress increasing core loss, let me share a little story. When I worked for a division of Emerson Electric involved in motor design, I visited a factory in the USA. Of the many different process areas I saw, the one that intrugued me most (intellectually) was the "Watt knocking". This involved some guys with arms like tree trunks picking up piles of stamped motor laminations and throwing them down on a large metal table to "knock the watts out" prior to the lams going into the annealing oven. The official line (from the engineers) was that this was to stop the lams sticking together so they were properly annealed and coated. The folk lore of the guys working on the line was that there was something else going on and you had to knock them just the right amount to let the watts out!!

Like · Reply · 5w · Edited

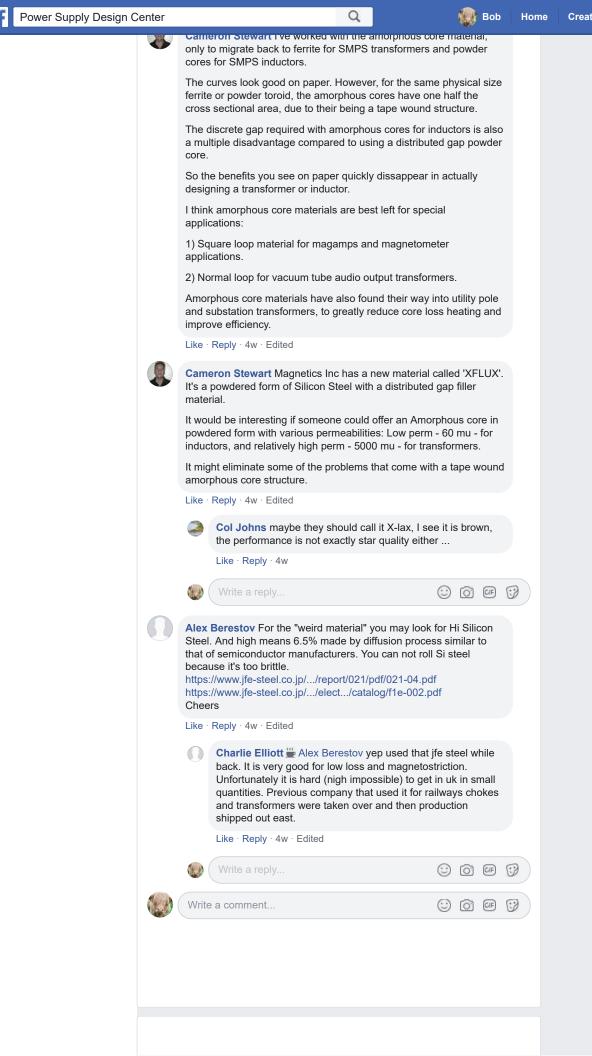


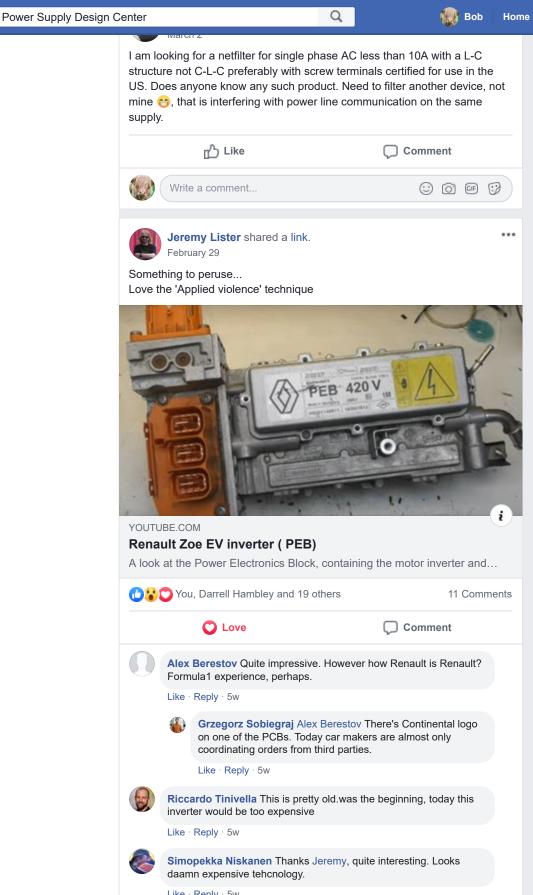
Charlie Elliott "I have edited the scoring metrics to be clearer.

Like · Reply · 5w



Alex Berestov If you apply vibration to an iron piece in a presence of Earth magnetic field for prolonged amount of time - it gets magnetized in a direction of the former for the fact. Stamping does exactly that. Perhaps mechanical shock was a cheap "degaussing".

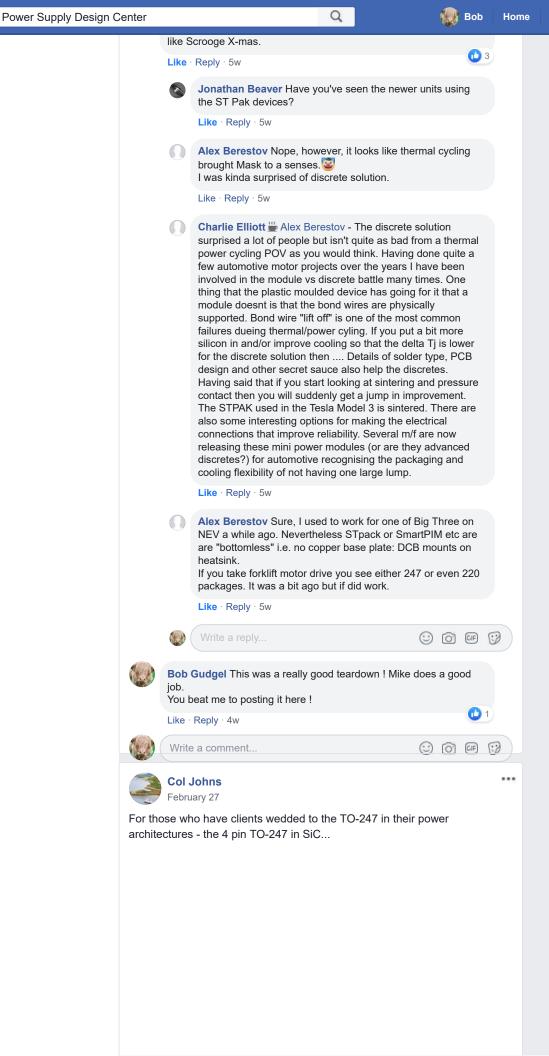




Like · Reply · 5w Jonathan Beaver Very interesting, looks pretty typical for early EV electronics from what I've seen. Huge, expensive and complicated, but probably fine for something getting made in the 10-100k/a range. I replaced the on-board charger in my older Nissan Leaf and it's

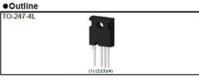
remarkable just how large and heavy that unit is for a 3.3kW on-

board charger. Like · Reply · 5w



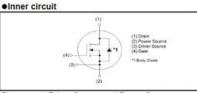
Home

$V_{DSS}$	1200V
R <sub>DS(on)</sub> (Typ.)	40mΩ
I <sub>D</sub> *1	55A
Pn	262W



### Features

- 1) Low on-resistance
- 2) Fast switching speed
- 3) Fast reverse recovery
- 4) Easy to parallel
- 5) Simple to drive
- 6) Pb-free lead plating; RoHS compliant



Please note Driver Source and Power Source are not exchangeable. Their exchange might lead to malfunction.



🚹 💟 You, Jay Philippbar and 10 others

32 Comments



Like



Comment



Col Johns We have used the previous std version with +15V on and -3V off - still going in the field ...

Like · Reply · 5w



Jonathan Beaver We've found the high internal gate impedance (7 ohms in this device) to make life somewhat difficult with this generation of ROHM FETs but otherwise, the 4 leg package has proven to work out well with a variety of other parts.

Like · Reply · 5w · Edited



Col Johns Agreed, even the SCT2080KE has 6.3 ohms, ACR @ 1MHz

Like · Reply · 5w



Jonathan Beaver Col Johns Yeah, we've harassed them about it a bunch and were assured that they're aware of the issue and it'll be better in the next generation.

Like · Reply · 5w



Col Johns Jonathan Beaver do you chaps have a website ..

Like · Reply · 5w



Jonathan Beaver Col Johns No, sorry. It's on the 'to do' list! We're a 2-man band who used to work with Qualcomm's wireless EV charging tech, now out on our own.

Like · Reply · 5w



Write a reply...











Cameron Stewart Gate impedance 7 ohms?(!)

Like · Reply · 5w



Col Johns Yup 18Vpk at turn on gives ~ 2.6A into the gate ... 40nS to 17V on the gate ... with inductive drive ...

Like · Reply · 5w · Edited



Jonathan Beaver Or, worryingly, with -3V drive, Vgs(th)min adjusted for 150C junction at 1.7V, that's only 670mA to turn on parasitically, worst case.

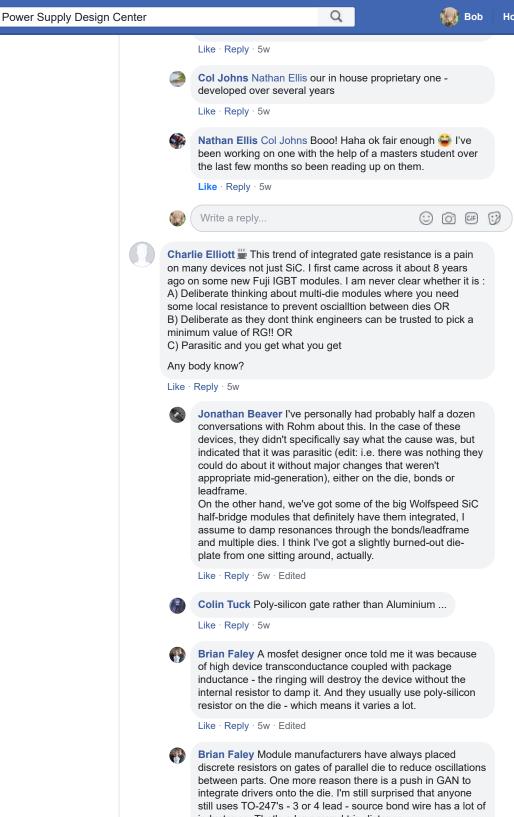
We popped a few of the 80mR versions. Fun times.

Like · Reply · 5w · Edited



Col Johns luckily resonant gate drive gives plenty of oomph to get to -3V and stay there ... we only run to 115degC junc

Like · Reply · 5w · Edited



inductance. That's a long round trip distance.

Like · Reply · 5w

David Edwards . Hello Brian Faley,

At least for MOSFETs a few tens of nano-henrys in the gate drive circuit don't mean much, but any source impedance common to the DS circuit and the GS circuit is to avoided if possible. I imagine that the source leads in the four pin TO-247 package each have their own bond wires directly to the source pads.

Like · Reply · 5w · Edited



paralleled TO-Leadless 300A devices. The gate drive was unipolar for cost reasons. No way that could ever have been done with D2pak-7 lead, TO-247 would have been laughable. TO-247 is about five times higher source inductance. During fault conditions, all the resonant transitions softening the blow of normal operation are out the window. I have been telling mosfet vendors for decades to get the leads out of their packaging and start treating them like the rf devices they are. Few listened, even though we were one of the largest customers for 60V mosfets on the West Coast. Kelvin leads are a start, but it's not a very high hard switched frequency even on a 4 lead package before things blow up without negative drive. I can see exactly why Alex Lidow of EPC has been preaching chip scale packages. It's time to join the 21 st century. TO-247 deserves to be buried. It's decades older than me, and I've been doing this for 38 yrs.

Like · Reply · 5w · Edited



Stephen Berry Charlie Elliott I was in a division of Emerson Electric in the early '90's. We used early HEXFETS from IR. We designed a 10kVA UPS running at 20kHz. Quite twitchy to get it working and we had to buy new scopes and probes to see the edges. Production started, but they started failing in the field. On investigation, IR had changed the internal gate resistors. We found it by connecting gate and source with drain and source on a DC PSU. A nearby coil was connected to a signal generator. The FET blew up when the frequency got to 100MHz.

Like · Reply · 4w



Write a reply...











Andrew Ferencz But you have to figure 1200V, 0.04 ohms, ... even with 7 ohms of internal resistance - it is amazing. A three-leaded device can cause a lot of extra ringing and noise from the common source inductance. So you can't use this at 50MHz .. but I bet if you compare the gate charge/resistance of this part with a MOSFET you are either close to the same or better. And frankly do you really want to hard switch a 1200V node at 1nS? 50A, 1nS ... no way no how will that will ever happen with a leaded package. 1nH = 50V ... What would be needed to know how to make it work reliably in a half bridge - how much external R for turn on is needed to prevent cross conduction - or how much negative drive?

Like · Reply · 5w

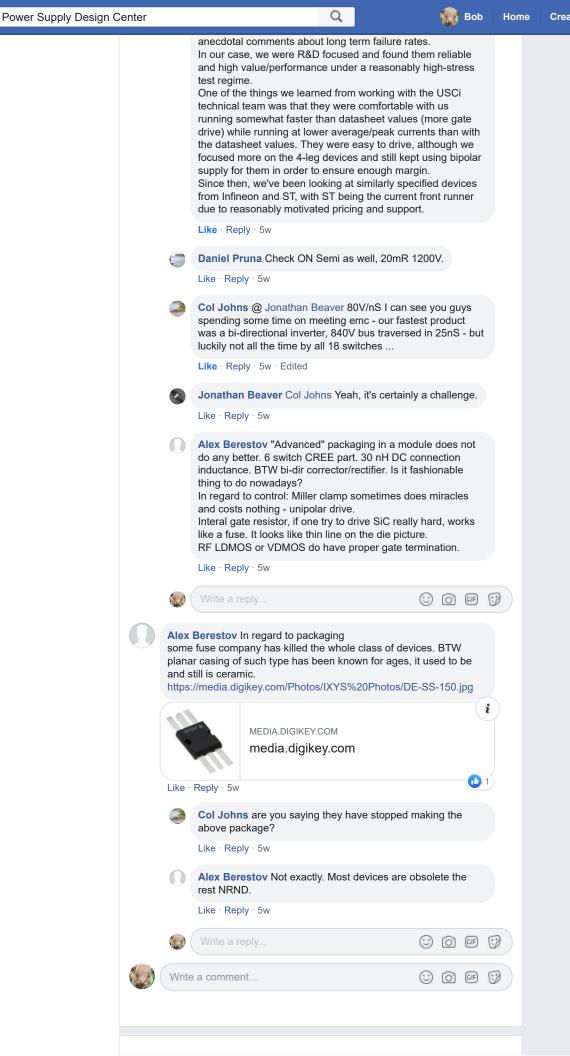


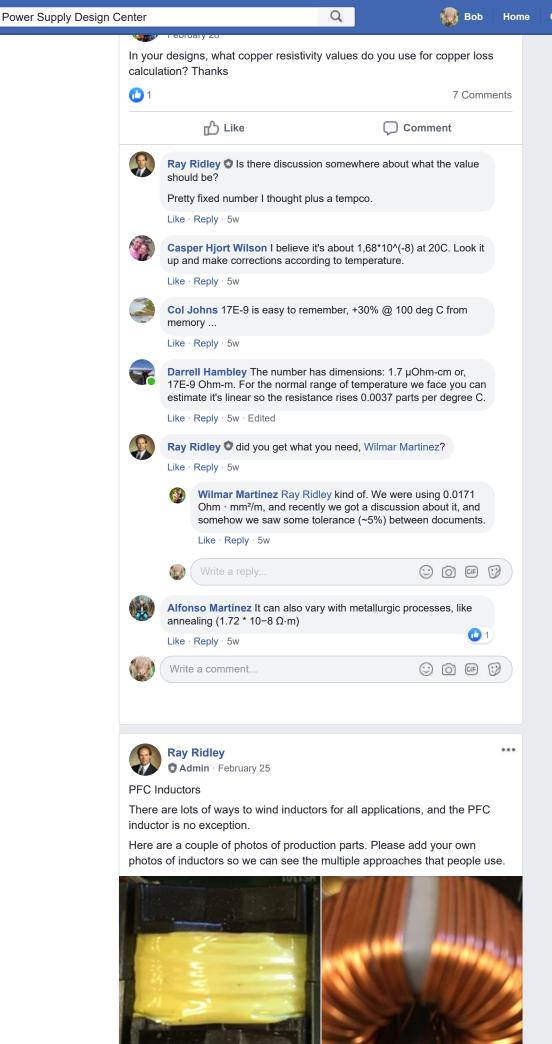
Jonathan Beaver In our application (PSFB with variable loading), it simply doesn't have enough margin against parasitic turn-on under high dV/dt conditions. Max dV/dt is around 25kV/us which is pretty slow for SiC. By comparison, we replaced it with a USCi part which we were pushing towards 80kV/us, measured.

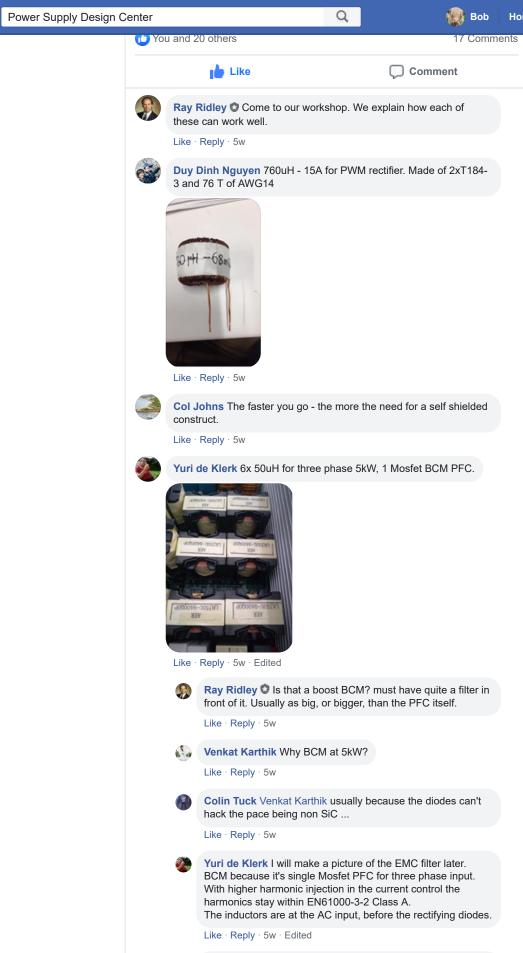
Like · Reply · 5w

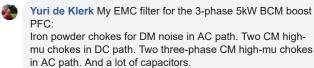


Andrew Ferencz Jonathan Beaver Thanks for that. I know in the high voltage GAN world (which I think isn't ready for prime time) Panasonic came out with a part that was ... lacking. I have been looking at USCi parts for inverters. Any advice from experience is worth a lot.











Like · Reply · 5w

Ray Ridley Vuri de Klerk nice how is the efficiency for tha bcm?

Q

Like · Reply · 5w

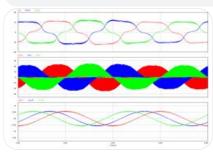
Yuri de Klerk I never had a load for 750Vdc, so only tested in combination with the next stage: Two fet forward with synchronous rectifiers: 24V/200A. Total efficiency 90.5%. The PFC chokes stay much cooler than I could have guessed. Next design I think can do with 3x E42/20 for this power.

Like · Reply · 5w

Colin Tuck Would love to see the input current waveforms if some are available ...

Like · Reply · 5w

Yuri de Klerk I have no pictures of real measured current. It looks a lot like the simulation.



Like · Reply · 5w

Yuri de Klerk Harmonics analyzer was used to stay below the limits in the standard. I had some trouble with 13 15 19 harmonic but was solved with tuning of the harmonic injection.

Harmonic order	Maximum permissible harmonic current		
	A		
Odd t	armonics		
3	2,30		
5	2,30 1,54		
7	0,77		
	0.40		
11	0,33		
13	0,21		
15 ≤ n ≤ 39	0,15 💆		
Even !	harmonics		
2	1,08		
4	0.43		
6	0,30		
8 s n s 40	0.23 8		

Like · Reply · 5w · Edited



⊕ @ @ @

Rogério Junior Dr. Ray Ridley, what do you think about creating a similar topic for transformers? I have some interesting photos to share about high frequency transformers for SST applications.

Like · Reply · 5w



Charlie Elliott Progério Junior - Please do create that post -I would be interested and I am sure many others would be as well.

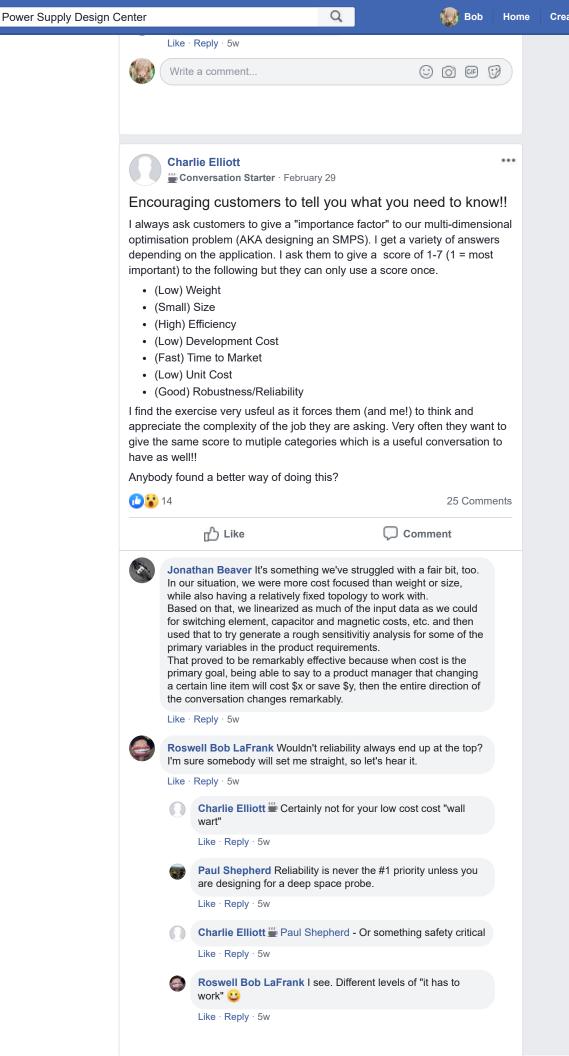












Ray Ridley It's a good excercise, thanks for doing this Charlie

Elliott.

Like · Reply · 5w

Like · Reply · 5w

Charlie Elliott 

"Premium server PSU" score?
(Low) Weight - 7
(Small) Size - 3
(High) Efficiency - 2
(Low) Development Cost - 5
(Fast) Time to Market - 6
(Low) Unit Cost - 4
(Good) Robustness/Reliability - 1

Home



Hello friends.

I have design 3W boost converter using ic BP1808.

Vin- 12V

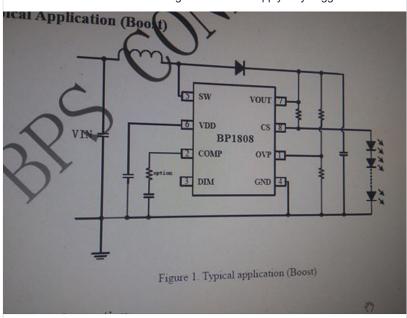
Vout- 36V, 100mA

Working fine .

But when i comes to emission test there is failure in RE and CE Which is at 450 KHz 78 uV db..

I don't know about EMI filter design for dc to dc supply..any suggestions.

Q



C 3 29 Comments





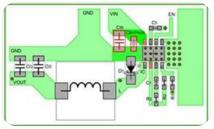


Alain Laprade Datasheet states this is a 420 kHz device. You are wrestling with the fundamental harmonic getting back to VIN. You need to add an input EMI filter. If you don't want to do the math yourself for the filter design, I recommend going to the IC manufacturer's web site for a demo board example to see what they recommend as a starting point.

Like · Reply · 8w



Shiv Kumar Mishra I would suggest review your layout as per design recomendation in datasheet. Try reducing ground loop area. Most of CE and RE problems can be overcome by reducing gnd loop. Could you tell us at what frequency your buck converter operating. You may need some input filter of targeted frequency.



Like · Reply · 8w



**Tanvir Fakir** Shiv Kumar Mishra thanks ..it is booat converter..and operating at 420KHz Freq







Alain Laprade Example given by Shiv above is incomplete. It needs an input filter.

Q

Like · Reply · 8w



Shiv Kumar Mishra I just downloaded one imgae from web and uploaded to have intial review of.

Like · Reply · 8w



Frank Warnes Measure the switching waveform on pin 5. If there is a lot of ringing a simple RC snubber might help. Also make sure your inductor is the right way round. The switching end needs to be the start of the winding so that the input end shields the noise from getting out. This should sort out the common mode noise

Like · Reply · 8w · Edited



Tanvir Fakir Frank Warnes see the waveform across pin 5..i dont think it is so large noise



Like · Reply · 7w



Tanvir Fakir Frank Warnes hi frand i added rc snubber circuit across pin 5 and ground..but still ringing noise is there

Like · Reply · 7w



Tanvir Fakir I have added rc snubber circuit but still there is ringing noise



Like · Reply · 7w



Ray Ridley Please, make a little effort to turn your graphics the right way!

Like · Reply · 7w



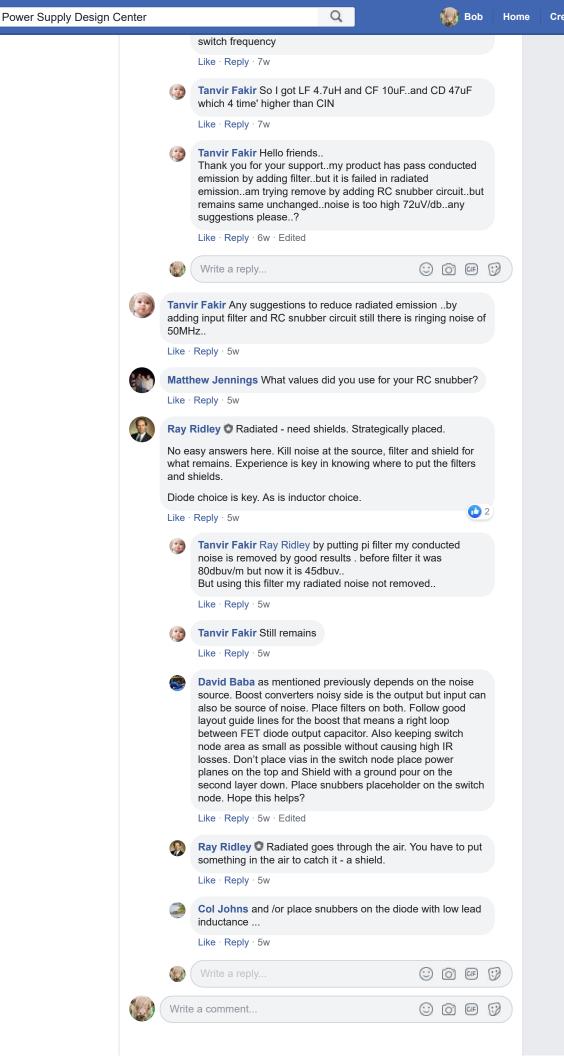
Tanvir Fakir But I don't think ringing noise will affect on conducted emission test

Like · Reply · 7w



Tanvir Fakir Rakesh Panda still finding solutions for CE..any suggestions?

Like · Reply · 7w · Edited









Here is a random thought. If you listen to the semiconductor companies, you would think that the control chip is the heart of a power supply, the most important component.

I am very much a controls person, but I don't think of it that way. The hard work and largest parts are elsewhere, in the magnetics, layout, power devices, thermal, etc. These all get designed first. The last step in the paper design is picking a control chip to fit the job, but the main power design is already done at that stage.

Many control chips, digital, analog, sophisticated or simple can often do the same job. That's why we see a huge array of different parts from one design review to another.



🚹 You, Jay Philippbar and 61 others

54 Comments





Comment



Colorado Mike Doherty Be careful tying the future of a product to a single-source component.

Like · Reply · 6w



Cameron Stewart There are too many control chips to choose from.

This is just in the mixed signal realm, without talking about DSP control, programmable logic array design, or the bevey of other "technology du jour" offerings to choose from.

I would politely describe the control chip situation as "chaotic and overwhelming".

Then there is the learning curve you are privileged to experience, discovering the undocumented bugs in the new control chip you were adventurous enough to try out.

If you are unhappy with the control chip you are using, by all means find another. But if the chip selection you have been using still works for you, I see no need to go looking for something new, just for the sake of it being new.

Like · Reply · 6w · Edited

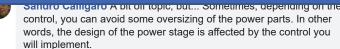


Alex Borisevich controls chips are prone to silicon bugs. and smarter the chip, more severe silicon bug can be. and thus you stuck with a thing that you cant change. power electronics and magnetics you can redesign and tune. but the controller you can just drop and try another one









I'm thinking about digital control and simple converters (like an inverter) doing tough tasks.

Like · Reply · 6w · Edited



Yuval Iz I never use new control chip's in my design,

Always read chip errata and for most chip I wait a year or two before I design with them.

Using this method I minimize silicon error to minimum

Like · Reply · 6w



Broox Le Well, if it's a sufficiently complex controller, sometimes even a few years in, it still has bugs/caveats which are not publicly documented or well-known - partly because few people fully check their designs under all the myriad of conditions and happened to catch it on the scope, and then some IC manufacturers who do have customer forums where they claim they want users to ask questions & share knowledge, actually DELETE polite cordial posts that describe real undocumented issues!

Like · Reply · 6w



Kevin Azul



Like · Reply · 6w



Charlie Elliott I have two things I constantly tell my junior engineers:

- 1) The more complex something is, the more there is to go wrong. This applies to designs in general and ICs in particular. The heavily integrated parts with loads of functions and very few pins can be challenging.
- 2) The wider you open the window, the more the sh\*t flies in!! Don't make the bandwidth of anything wider than it needs to be. An increasing challenge as your switching frequency goes up.

Like · Reply · 6w · Edited



Graham Ward I agree. The actual power side of things (accommodating thermal design, component efficiency and density, parasitics, good gate drive etc.) is the most costly bit. Get any of that wrong and you incur significant cost and effort to rectify the problem. While the control side is no less complicated, an oversight is usually easily rectified by changing a resistor value in your feedback loop for example, or changing a parameter or property of your digital control loop.

Like · Reply · 6w



David Seal I have long started each design I make by stating out loud the KISS engineering principle: "Keep It Simple, Stupid." The I.C shown, if used to run or control a power supply, would be the equivalent of using a sledgehammer to kill a mosquito: it can be done, but oh the effort involved.

Like · Reply · 6w



Ray Ridley There are so many controllers out there at this point, there are not enough engineers to get to the bottom of how they all work and what their latent flaws might be.

There are at least half a dozen I really want to try ourselves, but there just isn't time to get it done.



requirements from the application perspective. Power electronics is going in more and more high power applications EV , solar etc that indeed require a lot of the complexity to function and deliver benefit. There are myriads of communication protocols to deal with , safety and security hedges and control flexibilities to achieve ZVS, hysteresis control etc.

Q

Like · Reply · 6w



Darrell Hambley I totally agree with Ray's OP: "magnetics, layout, power devices, thermal, ..all get designed first. The last step in the paper design is picking a control chip (or chips, plural). My fellow Mech'l engineer and I are currently designing a complex high power system. As we've done before, all my work is designing magnetics, calculating power loss etc as we manage heat flow and play Tetris to fit it all in the enclosure. I have no worry about finding an IC which has a ramp compared to a feedback signal.

Like · Reply · 6w



David Edwards # High power complicated topologies such as inverters and induction motor control generally have lowish switching frequencies. For these, there is no dedicated quasi-analog controller (except for housekeeping) as the main control most likely will be an all digital micro-controller.

Like · Reply · 6w



Darrell Hambley ...or, all discrete analog control.

Like · Reply · 6w



Ray Ridley So at the end of the power design, you choose the all-digital controller which makes sens in many cases. Then you have the myriad of choices of which of the many options is the best for your application.

But, again, the actual choice of the chip comes last and doesn't determine the power converter choices.

Like · Reply · 6w



David Edwards . Hello Ray Ridley,

What I wish really would come last is the design of the enclosure. The initial layout should be without constraints and for maximum performance to prove the basic electrical design. Package size and mechanical design should be last.

Like · Reply · 6w



Ray Ridley Constraint #1: Price

Like · Reply · 6w



Ray Ridley O Constraint #2: Box

Constraint #3: Schedule

Constraint #4: Development price

Fortunately, in our company, we have the option of saying "no" to many design jobs since the needs just can't be met.

Like · Reply · 6w



Charlie Elliott # Ray Ridley I very often ask customers how they would like to prioritise your #1-4 plus a few others by scoring importance of each one. Can you guess how most reply 🎑 👺

Like · Reply · 5w



Col Johns Charlie Elliott , Price, Quality, Speed of delivery pick any two and the third is a function of those picked ...

Like · Reply · 5w



Write a reply...









manufacturers are better some not so. Most of the times you do not have pin to pin substitute.

However NS, Unitrode, Motorola used to have kind of "school of design" a la "school of thought" yielding well thought out IC's tailored to PSU designer's needs.

Like · Reply · 6w



Seppo Turunen Why not use a small FPGA? I am currently using a Lattice XO2-2000 and a couple of A/D converters to control a 1kW current-fed half bridge resonance converter prototype. The control functionality is fully contained in a technology independent VHDL design file so that there is no need to decipher controller data sheets or to guess how microcontroller peripherals are supposed to work.

Like · Reply · 5w



**Col Johns** Why not...? how many engineer hours has it taken you to get "near working"? how many more hours for a solidly engineered product ...?

Like · Reply · 5w



Seppo Turunen Col Johns I suppose what is relevant here is to compare the two approaches and, if I understand right, you want to point out that FPGA design is a real work item that requires justification. I could not agree more. If a commercial chip does the job, there is probably no point in replicating its functionality with an FPGA. However, if the required topology, timing, sequencing, security or feedback control is not supported by the controller, it may, in my opinion, be a faster and more predictable choice to program an FPGA to do exactly what is needed rather than to twist the commercial chip by building a kludge around it from discrete components. Also, as an alternative to an MCU, an FPGA could provide faster and more deterministic control. I am clocking the FPGA with 50 MHz so that I have a 20 ns cycle accurate control over everything. In contrast with SW design, VHDL design is parallel, so that adding functionality does not slow down anything designed earlier. In terms of logic design, we are talking about a fairly small project. Mine currently has eight pages of VHDL code and it includes, in addition to the SMPS control, a few auxiliary functions such as LCD control.

Like · Reply · 5w



David Edwards # I am not an FPGA expert, but in the past, FPGAs were expensive, large (way too many internal gates and lots of pins) and required multiple power supplies. Are there now inexpensive, 3.3 volt single supply FPGAs of modest internal size and external pins (<=48)?

FPGAs have the advantage that they can be reconfigured every time they boot up so that field updates are easy and their function can be altered by the main micro-controller depending on user input. I see one of their biggest advantages is speed, which allows creating digital ramps with extremely high precision for precise timing and PWM. These can be created using multiple pipelined ripple counters where each added pipelined stage only cost one clock cycle delay.

Because FPGAs don't do analog well, one has to think outside the analog box to create all digital control mechanisms.

Like · Reply · 5w



**Chris Merren** I have used the Xilinx zynq 7000 series SoC with SMPS with good results....

nas no second source? I wonder what the typical production lifetime is of such a part?

Putting a small FPGA on the same silicon or at least the same header as the micro-controller could be very attractive for power product use. Many micro-controllers have PWM modules, which are set up with registers rather than code, so they steal very few cycles from the main processor and processes.

Micro-controllers with three PWM phases are common, but what if you want to have eight, sixteen or some other number of phase outputs all equally spaced in phase over 360 degrees? Programmable (connection configurable) hardware logic would be very good for that.

Like · Reply · 5w



Chris Merren David Edwards The big issue with many microcontrollers is the A-to-D are total BS.... Sampling rate is poor and the data sheet is fool of fibs....If you use too many resources the sampling rate drops... The FPGA is the way to go, especially in the A-D dept and the latency issues with control loops...

Like · Reply · 5w



David Edwards Do FPGA analog-to-digital converters have good over-under voltage protection and are they available on small FPGAs? Also, some of the specifications for some of the FPGA analog comparators I have seen have not been impressive.

Would any members of this group care to recommend a small FPGA suitable for power conversion products? (Should be single supply, perhaps with A/D converters and analog comparators.)

Like · Reply · 5w



**Bob White** Hamish Laird Sounds like it is time for you to weigh in...

Like · Reply · 5w



Hamish Laird David Edwards Bob White lots of questions here. FPGAs are common in power control for custom peripherals. FPGAs are also falling in cost. We see the prices fall and continue to fall especially for the customers who have large accounts with vendors. There are also FPGAs in all silicon vendor companies which are used for power control chip prototyping.

Like · Reply · 5w



**Bob White** Hamish Laird OK, but what about combinations of FPGA and microcontroller cores? Don't you typically use a device with a significant FPGA married to an ARM core?

Like · Reply · 5w



Hamish Laird I do not know of the details for Intel or Lattice but Xilinx has made "If you want to buy it we will make it" statements for a long time.

Like · Reply · 5w



**Hamish Laird** Bob White We do use the FPGA with the ARM core attached as a development platform. We can then move to custom FPGA hardware to meet cost targets.

Like · Reply · 5w

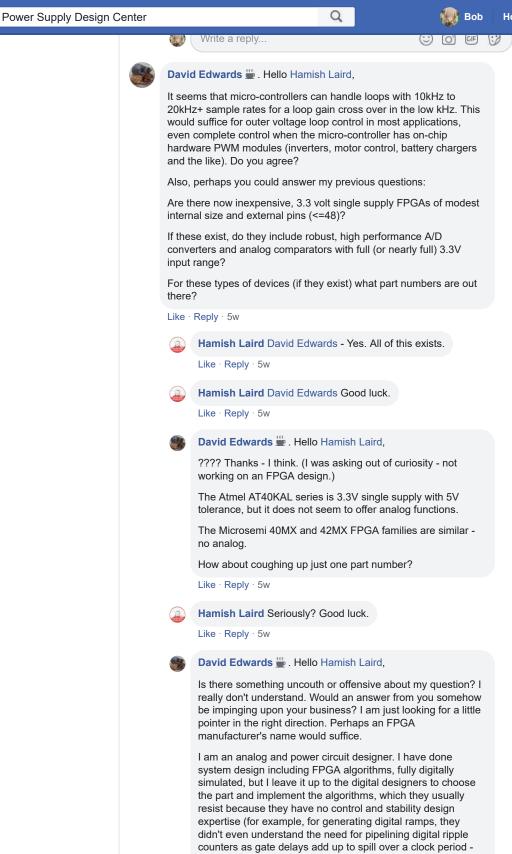


**Hamish Laird** We do o control in the microcontroller or processor core as processors are just too slow.

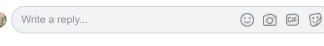
 $\text{Like} \cdot \text{Reply} \cdot 5w$ 



Hamish Laird That is - We do no control in the nmicrocontroller or processor core as processors are just too slow.



we had a lot of trouble finding a good digital engineer with FPGA and feedback control experience).



speed PWM feedback signal, filter it with audio bandwidth and feed it to a low cost external comparator the output of which goes back into the FPGA to complete the ADC feedback loop. That might be fun to design. Audio bandwidth should be good enough for controlling inverters, motor drives and the like.

Assume a 250MHz FPGA clock. With a 10 bit counter one could generate a 250kHz sawtooth. A simple three pole filter would filter the one bit PWM by just under 2,000x which would just sufficient for a 20kHz, 1024 step ADC bandwidth. I am just working this out as I type so I may be mistaken. The analog input would also need an anti-aliasing filter if the input contained high frequencies. Overall ADC bandwidth without too much phase shift might be only 5kHz or so. To bump up the bandwidth, one could have the FPGA produce two or three bits or do some oversampling tricks with in the FPGA.

Like · Reply · 5w · Edited



Seppo Turunen I am using the 3.3V variant of a Lattice Mach XO2 FPGA. The one with 2000 logic elements comes in a 100-lead TQFP package and has turned out to be more than sufficient for my project. For analog inputs I use LTC2315-12 5 Msps A/D converters that allow the FPGA to take plenty of samples from current and voltage waveforms for subsequent digital processing such as averaging, threshold detection and feedback control.

Like · Reply · 5w



Joel Holland Do you need a DSP as well? What switching frequency did you use and at what resolution? What do you think the maximum limits for those would be?

Like · Reply · 5w



Seppo Turunen Joel Holland I do not have a DSP. I am switching at 100 khz. The FPGA clock is 50 MHz. I am using registers of different length in the arithmetic, ranging from 12 to 32 bits. The longest ones are only needed as a scratchpad in divisions, though.

Like · Reply · 5w



Ray Ridley V Nice.

Like · Reply · 5w



Write a reply...











David Edwards Do any readers here have enough FPGA experience to comment on the last several remarks and/or answer the questions that did not get answered (read starting with the comment that begins, "I am not an FPGA expert . . . "

Like · Reply · 5w



Seppo Turunen There are families of small 3.3V FPGAs on the market with 256 to 50000 logic elements. The pin counts range from 32 and prices from 3-4 usd upwards.

Like · Reply · 5w



David Edwards Seppo Turunen Thanks for answering.

Like · Reply · 5w

Like · Reply · 5w

**Pranit Pawar I** created this thread because I looked for papers for optimal layout design and every paper just gives some 10-20 configurations and shows the resulting parasitics

of the arrangement. no reason, just graphs.

цке · керіу



Ray Ridley DExperience. And intelligent iteration. That's the fastest way to product.

Q

Like · Reply · 5w



Ray Ridley Graphs are good, that is how good engineering

The modern way is to want to solve it all with a computer, but that will never happen. Doesn't ever stop people trying though

Like · Reply · 5w



Daniel Ruiz We didn't use it to design or look for an optimized layout as much as to extract parasitic values to use in our simulations.

Like · Reply · 5w



David Edwards For most circuit traces and signals a few nH don't matter much. It's only those with high di/dt that may be problematic. In a switching supply what's always important is the inductance of the common source path between the gate drive and the main switched current of the MOSFET.

Like · Reply · 5w



Pranit Pawar Yes its a GaN high power drive, so di/dt and dv/dt is high

Like · Reply · 5w



Write a reply...











Darrell Hambley Pranit, You can get a good estimation of inductance if you break down your traces into linear elements. Use the equation for a strip-line over a plane:

Where: I is the length, d is the thickness of the board material and w is the width of the trace. All in cm. If you're working in inches, multiply by 2.54 cm/inch for:

L=32 nH-inch

For example, For w = 0.05 inch, d = 8 mils, l= 1 inch the trace inductance will be:

L = 32nH-inch \*1\*0.008/0.05=5.1nH.

You can verify this when you see a voltage spike on your o'scope from ground to the source of a MOSFET for example. If you know the rate of climb of current, di/dt, you will see that this spike voltage is close to:

V=L\*di/dt

Like · Reply · 5w



Ray Ridley of don't forget bond wire inductance. Plus, strip lines over planes probably don't exist in many places.

We should have a rule on the site, perhaps - metric units only!

Like · Reply · 5w

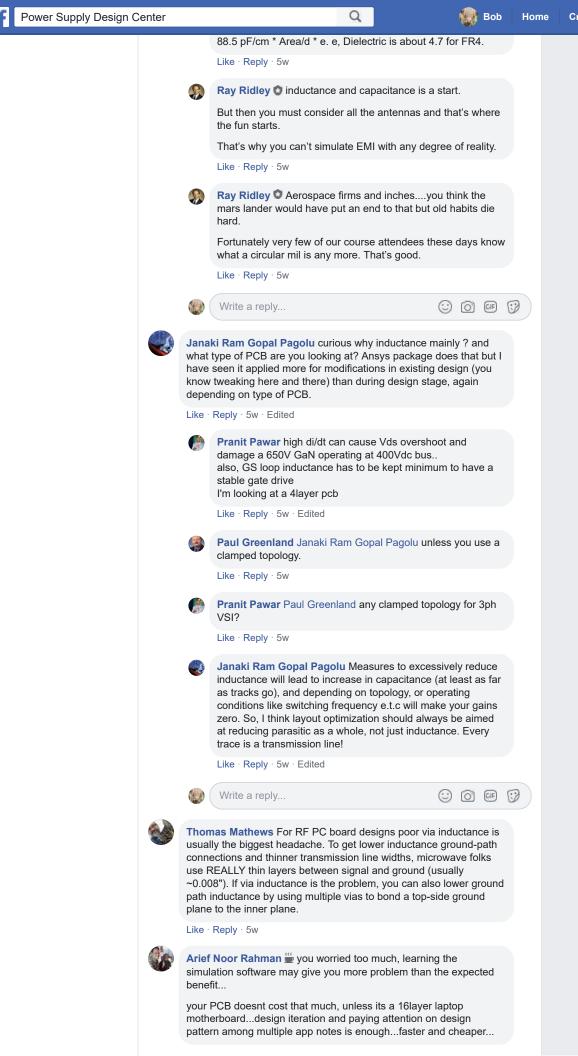


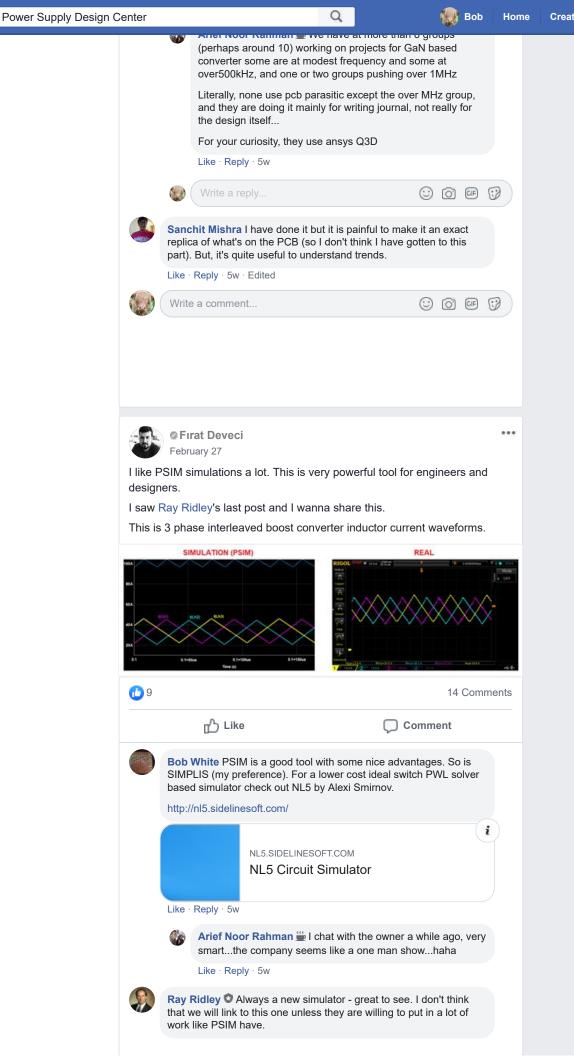
Pranit Pawar And for a plane, similar approach can be used to break down the polygon into small strips and integration has to be done?

Like · Reply · 5w



Darrell Hambley Many firms in aerospace use inches for board layout dimensions. I did leave the equation there in cm for those who only work in metric, assuming they don't know how to multiply by 2.54. Praint - yes, it can be integrated. Do pay attention to lead wires as Ray suggested. Always include source and drain lead inductance in your models.









kay kiuley v i believe that one of the coming strengths of Poli the digital control they are implementing, plus the motor drive aspects. I will let Albert Dunford speak more on that topic.

Like · Reply · 5w



Albert Dunford PSIM provides support for a great deal more than analog power supply. Not sure how NL5 fits into digital control, motor drives, embedded code gen, non-linear switch transitions, stability and convergence in larger simulations,

Like · Reply · 5w



David Edwards . Hello Ray Ridley,

I would love to see a similar comparison between your modification of LTspice, PSIM and SIMPLIS (and perhaps some others - see below). In addition to comparing plots, a listing of run times would be

This is taken from one my entries in the LTwiki:

The SPICE engine runs on fine tuned Modified Nodal Analysis technology, but competing technologies are emerging. Many simplify all nonlinear elements (diodes and other switches) into piecewise linear equivalents (2 or more line segments). This reduces the simulation to solving a repeating succession of related linear topologies. These are joined at their border points in time, but are perfectly linear in between. Each topology can be quickly solved without the many trial and error points of a nonlinear Newton-Raphson solution. Most notable of this breed are SIMPLIS (SiMetrix), PSIM (Powersim), PLECS (Plexim) and NL5 (Sidelinesoft).

These engines feature very quick steady state solvers for switched circuits and switched mode power supplies. Typically named POP or PSS (Periodic Operating Point or Periodic Steady State), a long, drawn out initial transient is avoided. Near instant POP/PSS and transient run speeds allows a time domain DFT ac analysis to be performed on switched circuits. Loopgain of switching power supplies and class-d amplifiers may be quickly analyzed in the time domain. Only a single nonlinear switched model is required - no need to resort to equivalent circuits with added "sampling effect" networks. Simulated results precisely match lab measurements (Venable, HP4194A, etc.) to and beyond the switching frequency.

Like · Reply · 5w · Edited



Ray Ridley Don't forget our simulation engine in RidleyWorks. Faster than any of them.

Like · Reply · 5w



Ray Ridley Sounds like a good job for someone who is (semi) retired.

Like · Reply · 5w



Ray Ridley Remember, all of these methods depend upon the circuit being stable. Otherwise there is no POP and you have to go back to small-signal models (which you should be using anyway.)

Like · Reply · 5w



Ray Ridley I believe the new-found speed of the PSIM has rendered it a moot point about whether the POP method is needed now. They have certainly cut deep into this prior advantage of Simplis.

LTspice is good too, you just have to wait. But what's the hurry? Layout a board while it does its thing.

So many options. What a great time to be a power designer!

Like · Reply · 5w



Yaqoob Muhammad User interface wise, I think, nothing can beat



the scope makers for making this investment.

This doesn't alarm us at all - it is great to see such awareness of the need for Bode plots. What this is going to do is get people started on the topic, and get the measurements back into education.

Later, users will find that the performance can be quite erratic, depending on many factors, and what kind of thing your are trying to measure. Passive circuits - all is well. High performance noisy switchers, not so good.

We have been testing diligently for the last few months to see how things stack up versus the AP310, and we are very happy with the results. There are currently at least 8 different analyzers in our lab under review.

The good news for us is that nothing comes close to the AP310 analyzer for performance. You can see this in the plots below of power supply output impedance. The AP310 just cuts through the noise, and gives the same result regardless of circuit setup. Other wannabe analyzers are all over the place, especially in the range from 10 Hz to 100 Hz.

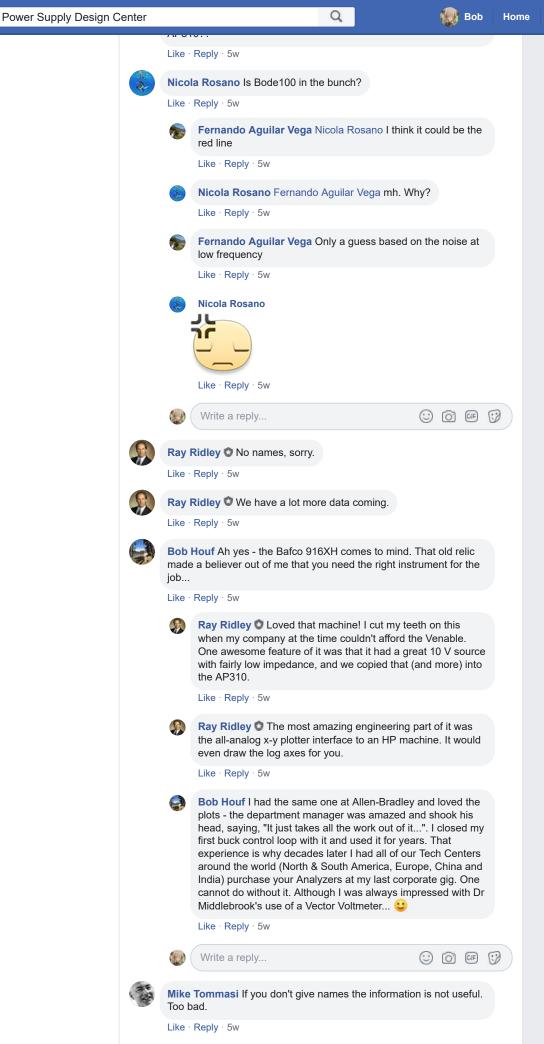
In these tests, the exact same circuit is being used, same cables, same isolator, everything.

If you need a rough idea, use whatever is at hand. But if you need reliable rugged performance under all conditions, the AP310 analyzer is the only one that gives it to you.

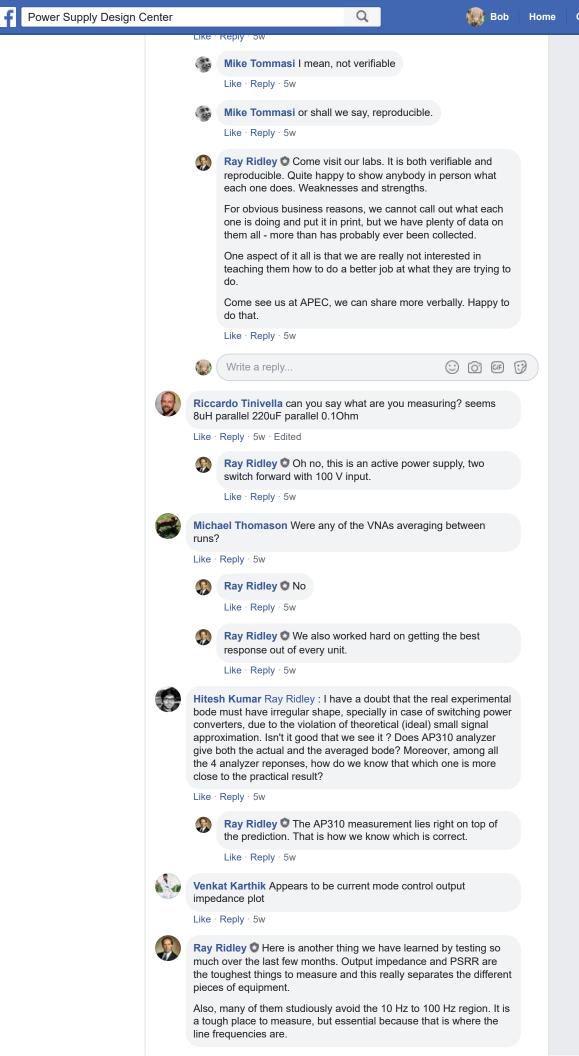


Comment

Like

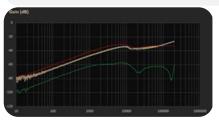


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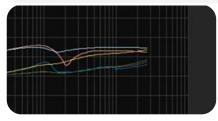
Ray Riciley 👽 Triis was a really illuminating and surprising set or experiments on 9 different analyzers. The AP310 reference is 20 dB below the others. This is a PSRR measurement.



Like · Reply · 5w



Ray Ridley More variability - see how much fun we have been

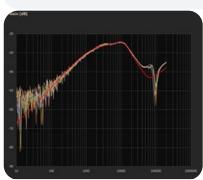


Like · Reply · 5w



Ray Ridley Here is one more plot of impedances, and a question. You can see the AP reference trace. Are the other measurements "good enough"?

Probably all depends on your industry, but I don't really know the answer to this.



Like · Reply · 5w



Ray Ridley To be honest, we can squeeze a loop gain out of almost anything. But it takes a lot of experience to do that. Most users won't have the expertise to do that, hence the AP310 with RidleyWorks that makes it a one-button setup.

PSRR and Output Impedance are much tougher to measure well. Many of the machines just can't do it.

Modern scopes certainly have processing power to handle it. They probably need to work on optimizing their analog circuitry for the task.

One thing to keep in mind when interpreting loop gain plots, some analyzers may be very good a presenting just the response to the fundamental test frequency, filtering out all harmonics and any other spurious signals. However, this may not yield the best indication of stability margin.

Why? Oscillation occurs at the frequency point which, if you were to magically break the loop at the input to the comparator (where the signals are analog), the signals on both sides of the loop would be identical. However, these may not be sine waves. If there are significant harmonics present, these must be taken into account in computing loop gain.

To be honest, I don't fully understand the math required, but this effect has been demonstrated in self-oscillating class d amplifiers where the oscillation point varies significantly from that predicted from the Bode analysis and enhanced .ac simulations. This problem is best illustrated by attempting to predict (using Bode analysis) the oscillation frequency of a simple Schmidt comparator oscillator circuit.

Like · Reply · 5w · Edited



Ray Ridley There is a conflict of optimizing the analog hardware to be a good scope versus being a good analyzer. Every scope we have measured so far, and some of the analyzers, have the same problem.

It makes them very susceptible to different test setups, which is not a good thing.

Like · Reply · 5w · Edited



Ray Ridley The AP 310 is not susceptible to these DUT setup changes. That is a very significant thing, this is a new realization for us, a result of all the testing we have been doing.

if you have our experience here, you can tell when things are not measuring right and maybe change setups. Without that, you are shooting in the dark, one of the reasons that people get frustrated with FRA measurements.

Like · Reply · 5w

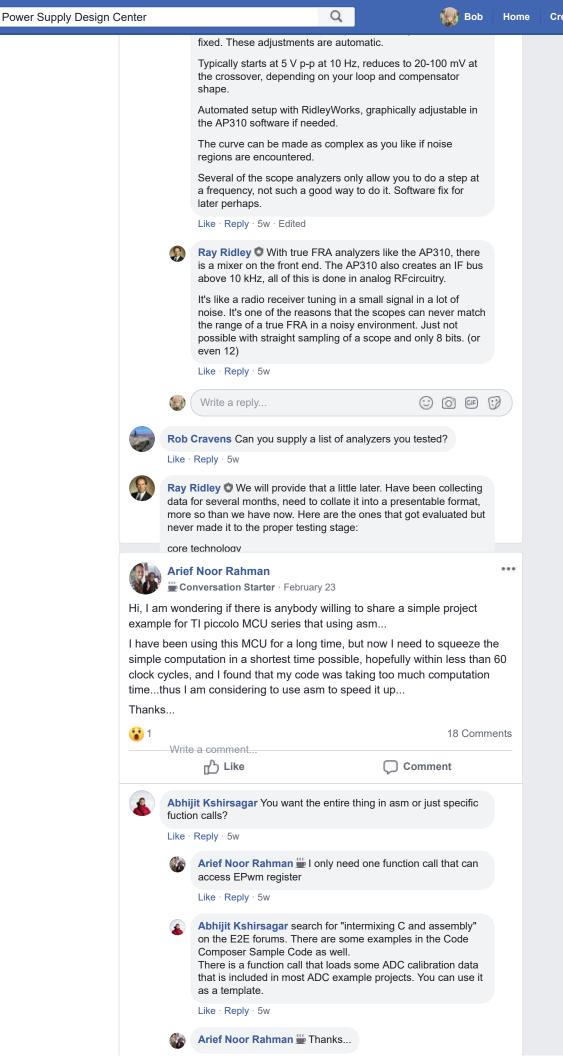


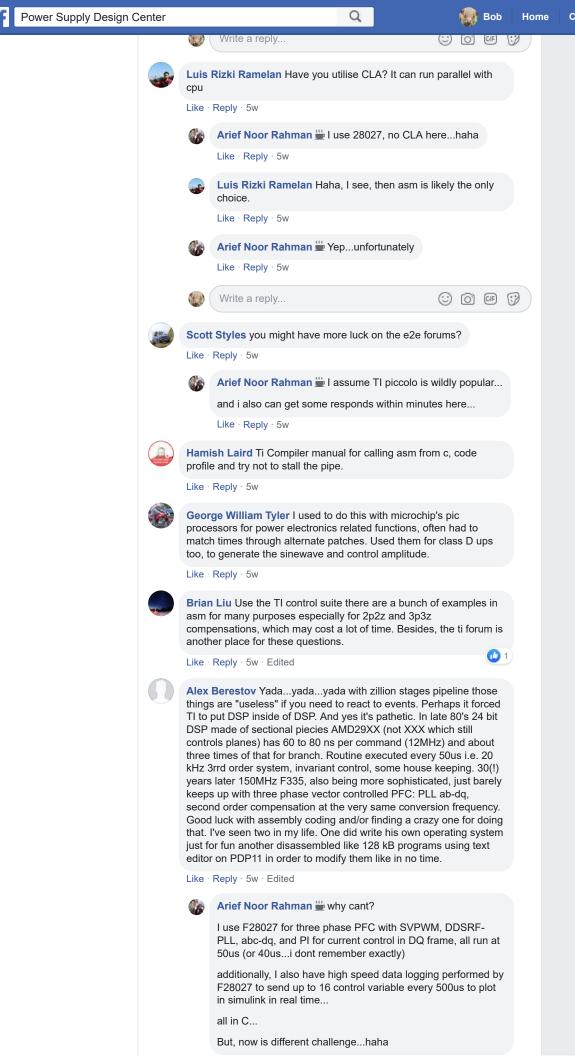
David Edwards Frequency Response Analysis injects a smallish floating ac signal into the control loop, usually at a low impedance point. It then does a vector ratio analysis of signals measured from the two ends of the floating source with respect to ground. Discrete Fourier analysis techniques are used to reject noise.

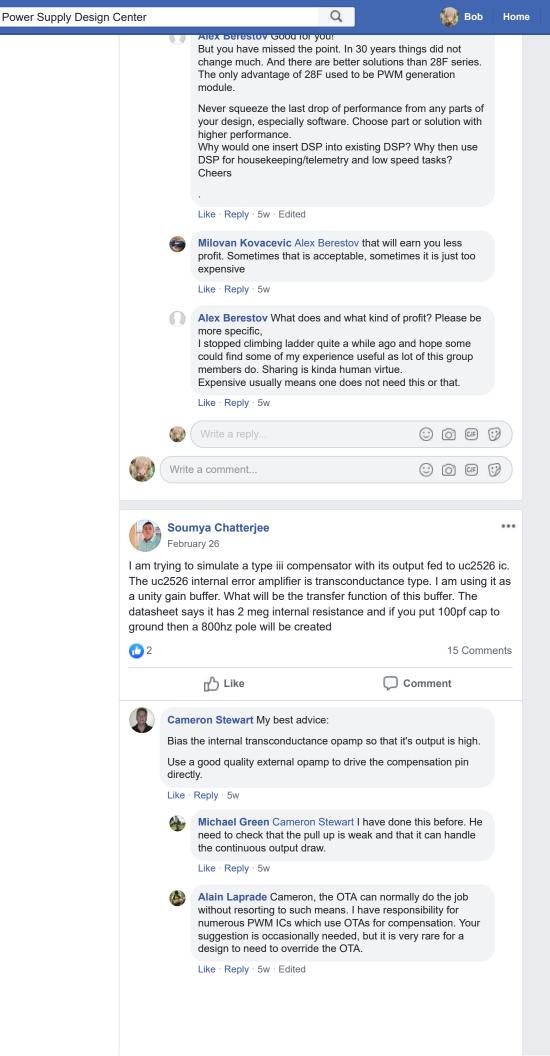
Without thinking about it, one might assume there would be no need to adjust the size of the floating source over the measurement frequency range. However, at the low frequency end, due to extremely high loop gain, one of the vector signals gets very small and the floating source amplitude must be increased to avoid signal to noise issues. A similar effect happens at the high frequency end past unity loop gain.

I am correct to assume that the AP310 makes these adjustments automatically?

Like · Reply · 5w · Edited







for Type III compensation.

Like · Reply · 5w



Ray Ridley Isn't 2526 voltage mode?

Like · Reply · 5w

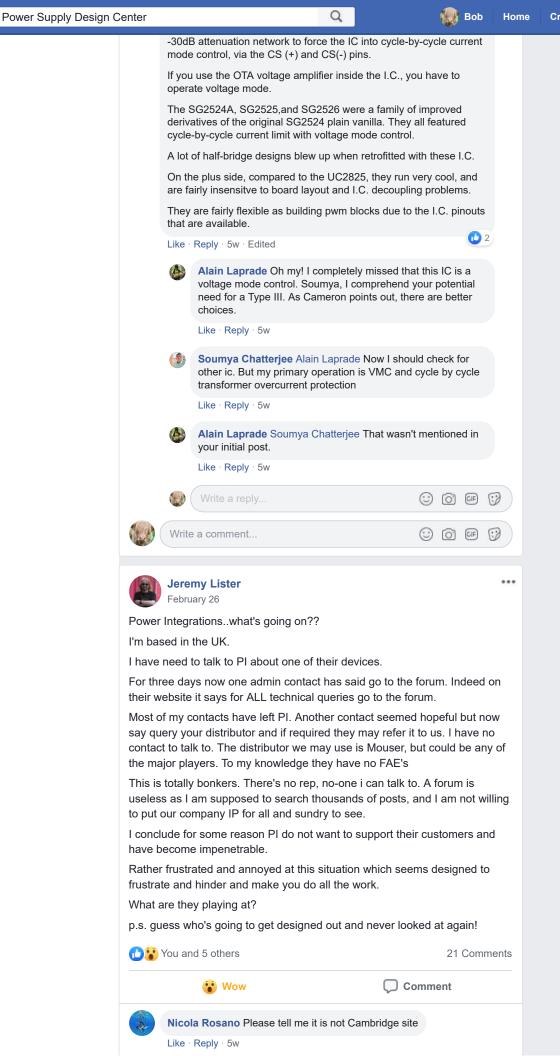


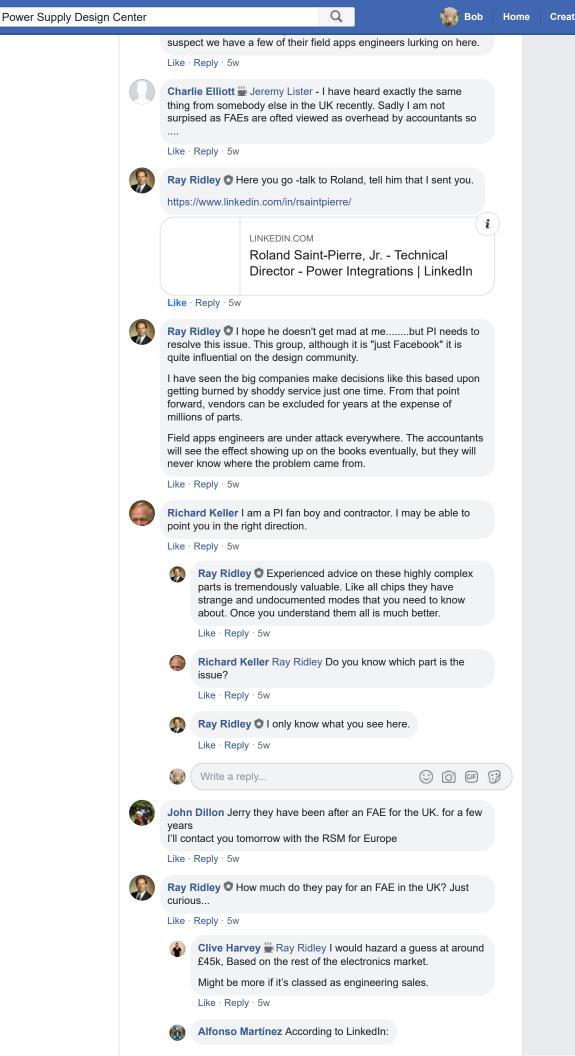
Col Johns it has a CS+ & CS- pin for terminating a cycle once 100mV is exceeded...

Like · Reply · 5w



Ray Ridley OK.





Write a comment...

(C) (C) (C)



I am in trouble to measure the NTC temperature using microcontroller adc. I used STM32F405 controller . I did not use external reference in controller for ADC measurement. Internal reference is used. Now the internal reference varies from 1.18V to 1.24V which is approximate 2% of measurement error introduced. So if my temerature range is 0 to 35degC and hence maximum error is 0.7degC.

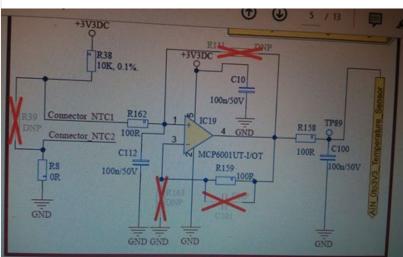
Q

I can not use external reference for MCU because STM32F405 is not having external reference pin in 64 pin package.

So can anybody suggest me any idea, solution or path to get rid of this

Supply voltage for NTC and Microcontroller is same dc rail and coming from LDO.

For now I am not considering the non linearity of NTC.





20 Comments







Ray Ridley Dlease try to do some cleaner graphic. It is so easy to use the snipping tool, then paste into the comment. People shouldn't have to get eyestrain reading what you post.

Like · Reply · 5w



Ray Ridley Why not add a precision reference if you need more accuracy?

Like · Reply · 5w



Shiv Kumar Mishra STM32F405 do not have external reference pin in 64pin pin package. That's the reason

Like · Reply · 5w



Bob White I think you need to do a full tolerance analysis on the entire sensor circuit. For example, you did not mention the tolerance of the temperature sensor. How does that compare to the error introduced by the variation in the internal reference voltage for the A2D converter?

Like · Reply · 5w



Yuval Iz Simply use an accurate voltage regulator and feed the microcontroller VDD and feed VDDA via a bead and a 0.1uf to gnd using this methode the ADC vref became the regulator voltage Analog device have accurate linear regulator you can use

Like · Reply · 5w



Charlie Elliott Feed a vref into another ADC input and do the compensation in software!

Like · Reply · 5w



Charlie Elliott Shiv Kumar Mishra - I and other members of this group are very happy to help but we are typically not prepeared to do the actual job without being paid for it!! Please think carefully about what I have suggested and I am sure what you need to do will become clear.

Like · Reply · 5w



Ray Ridley Let me guess....."can't afford a Vref in this design?"

Like · Reply · 5w



Shiv Kumar Mishra Sometimes we made worng guess. MCU does not have external reference pin 64pin of stm32f405

Like · Reply · 5w



Julio La Leggenda Use a current source to generate a precise voltage reference.

Like · Reply · 5w · Edited



Broox Le What exactly is the problem? - is the error tolerance not tight enough for your application?

Like · Reply · 5w · Edited



Alex Berestov 1. Did not you know If a ruler is 0.7% accurate that's all you gonna get?

2. Did not you read datasheet before you designed thingy of yours?

3. It's a good lesson, next time think before you do.

Introduce good ref into design of yours and measure it with free adc

P.S. It's power supply (not analog or micro) design group BTW.

Like · Reply · 5w · Edited



Syed Rafi Sifath Palal 1. Have a precise regulator is a good option, 2. also possible to calibrate using software, eg use another adc pin and measure a fixed voltage then calculate the variation from your base device then include this variation in you temperature calculation. The varietion input you can take in uart and store in flash 3. You can use a potentiometer in series with ntc and can adjust the output manually for different devices. The resistance of pot might change with temperature though, but I guess this still reduce your error

4. Software calibration using only ntc also possible, you measure your base ntc reading, and target ntc reading, add the variation calculation in Target ntc using uart and store it in a non volatile memory.

Like · Reply · 5w



Frank Warnes I always prefer the LM50 to using an NTC. Gets rid of all the complication

Like · Reply · 5w



Yuri de Klerk Or MP9700

Like · Reply · 5w



Charlie Elliott "Yuri de Klerk AKA "the thermistor buster"

Like · Reply · 5w



Milovan Kovacevic Sometimes you earn more money, sometimes you make your life easier, sometimes both, sometimes neither

Like · Reply · 5w



Write a reply..





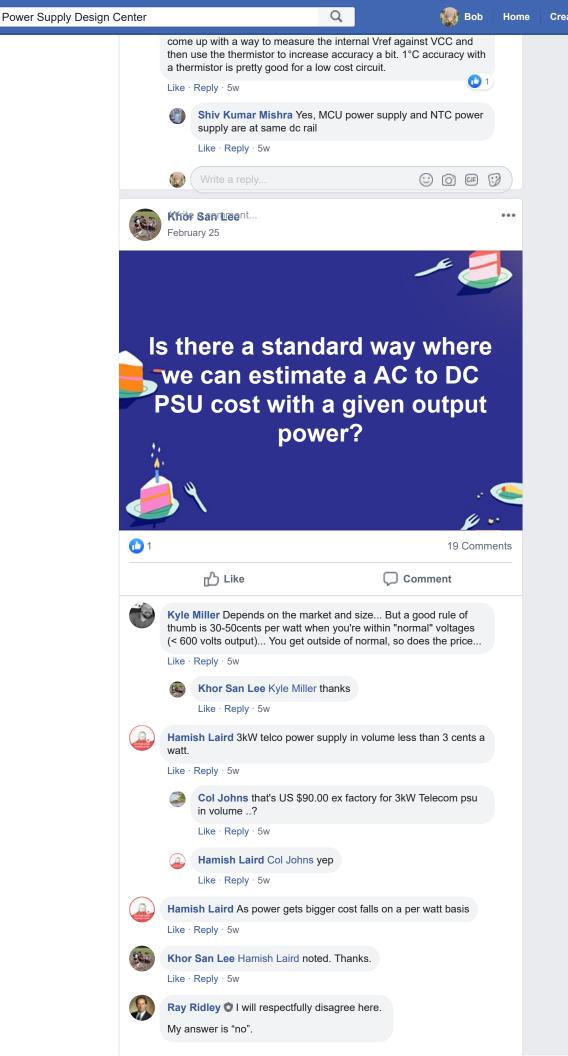




























Dave Lanerty You can't estimate cost until you have a product spec and an idea of what type of design is required to meet that spec.

Like · Reply · 5w



Bob White And aside from the very important specifications, what is the production volume? The cost difference between making 100 per year and 100,000 per year is orders of magnitude (see Hamish's note that high volume telco rectifiers sell for US\$0.03 per watt).

Like · Reply · 5w



Jeremy Lister The sales manager will define the price and you make the design fit that price...a route to disaster

Like · Reply · 5w



Ray Ridley Ocorollary to this:

The system definer will define the enclosure, and you make the design fit that space.

Like · Reply · 5w



Ray Ridley Disaster recovery is our thing. By the time people come to us for a design, they need it now, and cost is not the first thing on the list any more. The disaster has already happened, and there is no power supply available for the product because things were designed with only price in mind.

We do FAST prototypes for people in trouble. It's stressful sometimes, but rewarding. Our last fast prototype was 100 W isolated converter design, build and test in 1 week. That included all magnetics designed and wound as part of the process.

Before that was a 400 W flyback converter, also completed in 1 week

It is not \$0.03 per watt 🙂

Like · Reply · 5w · Edited



Ray Ridley As Bob has mentioned, you can't begin to price a product if you don't have the schedule and production quantity.

The Telco rectifiers that we review here have probably 20 man years of development in them, or more. Trying to enter this space without all this investment behind you is not going to work.

The second Telco rectifier you design will be dramatically less. And so on.

Like · Reply · 5w



Ray Ridley One more comment on the Telco rectifiers - I cannot see why anyone would want to be in that business. You look at the products, and cannot imagine being able to make it for the price.

Yet, still, the price pressures continue from purchasing and sourcing departments until it is getting to the point where power supply companies don't even bother quoting a design any more.

Hence the design goes to a new company in a new country that doesn't understand how it all works yet. They will quote anything to get the job!

Like · Reply · 5w



Ray Ridley And who paid for the NRE? Where is it made?

Is this something you are buying now? Or are you planning on designing it?

Crazy world we choose to operate in!

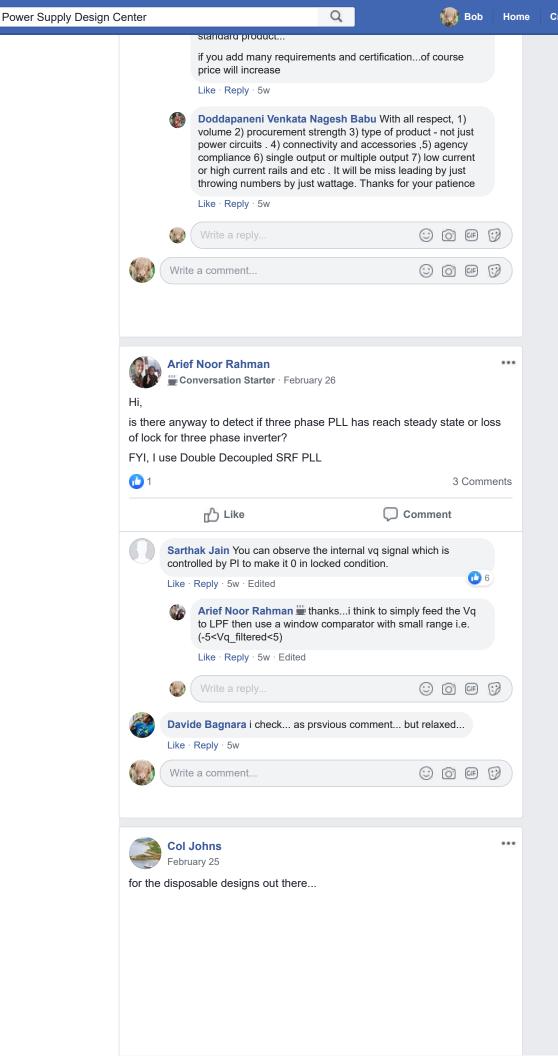


**1** 2



Doddapaneni Venkata Nagesh Babu Many specs to consider, not just watts alone to decide cost.

Like · Reply · 5w





Q







😝 🚵 You, Darrell Hambley and 75 others

19 Comments



Like



Comment



Roswell Bob LaFrank works on tube radios

Like · Reply · 5w



Ray Ridley © Can you share the origin of that part? Col Johns

Like · Reply · 5w



Col Johns sent from an engineer who wishes to remain anonymous ...

Like · Reply · 5w



Maxime Berger Maxime Deveau 6







Norman Elias Shielded caps?

Like · Reply · 5w



Dan Watts Similar thing is no uncommon in rechargeable batteries.

Like · Reply · 5w



Dave Lafferty I have done this on vintage equipment that the owner wanted restored and recapped. Put equal or higher voltage caps of better quality than originals in the older cans to maintain the vintage look.

Like · Reply · 5w



Clive Harvey when working in an aerospace company, they all of a sudden had very expensive products going bang on the production line during final test, one after the other.

Route cause came out to be a IC that was fake, simply a empty package with no die.

Managed to track the part back as having passed through China and apparently got swapped out there somewhere.

Like · Reply · 5w



Scott Styles 10A rated cabling burning at 9A... caveat emptor.... https://www.youtube.com/watch?v=wts5EEO7jr0



YOUTUBE.COM

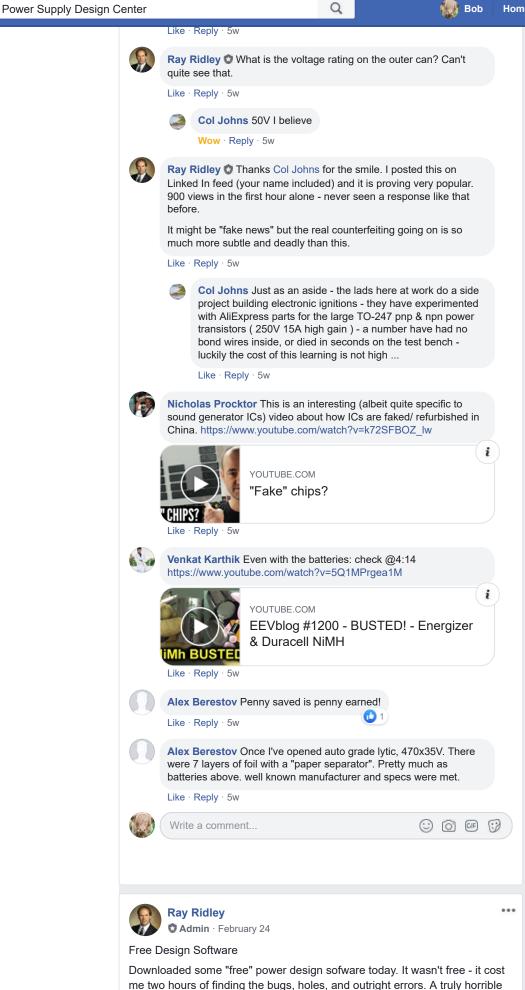
10A Rated IEC Power Cable Running at 9A

i

Like · Reply · 5w · Edited

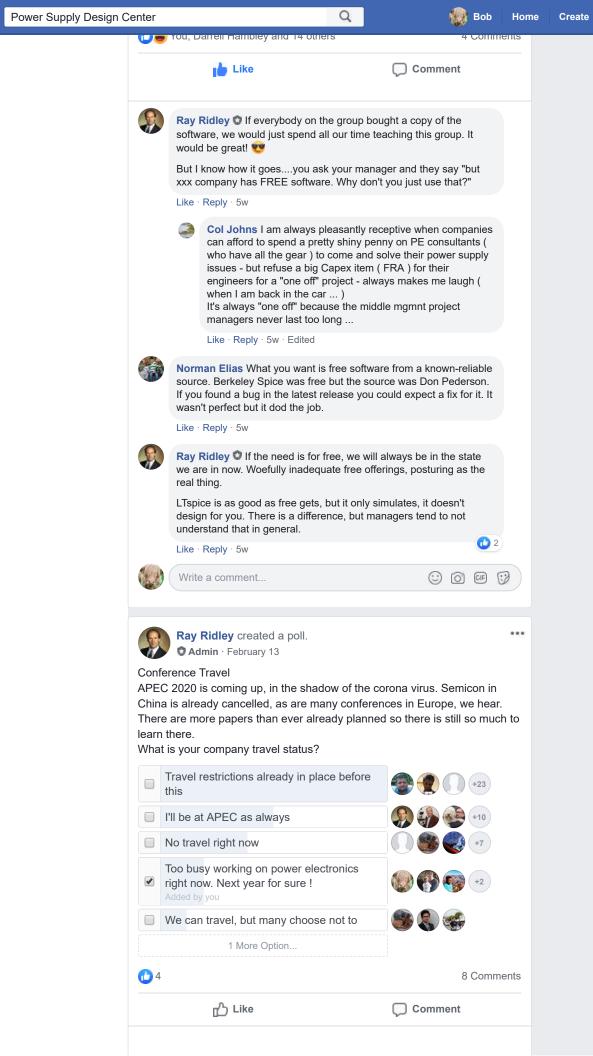


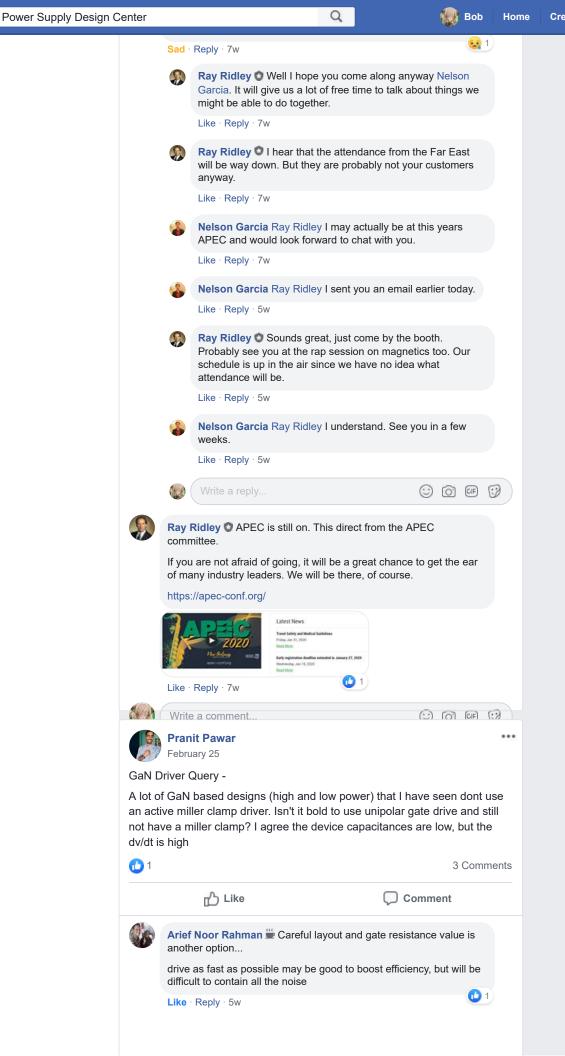
Jay Lee Very high esr and esl

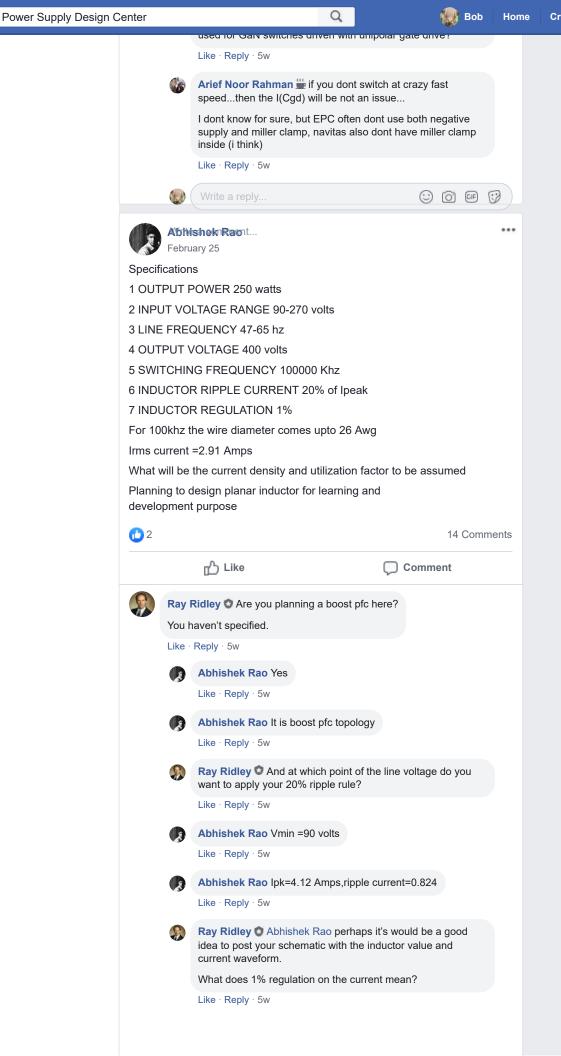


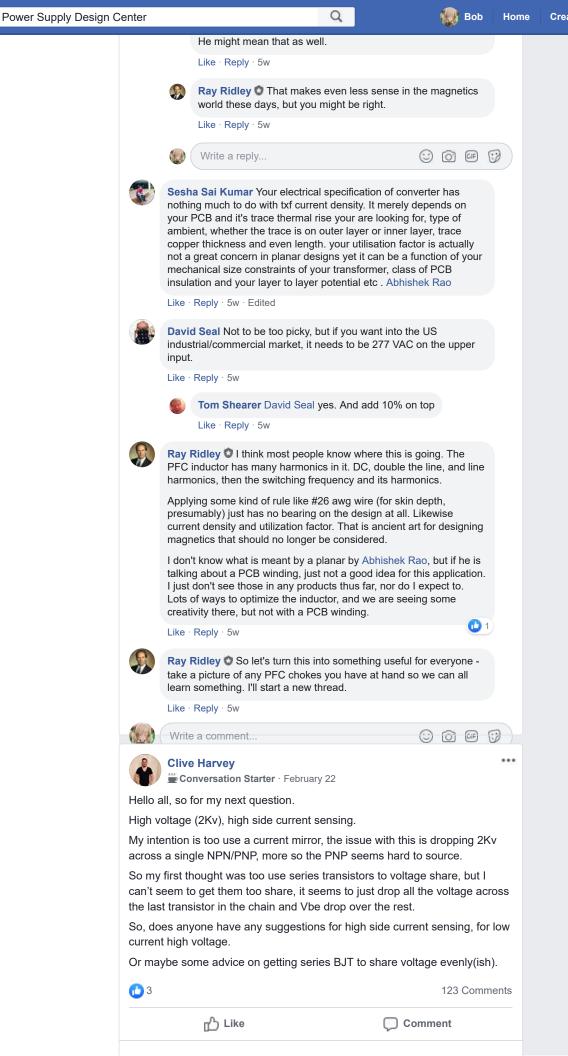
experience! Then straight into the trash can.

Do yourself and your company a favor - buy our design software and save a lot of time and money!









Like · Reply · 6w



Clive Harvey PRobert L Rauck I was considering this, but with very low current would this not be difficult?

I will want too set current limits around 10-20mA.

Like · Reply · 6w



**Robert L Rauck** Transformer turns ratio would be different but it can be done.

Like · Reply · 6w



Colorado Mike Doherty How much current?

Like · Reply · 6w

Hide 15 Replies



Clive Harvey Colorado Mike Doherty 10-20mA

Like · Reply · 6w



**Colorado Mike Doherty** Clive Harvey can you tolerate a series sense resistor with a set of matched voltage dividers upstream and downstream from the sense resistor? Amplify the difference for current to voltage.

 $\textbf{Like} \cdot \textbf{Reply} \cdot \textbf{6w} \cdot \textbf{Edited}$ 



Clive Harvey Colorado Mike Doherty to be fair that's not much different too the current mirror approach, I have a 1000hm sense resistor that I'm sensing from.

I guess this can be done with a diff amp rather than a current mirror.

But I'm guessing this would be expensive and also wouldn't there be issues with HV common mode rejection?

Like · Reply · 6w



George William Tyler Colorado Mike Doherty resistor tolerance become an issue

Like · Reply · 6w



George William Tyler How accurate must it be?

Like · Reply · 6w



Clive Harvey George William Tyler accuracy wont be a massive issue, this is for output safety protection, preventing a dangerous current, rather than output current control.

Like · Reply · 6w



Clive Harvey EGeorge William Tyler I'd have thought 10% wouldn't be an issue.

Like · Reply · 6w



**George William Tyler** Clive Harvey then sense primary current? Unless it's flyback

Like · Reply · 6w · Edited



Clive Harvey ∰ George William Tyler from a safety point of view I'm not sure sensing primary current is suitable.

If it is, then I could just set the primary side current limit accordingly.

Like · Reply · 6w



George William Tyler Human body can take 200a for 50uS













Like · Reply · 6w



George William Tyler This is the output of a fence energiser, designed to meet C2 rating. It's all about energy

Like · Reply · 6w



George William Tyler You hace caps on the output? Voltage multiplier? Flyback? How do you control the output current with whatever you sense with?

Like · Reply · 6w



Jay Philippbar How much bandwidth do you need?

Like · Reply · 6w



Clive Harvey George William Tyler do you know of any standards I could read?

My approach at the moment is to diode or the primary and secondary current sense, so if the output current exceeds the safety limit, the controller will start to fold back and go to constant current,

Like · Reply · 6w



Write a reply...











Col Johns High side current sensing has issues if the 2kV moves up and down a bit - consider low side sensing...(?) We have high side sensing on our 250VDC input MPPT controllers it is an exercise in analog design to scale up to 2kV, pnp/npn in series and controlled to give a linear result ...

Like · Reply · 6w





Clive Harvey Col Johns the issue being in the event of an electrocution we don't have control over the return path, hence high side.

I was hoping I could get the normal current mirror to work and share the voltage over several BJT, but I can't seem to get that to work. I've worked a lot more with FET's than BJT's.

Like · Reply · 6w



Col Johns If there was a small P channel SiC device at 2200V the analog level shifting would be easy ...

Like · Reply · 6w · Edited



Col Johns A very simple ckt for peak sensing would be via an opto ...

Like · Reply · 6w



Clive Harvey Col Johns my Monday plan was too look into FET based current mirrors, everything I've seen so far has been BJT, but I can't see why it can't be dont with FET.

So yes, I'm guessing there should be some suitable SiC devices.

Like · Reply · 6w



Clive Harvey <sup>™</sup> Col Johns would you simply put the diode of the opto in series? How accurate do think that would be? What drawbacks do you see?

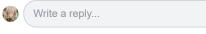
Like · Reply · 6w



Clive Harvey in I'm guessing with the CTR being so variable, it could be abit to crude?



Nathan Ellis Imagining this may end up being more expensive than optocoupler option though (not sure). Also if you want to learn more about cascoding you're prob best off heading to an analog circuit design book. I'm not sure what transistor mirror circuit you're referring to.









Like · Reply · 6w



Clive Harvey Scott Styles wouldn't the current need to be AC for a current transformer too work?

This is a D.C. Rail.

Also I would imagine this solution is quite expensive, which would be prohibitive.

Like · Reply · 6w



Scott Styles no it is a dc coupled device. it is just a DCCT with a heap of turns on it. ...as for cost can't say but have seen BOM cost angst translated into enormous development expense on many occasions...

Like · Reply · 6w



Clive Harvey Scott Styles in this instance it's for an automotive end use, so every penny counts on the BOM.

That's the real difficulty with automotive products.

If a cost effective solution to an issue like this can't be found, it can kill a product.

Like · Reply · 6w



Clive Harvey Scott Styles just did a quick bit of reading, DCCT do sound interesting. Do you know of any low current DCCT, that would be in the \$1-2 price mark?

Like · Reply · 6w



Scott Styles that's not really my world.. get in touch with Raztec and ask them. there is another company in the states that does baby DCCTs like this but name escapes me.

I'm just an NPI engineer. I don't do design. I do get involved in fixing thigs that have been overly KISSed or overly cost wrung out though...

Like · Reply · 6w



Clive Harvey Cheers I'll check them out.

That I can relate too.

Like · Reply · 6w



Write a reply...











David Seal Proportional opto-coupler. Float the high side as high as you want, it won't care.

Like · Reply · 6w



Clive Harvey David Seal does that differ from a normal opto?

Like · Reply · 6w



David Seal The emitting (sensing) LED gives off an amount of light proportional to some given input voltage. This requires internal support circuitry to do, since the LED light curve is not linear. The receiving side is an LED of identical design, and also with support circuitry to keep the proportions linear.

Like · Reply · 6w

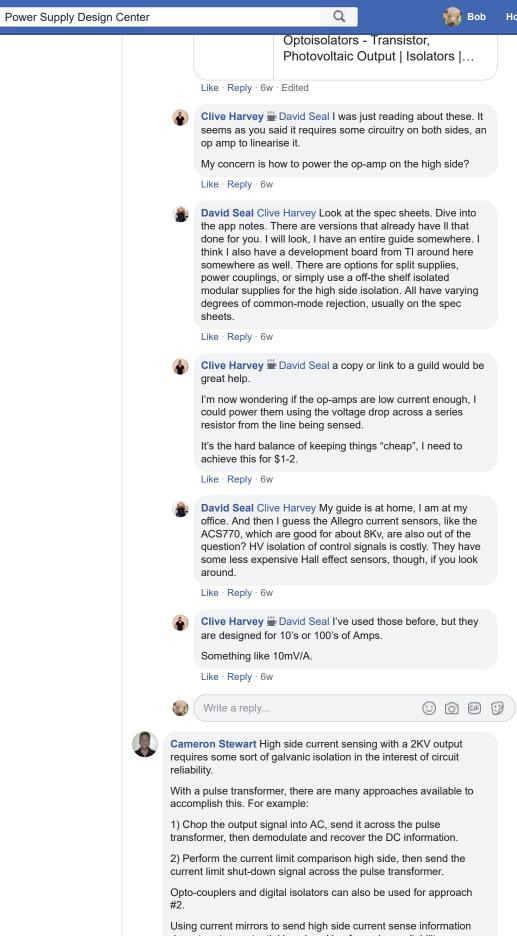


Clive Harvey David Seal ok that's interesting and this support circuitry won't mind the high Common mode voltage?

Like · Reply · 6w



**David Seal Clive Harvey** https://www.digikey.com/.../optoisolators.../903...



Using current mirrors to send high side current sense information down to return potential is only asking for serious reliability problems.

 $\mathsf{Like} \cdot \mathsf{Reply} \cdot \mathsf{6w} \cdot \mathsf{Edited}$ 



**Cameron Stewart** A schematic or block diagram illustrating the application would help. There are too many missing pieces of information.



application is quite simple. It's a HV flyback, I've had a few posts and advice regarding it, I think you have offered some advice on it.

What I'm trying to achieve is an output current limit for safety limit or cut off.

My concern is that if I do this primary side, this won't be suitable for a safety case, that's point of load sensing is what's really needed.

Like · Reply · 6w



## **Cameron Stewart** Clive Harvey

I think sensing primary current is actually safer: There is no way that you can have a secondary current limit fault without it being reflected back to the source at the primary.

Where else is the energy being sourced except at the primary, into the flyback transformer?

So I disagree with your assertion that sensing primary current is somehow not safe.

The main limitation with primary current sensing is accuracy. But accuracy should not be confused with reliability or safety.

If your primary current sensing is only 10% to 15% accurate, from a safety standpoint that is still acceptable. The human body shock threshold will vary far more than that anyway because skin resistance varies so much.

You do not require 1% precision accuracy. You require reliability and low cost. Primary current sensing easily fits the bill.

Like · Reply · 6w · Edited



Clive Harvey Cameron Stewart thanks for this, I think I'll do some testing on this and if I can prove the safety case, that I as you say, all is reflected too the primary this is a great solution.

I guess what I have to confirm is what my variation in primary side current is for the same output current and make sure I can't exceed my safety limit.

Just off the top of my head, if I measure/simulate the primary side current at the output limit, and limit my primary current too this, I shouldn't be able to exceed this.

That side, my primary current varies at input voltage.

So the primary input current at 9v input vs 18v input, would allow for twice the output current.

Given that the primary current can vary so much, that's why I was trying to do output current sense.

Like · Reply · 6w



#### **Cameron Stewart** Clive Harvey

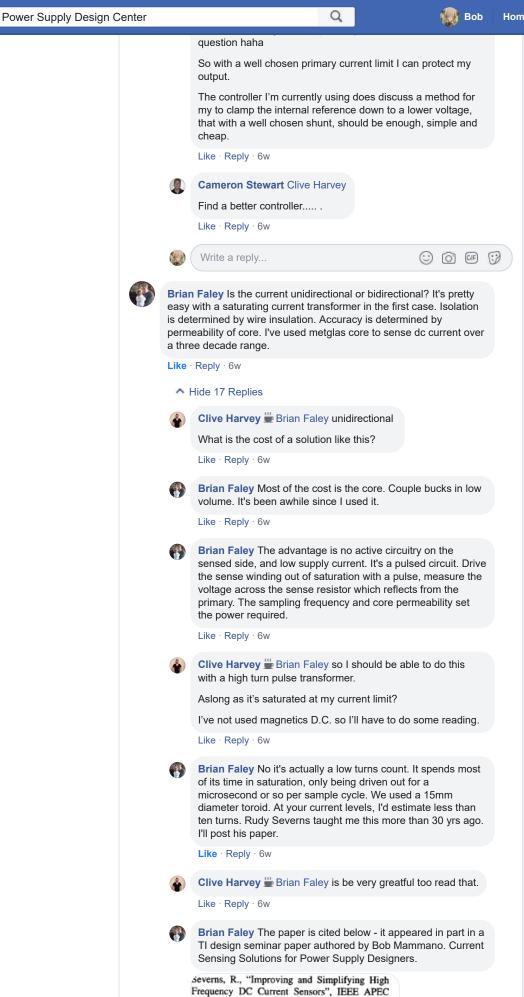
The energy into the transformer per cycle is 1/2 Ll squared. If the input voltages increases, you simply reach the peak primary current limit point sooner during each cycle.

But current limit at 9V input is the same as current limit input at 18V.

The argument is more mathematical and basic physics than one of safety.

I'm assuming fixed frequency PWM in making this argument.

Things get messier for fixed on time, variable off time operation.



Conference, 1986.





Like · Reply · 5w · Edited



#### **Brian Faley**

2. When the pulse generator is on, Q1 closes and the reversal in voltage across the secondary allows the core to come out of saturation with a current Is = Ip / Ns. At the same time, Vo is developed by sampling the voltage on Rs caused by Is.

This circuit could potentially operate with sampling frequencies up to the megahertz region, allowing reasonable resolution of current waveshape with a bandwidth in excess of 100 kilohertz. An additional benefit is that the low duty-cycle of the excitation voltage acts as a multiplier to the turns ratio and allows very high primary current without a corresponding number of secondary turns. [12]

Like · Reply · 5w



Clive Harvey Brian Faley unfortunately I'm not an ieee member to can't view the paper.

Like · Reply · 5w



Clive Harvey Brian Faley cheers for the screen shoots. That's a clever approach.

So, I guess this is measuring the time it takes for the core to saturate, the lower the current, the slower the core saturates, this then averages the current flow across the sense resistor.

Like · Reply · 5w



Brian Faley no. during the time that the core is driven out of saturation, the current in the sensed winding will flow through the secondary sense resistor - reflected by the turns ratio. The value of the sense resistor times the reflected current equals sensed voltage. It will only appear as long as the pulse is active - so you'll need a sample and hold - or a diode / capacitor circuit to isolate it. It's pretty easy to generate several volts on the sensed winding. It's only for a short time in my case we ran at 100khz with an on-time of about 500ns.

Like · Reply · 5w



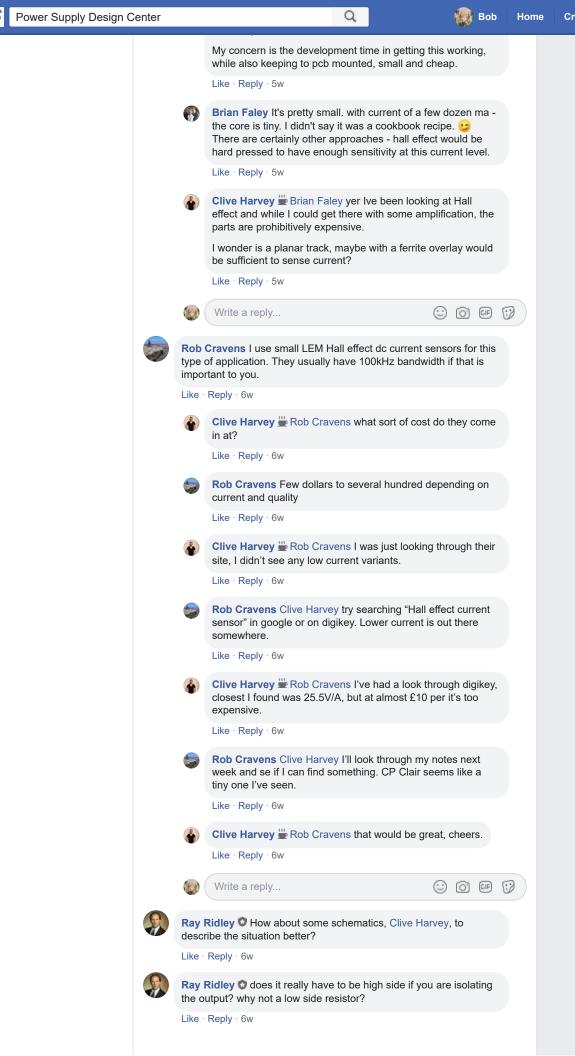
Clive Harvey Brian Faley are there controllers available to do this or does it need discrete design?

Like · Reply · 5w



Brian Faley a really square loop core like metglas has a permeability approaching 100K. Since the saturation is amp turns - a dozen or so turns is plenty to saturate the primary even at milliamp levels. This is a sampled system. It's going to take some work to figure out what the best turns and core combination is. The advantage is no active circuits on the hv side. We implemented this with a TLC555, a low leakage diode and capacitor, and a p-channel fet. I don't know of an off-the-shelf IC .

Like · Reply · 5w · Edited



Home

This is to protect for safety, so the return path could be a human, this is to prevent electrocution.

Cameron Stewart has pointed out with a well chosen primary side current limit I should be able to limit my output current sufficiently for safety.

Like · Reply · 6w



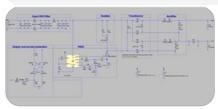
## Cameron Stewart Clive Harvey

If we had a circuit diagram to view, I think we could show you how to do low side secondary current sensing and still gurantee safety.

Like · Reply · 6w



Clive Harvey E Cameron Stewart heres the initial approach.



Like · Reply · 6w



### **Cameron Stewart** Clive Harvey

Just as I thought:

Remove the ground at the bottom side of the L4 / C6 junction.

Connect your current sense resistor from that junction to ground. This eliminates the non-isolated ground as a problem. You will need to sense a negative going current sense signal with respect to ground.

A single supply opamp (LM2904) to sense current limit will perform this function, without a (-) rail housekeeping supply source.

Ground the (-) terminal of the opamp.

Connect a summing resistor from the (+) terminal of the opamp to the current sense resistor negative signal.

Connect a second summing resistor from the (+) terminal to your LT1247 Vref pin.

Install a schottky clamp diode: Cathode at the (+) input. Anode to ground. This prevents the (+) terminal from being pulled below ground and forward biasing the IC substrate.

The output of the current limit opamp will pull down on the LT1247 compensation pin through a series or ing diode, overiding the voltage loop.

Sometimes, frequency compensation is applied to the opamp to gurantee stability, in the form of a pole zero network. This takes an extra network between the opamp output, the (-) terminal and ground to implement.

Having said that I've noticed one thing, completely unrelated: The EMI filter has no damping network for stability.

Like · Reply · 6w · Edited



Clive Harvey Cameron Stewart owww I hadn't even considered that, so measuring the return path for the output capacitor. I'll read this again tomorrow, as it's silly o'clock here now and I should have been in bed hours ago, just got stuck binge watching a series lol.

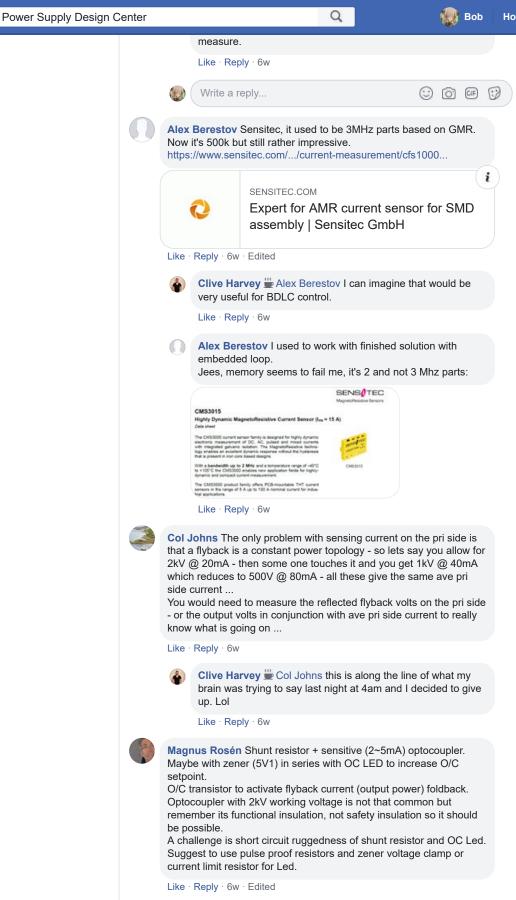
Like · Reply · 6w



#### Cameron Stewart Clive Harvey

I've updated my previous post to correct for wrong polarity issues with the opamp terminals.

Like · Reply · 6w · Edited

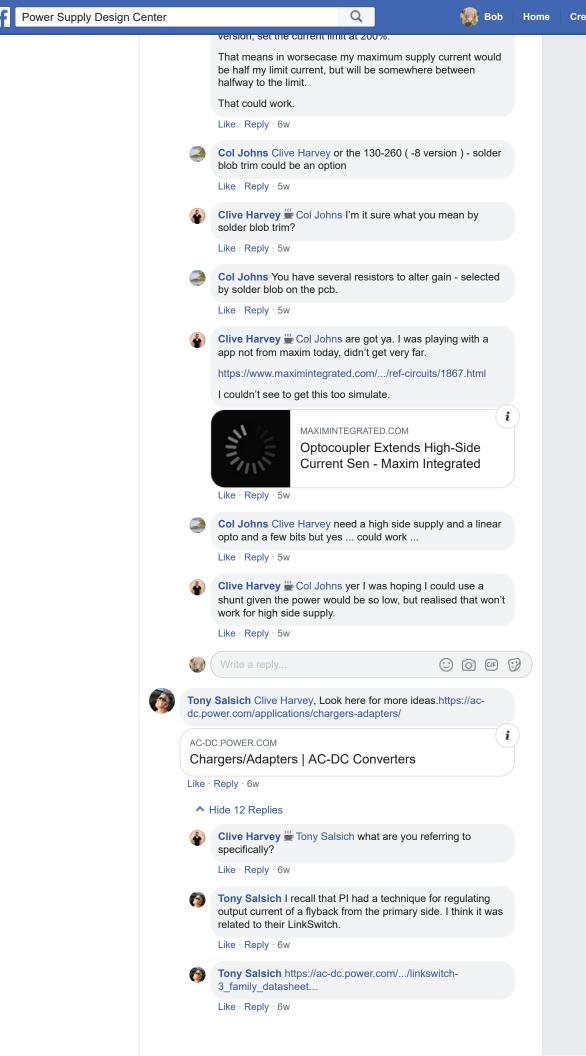


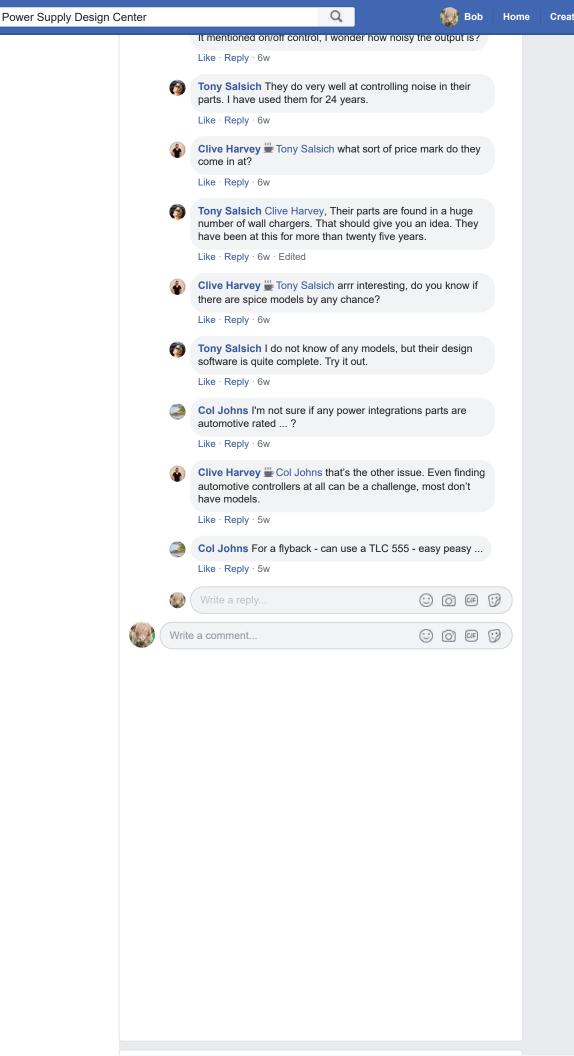


Col Johns Automotive rated; VOMA618A-8

https://www.google.com/url?sa=t&rct=j&q=&esrc=s...







What's in the Ridley Box?

Come to booth Number 1517 at APEC 2020 to learn about our new product which will shake some things up in our industry. We will just leave it cryptic

Q



🕧 You, Jay Philippbar and 38 others

22 Comments







Ray Ridley O Notice we have hired the young generation here at Ridley Engineering to make sure we are keeping up with the times!

Like · Reply · 6w



John Baillie Damping circuit for input filter? 👙



Like · Reply · 6w



Ray Ridley Glad you have being paying attention!

Like · Reply · 6w



Richard Payne Jack in the box

Like · Reply · 6w



Ray Ridley We could have saved some airfare there - good idea for next year!

Like · Reply · 6w

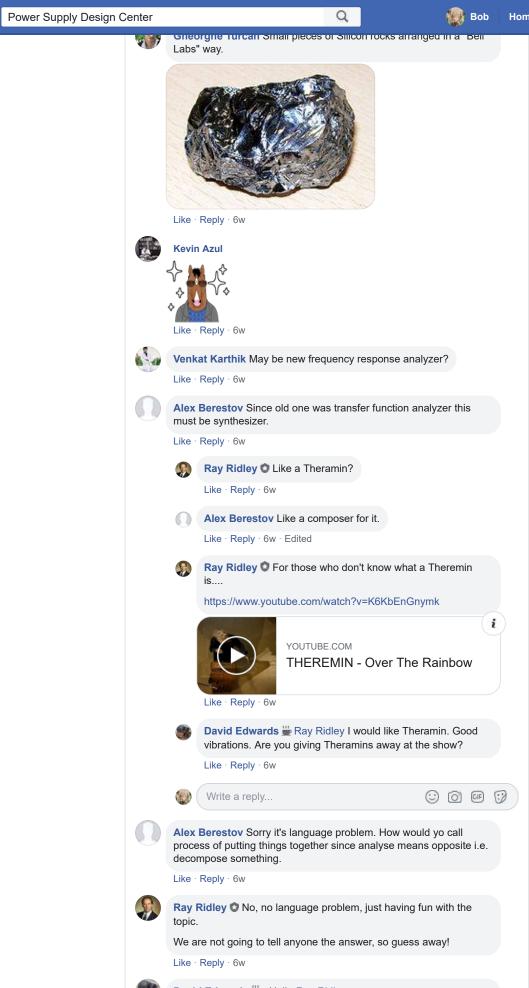


Steve Mowry 60Hz magnetics?

Like · Reply · 6w

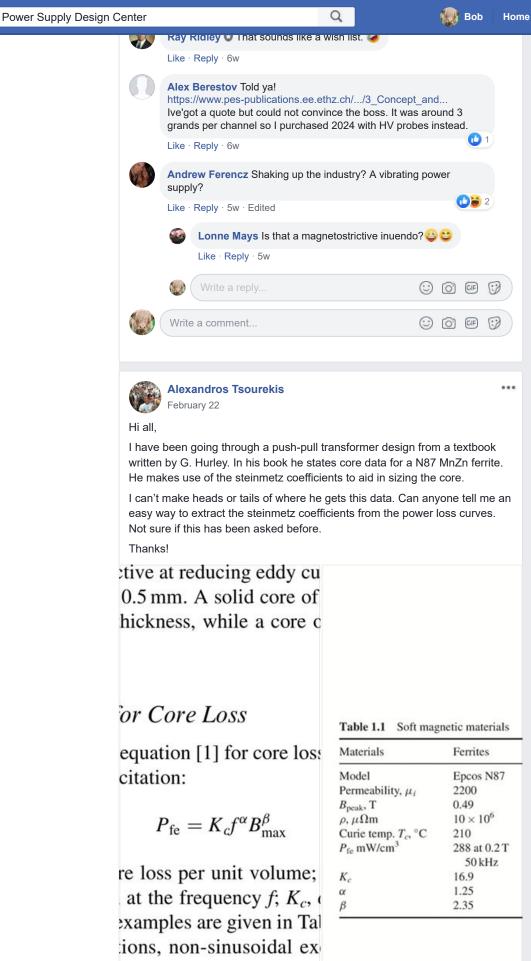


Ray Ridley We have some 0.1 Hz magnetics, part of our injection isolator.

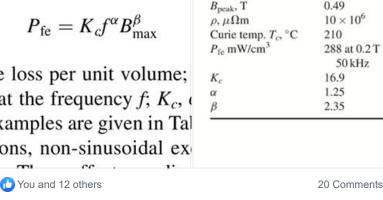




Perhaps among other things, the box contains individually packaged wireless battery powered oscilloscope channels where the display and controls are on a laptop, tablet or phone device?



Like



Comment



Like · Reply · 6w



Nicola Rosano Easier then youssef advice you can do the following.

Q

If you have core losses curves, simply consider 2 curves around your switching frequency (let's say 100kHz and 200kHz). On the 100kHz curve take 2 points and register power loss and flux induction values. Repeat the same process on the second curve for 1 point only and register power loss and flux induction.

Actually you can build three steinmetz equations (three points) with (B,P and f) noted for each point. Three equations in three variables (Kc,alpha,beta coefficients to define). Done.

Like · Reply · 6w · Edited

#### Hide 14 Replies



Alexandros Tsourekis Thanks to both of you for the advice. I tried doing some log/In functions to try and get simultaneous equations. I thought there would have been an easier way to do this. I was using three points for the 100khz because that's the only curve I had. I'll give it another try.

So just to confirm what Nicola Rosano is saying, the steinmetz coefficients would be the same for the 100khz and 200khz? Sorry if it's a bit of a stupid question 🙂

And just as a note to anyone interested in the book, it's an excellent book both in terms of theory and practice, but it's riddled with little typos so just some caution to anyone using

Like · Reply · 6w



Paul Shepherd Alexandros Tsourekis It's one of the better values in engineering references out there. Not \$200 is a nice thing! And, Professor Hurley is a very friendly guy (I played tour guide at a conference for him one time)

Like · Reply · 6w



Alexandros Tsourekis Paul Shepherd that must have been quite a treat. Didn't mean to take a jab at the book, it's hands down one of the best engineering textbooks I've read

Like · Reply · 6w



Nicola Rosano Alexandros Tsourekis generally steinmetz coefficients are not the same but spreaded on frequency domain - typically divided in 3-4 frequency bands. You can see it easily on the magnetic datasheet. But if not present, as your case, you can use that method for a simple approximation. It works pretty good.

P.s. just as an example.

Give a quick look to Ferroxcube datasheets for 3C97 or 3F36 material. These coefficients are reported clearly.

Like · Reply · 6w · Edited



Nicola Rosano See page 7 attached link as example.

https://www.google.com/url?sa=t&source=web&rct=j...

Like · Reply · 6w



Alexandros Tsourekis Thanks Nicola Rosano, that's clears up a bit of confusion. I see in the ferroxcube datasheet they have power loss curves for more than one frequency but I don't see the actual Steinmetz coefficients published in the material datasheet.

Like · Reply · 6w

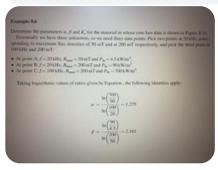


Alexandros Tsourekis Sorry I typed that too soon, I'm clearly looking at the very condensed versions of the datasheets

Home

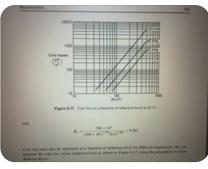
back of the back theres an example. I'll leave this here for someone else's reference. In Hurley's textbook chapter 8.3 shows how to get these. Sorry if I wasted your time.

Q



Like · Reply · 6w

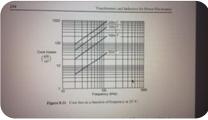
## **Alexandros Tsourekis**



Like · Reply · 6w



#### **Alexandros Tsourekis**



Like · Reply · 6w



## Nicola Rosano Easy told you 🙂



Like · Reply · 6w · Edited



Nicola Rosano I can even add it is not the best book on magnetics (to me). Surely more recent then McLyman 3rd edition.

Note also two things:

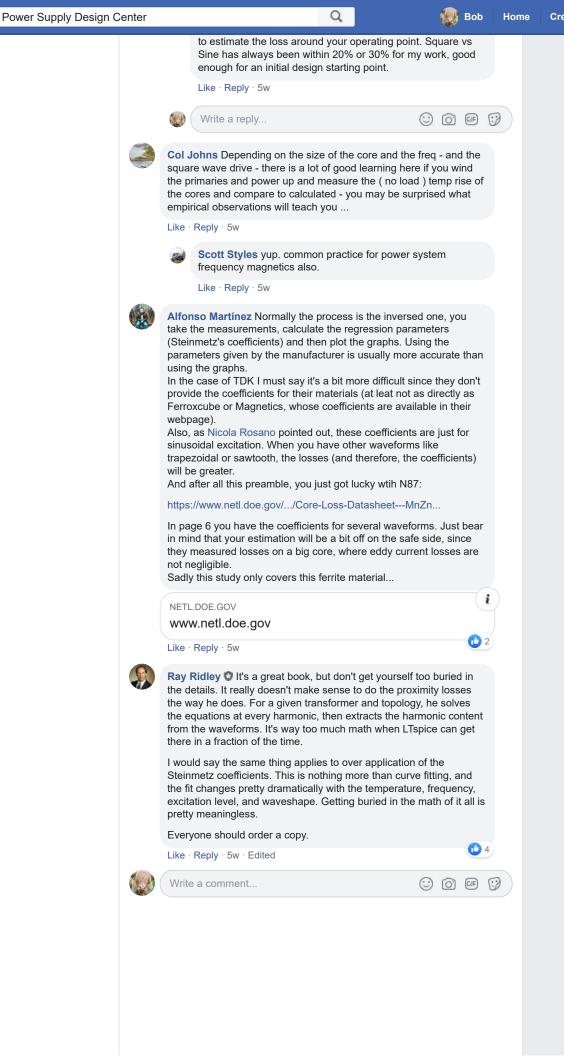
- 1. despite result doesn't change 'log' function the datasheet typically refers is 10 base not Neper base.
- 2. That curves , just to close the loop, assume your excitation is sinusoidal with DC component null (not valid for hard switching converters in which the excitation is a 'square wave', sometimes, with DC component).

Basically your results will be underestimated.

Like · Reply · 6w · Edited



Alexandros Tsourekis Nicola Rosano I've been mixing and matching books. I find the book is really good at explaining magnetic fundamentals, and yes it is more recent, which is part of its appeal. I agree, using log or In should not make a difference in the calculation even though the base is 10 on the graph





# **Arief Noor Rahman**

Conversation Starter · February 19

How to clean flux residue under high voltage TO-Leadless package?

This TOLL package is promoted to have very low package parasitic, but now I have a problem like large leakage from Drain to Source at higher voltage, which to my experience it tells me that there is a flux residue between drain and source....

Thanks,





34 Comments







Scott Styles could you put a route in the PCB?

Like · Reply · 6w



Arief Noor Rahman ws sorry, i dont understand what a route is?

Like · Reply · 6w



Col Johns Arief Noor Rahman A small width routed line in the pcb between drain and source ...

Like · Reply · 6w



Arief Noor Rahman iii like a pcb cut out?

in my case now, i cant do that because I need to use the bottom layer for the power return path...and it needs to be as short as possible, thus its impossible for me now



Write a reply.







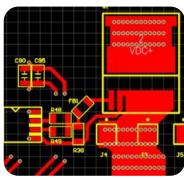


Arief Noor Rahman well...i just remove the mosfet, and clean all the flux, and solder again without additional flux...now it works...but, it is very difficult to ensure good solder flow without flux...(i have no idea if my solder tin can flow properly)

Like · Reply · 6w



Arief Noor Rahman 🎬



Like · Reply · 6w



Broox Le Leadless packages are almost impossible to reliably clean under. It can be done by ensuring a good solder stand-off height (solder-mask defined pads can help) and then solvent bath cleaning, but it's not usually recommended for production. The noticeable conductivity is most often a problem with water-soluble and fluxes which are 'cleaning required'. Instead, for leadless device packages, it's recommended to use only 'no-clean' solder flux and ensure the amount & reflow process parameters are set to ensure all of the flux will be rendered inert after reflow ('no-clean' fluxes have to be exposed to enough heat for enough time to render them inert & nonconductive).

Like · Reply · 6w · Edited



**Bob Gudgel** I would re-iterate what Broox just said. Use noclean flux that -deactivates when the board goes through the reflow oven.

I've been through hell and back with solder flux being conductive even at lower voltages when they were either dirty or still "active". It's awful. Pain in the butt. Good to have a production engineer that understands this stuff if you can find one and have the funds.

Like · Reply · 6w



Arief Noor Rahman in am now just making a pcb prototype, but it still pain in the \*, because after i realize this problem, I then remove all the important component clean it from flux residue without any added flux...it was painful...haha

Like · Reply · 6w



**Broox Le** Note, water soluble and 'cleaning required' fluxes can appear non-conductive when the assembly is warm, but later absorb moisture from the environment to become noticeably resistive.

...I discovered one PCB assembler used the wrong flux on a batch of boards such that some of the white LEDs on the boards had effectively become dim 'night lights' - as just a few micro-amps of current were bleeding through the flux to ground, and visibly lit the LEDs enough to be noticeable in a dark room - and was surprisingly bright when the user's eyes adjusted to the dark.

Like · Reply · 6w



Arief Noor Rahman wy ya...I once have an inverter with TO247 package mosfet, I forgot to clean the flux residue on the PCB and even at voltage below 30V, the current between the MOSFET pin is already very high...

 $\text{Like} \cdot \text{Reply} \cdot 6w$ 

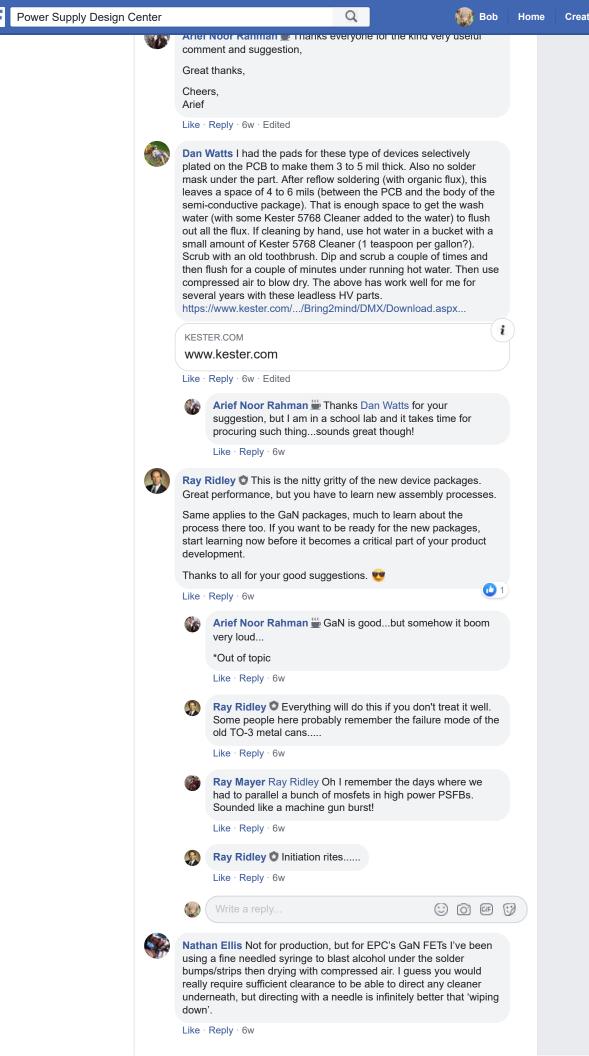


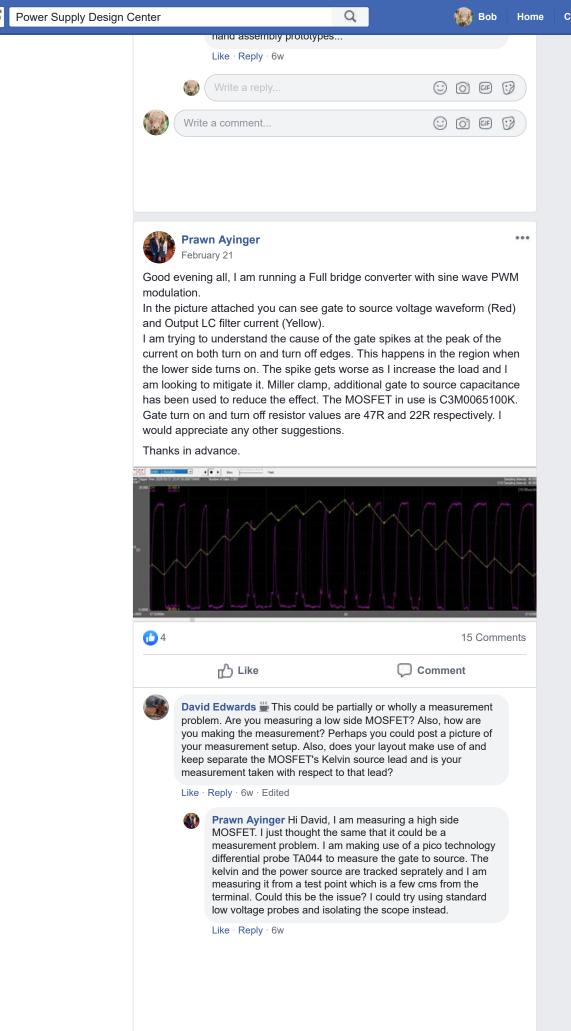
**Dustin Lackey** We have had some success specifying underfill which at least fills in the area with nonconductive material.

Like · Reply · 6w



**Colorado Mike Doherty** Great to see some sound advice here. This is a powerful group!





problems make no sense at all without it.

Like · Reply · 6w

Peter Bernard Green May be due to MOSFET body diode recovery in hard switching operation.



Home

manufacturers relable as their own: https://www.sapphire.com.tw Their website has PDFs of their calibration procedures (and the hidden adjustments under the label).

Q

Aeroscope made a low cost (<\$300) wireless scope probe (no longer available). I believe they were crowd funded at first and evolved into IKAscope: https://www.ikalogic.com

Enertronics made the wireless probe WP-A100, but seem to be out of business, but the paper Alex found is worth a read: https://www.pes-publications.ee.ethz.ch/.../3\_Concept\_and\_Exp...

And, of course, Tektronix makes the very expensive (>\$20k), very high performance IsoVu probe: https://www.tek.com/isolated-measurement-systems



bandwidth unless the leads are dressed very carefully. The leads should be twisted together and run through high perm long format ferrite beads. The grabber probes should be cut off and the wires ends soldered directly into the circuit under test. The beads form a common mode low pass with the 15pF or so common mode capacitance to ground, which improves the probe's basic performance.

Common mode rejection of these inexpensive probes is around 1000x at 1MHz, less at higher frequencies. A 200V switching signal may produce several volts of common mode signal on top of the differential mode gate drive signal in a hard switched application, hence the need for the additional common mode rejection provided be the ferrite beads.

The twisted pair leads should be spaced several centimeters away from the PCB to avoid capacitive coupling from high dv/dt circuit traces.

Like · Reply · 6w · Edited



David Edwards The Aeroscope probe may be the wave of the future. These type of probes benefit from cell phone and tablet technology. The are powered by rechargeable batteries that last all day and communicate to a PC, laptop, tablet or smart phone by WiFi or bluetooth. In order to make this work they must have on board data acquisition memory and just stream the video data to the remote display/controller device. What a great idea.

Like · Reply · 6w



David Edwards ∰ Notice the difference in exposed metal between the Aeroscope and the IKAscope probes. This is probably due to the need to meet strict safety regulations to minimize shock hazard.

So how should one access physically hidden signals with a relatively large probe? Certainly holding it by hand near potentially lethal exposed circuit voltages is not a good option. I like to set up the measurement with the power off and be safely distant before applying power. Perhaps scope tip jacks could be an option (but the tip ring must be accessible).

Another option is to cut a short length of small diameter (0.3cm) Kapton insulated coax and solder one end directly to the gate and source leads of the device under measurement and solder a scope tip jack to the other end.

If the cable must be longer than 20cm or so then a surface mount 50 ohm resistor should be inserted between the gate lead contact point and the center conductor of the coax for impedance matching. A high perm ferrite bead or two around the cable might be a good idea as well.

Like · Reply · 6w



Arief Noor Rahman We have that plenty of that sapphire instrument HV diff probe in our lab, and we use it all the time for high side measurement...

For all silicon switches they are generally good enough, for SiC so far still okay though not perfect, but for GaN maybe too slow to capture all its fast transient and ringing...

I never need to do what David Edwards did, which I guess also depends on how accurate you need it to be...

Like · Reply · 6w



**Adam Lawrence** Arief Noor Rahman Same for our lab. We use many rebranded Sapphires for applications in the tens to lower hundreds of kilohertz. IsoVu is much better for GaN.

Like · Reply · 6w

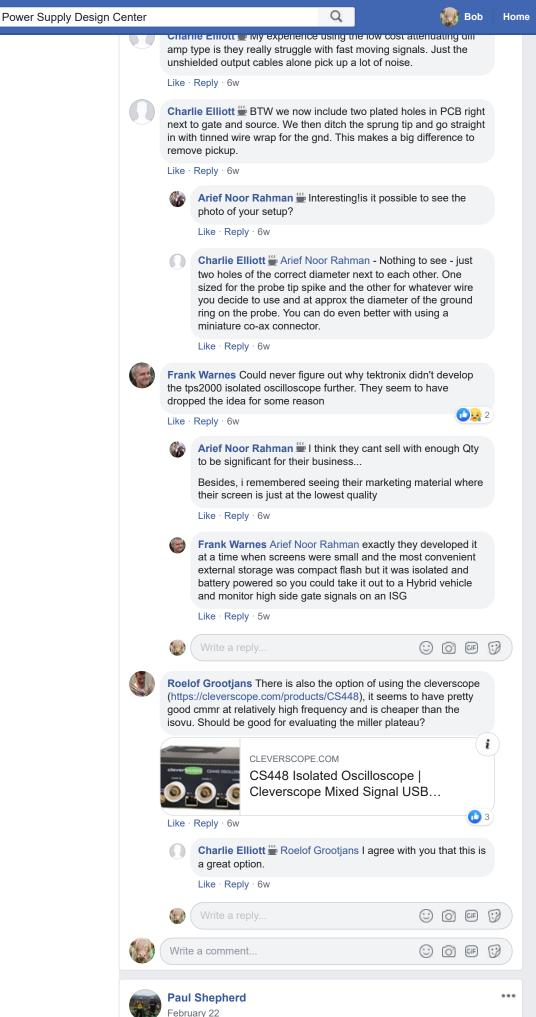


Arief Noor Rahman Thats out of question...but considering price of >50x...it is hard to make purchasing decision

Like · Reply · 6w



Ardhendu Das Also check out pinteck probes , they cost around 300-350\$





Has anyone combined digital command and condition monitoring with an analog modulator? To be more specific, I'm thinking about one of the classic modulators like the UC1843, combined with a microcontroller to add all of the "fancy" things. One random example that I don't think I will do, but shows the kind of potential I am thinking about, is to use the uC to generate the sync pulses and create frequency jitter. For another example, the PWM Modulator could do the current-loop control directly, but the uC might be able to implement the Type II compensator between and A-to-D input and a D-to-A output.

Thanks!



24 Comments



Comment



A-ARon Jones A hybrid? Sounds like the best of both worlds but it would be expensive and relatively inefficient at low loads (sleep current of processor plus analog components)

But sounds like fun from a designer point of view.

You can do a lot by modulating the feedback pin of a traditional control loop with a PWM signal and choosing a controller with an external frequency sync pin

Like · Reply · 6w · Edited



Paul Shepherd That's exactly my thought. Good point about the uC being a drag at light load. Fortunately, I've transitioned from commercial world, where a \$1 DC/DC converter is a crisis, to aerospace, where at \$250/circuit board, I'm still the cheapest part in the system.

Like · Reply · 6w



Paul Shepherd I was playing with a REALLY fancy Linear Tech part (LT8711) last year, and it does a lot of things that I like, but there are some features that I would turn off if I could. That's one of the things that is making me think about this hybrid approach.

Like · Reply · 6w



Joel Holland A-ARon Jones could you explain a bit more about digital control at low/no load?

Like · Reply · 6w



A-ARon Jones Joel Holland it's mostly a matter of the current running to keep the system alive, while most microcontrollers can get to pretty low sleep currents running the ADC (depending on architecture and sample rate) can take as much current as the load.

It's still milli/micro amps but it matters if your system is running off a battery

Like · Reply · 6w · Edited



A-ARon Jones Paul Shepherd is weight and PCB real estate still a major problem in aerospace power supplies?

Like · Reply · 6w



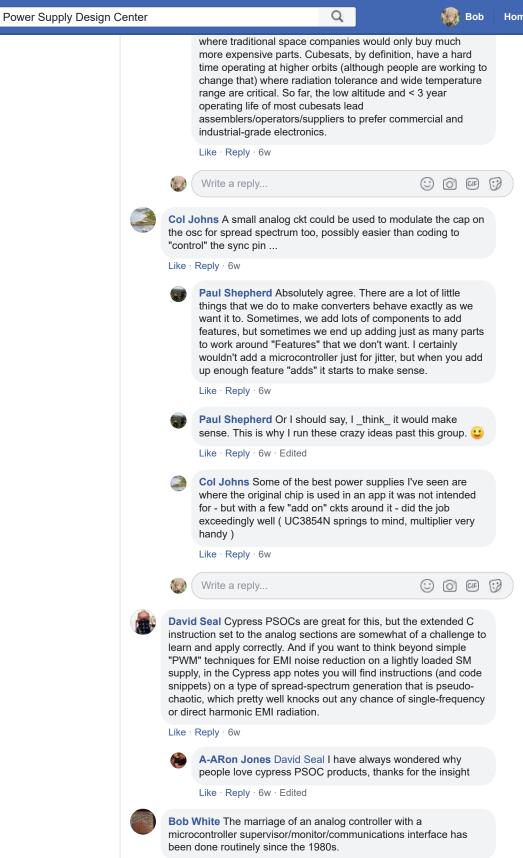
Paul Shepherd A-ARon Jones Yes. Mass has always been the enemy, but volume is also now an issue because I work in cubesats. The tradeoff is that cubesat companies are much more open to COTS components.

Like · Reply · 6w · Edited



A-ARon Jones Paul Shepherd why would other companies not be open to CoT? Too hard to prove the stability of nonlinear control?

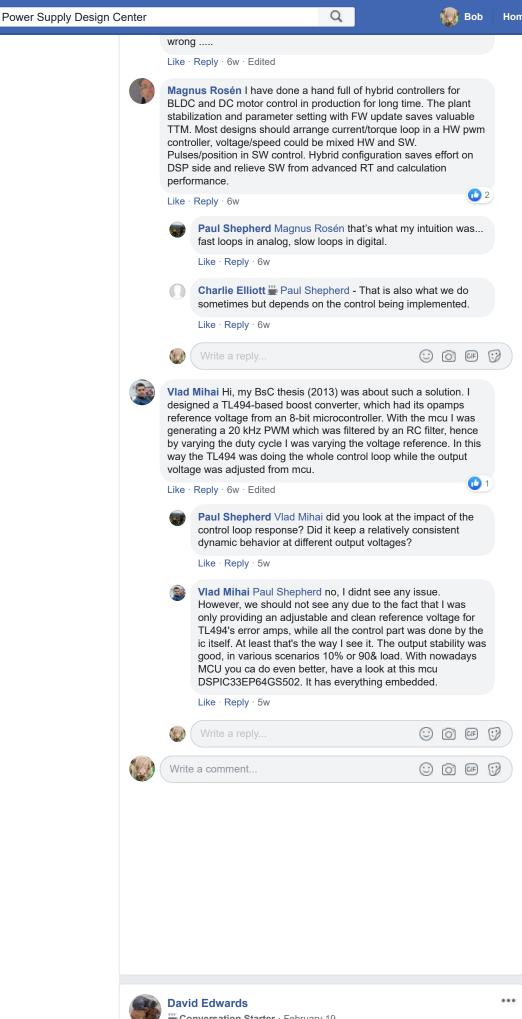
Like · Reply · 6w · Edited



Like · Reply · 6w · Edited

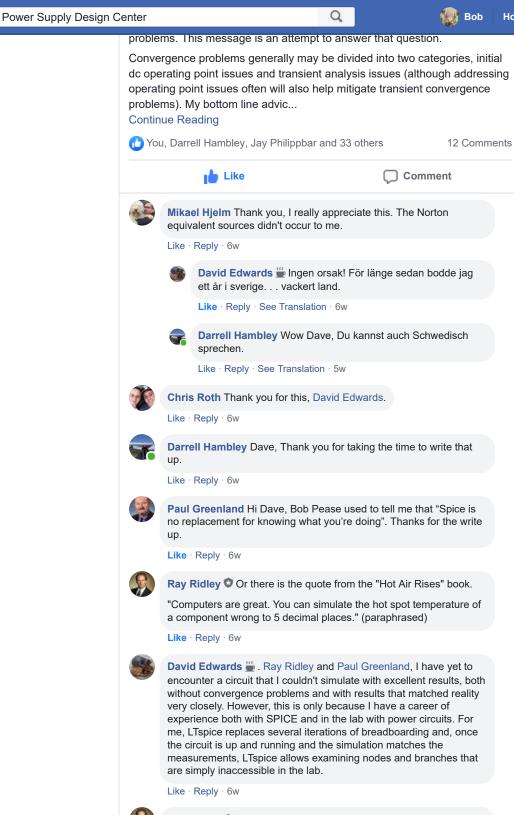


Brian Faley I've personally done dozens of hybrid designs that are still in mass production, using an analog modulator with a digital controller providing reference, on/off, and sequencing commands. Inverters, battery chargers, power supplies. Everything from 10w to 80kW. Despite the promises of digital control, I've never seen one out perform a well tuned analog system using peak or average mode current mode control. It is more expensive, and requires solder to program. Much more robust over current and short circuit protection.





LTspice Convergence





Ray Ridley Indeed, it is a great tool when used wisely. Indispensable.

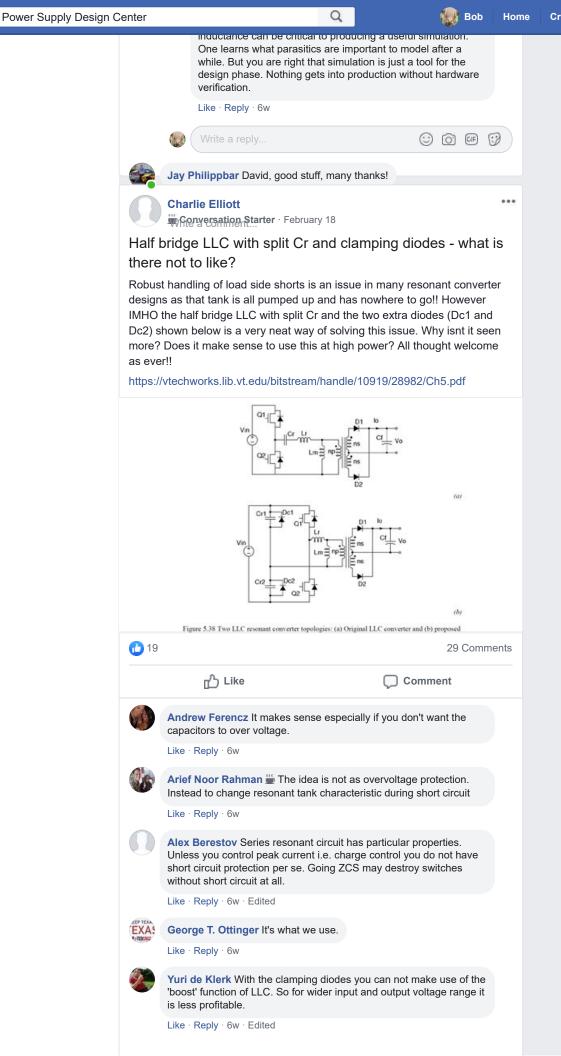
The point I always try to make is that it doesn't make the hardware testing unnecessary.

Like · Reply · 6w



Ray Ridley Another way to think about it - rarely do things surprise me in a simulation.

Always, the real circuit surprises me.



design and our Application Note might be of help for your future designs.

Like · Reply · 6w











Daniel Pruna I have used for 2kW design, it works pretty well.



Like · Reply · 6w



Yuri de Klerk I simulated it (PSIM) and it works wonderfull, besides the drawbacks I mentioned.

Q

Maybe also tested it, but it was about 9 years ago so not

Like · Reply · 6w · Edited



George T. Ottinger 6000 short circuits (each) in HALT testing on 4 samples of my product, both applying short while running and startup into a short.

Like · Reply · 6w



Hamish Laird Charlie - this is in a very high volume telco supply from about 2006 2007.?it does all you need.

Like · Reply · 6w



Ray Ridley There is another variation where the caps are just put in series with the transformer, one next to Lr and the other in the return leg. Diodes used as mentioned.

Any comments on this versus the figure b proposal?

Like · Reply · 6w



Col Johns One would still be clamping the Vpk on the caps to the supply rail - in fig B the caps sit at HVDC/2 on average but their AC excursion can be from 0 to HVDC allowing a certain amount of boost function from the LLC (CLL), for a series cap ( to the Tx ) the net average volts are 0, again 2 diodes are required - and the excursion is +/- HVDC on the series cap ( at half the capacitance ) - at first glance the effect would be the same (?).

Like · Reply · 6w



Yuri de Klerk I can not figure this in my mind. A drawing maybe?

Like · Reply · 6w



Kevin Azul



Like · Reply · 6w



Ligi Zhang check this one, medium voltage and high power https://ieeexplore.ieee.org/abstract/document/8345190

Like · Reply · 6w



Charlie Elliott Eliot Zhang - Any chance of publishing this on researchgate.net so everybody can see the fruits of your hard work?



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i

Like · Reply · 6w · Edited



Ray Ridley Or, for this group, just put up the schematic so everyone can see it without having to pay.

Like · Reply · 6w



Col Johns the paper cited is not that relevant ...





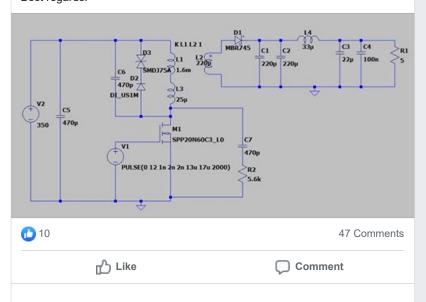
Hello,

I'm the guy who have trouble with flyback converters. Few days ago I asked the question about blowing-up resistors and MOSFETs. After your advice, I realized the reason why they are blowing up. The problem is that transient voltages due to leakage inductance of flyback transformer. In order to compansate voltage spikes, I changed the snubber network which is parallel to flyback transformer. And added one more network to MOSFET's drain to source.

Most of transient voltages have been suppressed. But I can not suppres the first transient voltage that has the highest frequency. In my opinion speed of my components are not enough to suppress first transient voltage. I susptected from rectifier diode which is part of snubber circuit which is connected to flyback transformer. But diode type is UFRR. So I didn't find any solution suppressing first transient voltage. Can you help me please?

You can find the circuit that I'm having trouble with below.

Best regards.



capacitance which can make it look like an UFRR property. If I understand correctly, you are struggling with a MOSFET turn-on current spike? If yes, you may want to consider replacing C6 with an RC snubber. I cannot comment on the value chosen for C6, but the transistor will have a low impedance path to V2 at turn-on if you don't add a series snubber resistor. Value to be chosen based on bench waveform measurements. While on the subject of snubbers, R2/C7 values will have virtually no effect. R2 is much too high to be an effective snubber resistor. You might want to experiment with much lower values on the bench.

Like · Reply · 6w



Bahadır Yıldırım Hi Alain, thank you for your advices. When I open the datasheet of IS1M, datasheet says it is UFRR. If that is not UFFR, how can I understand it? In practice, when I use V2 as low voltages like 110VDC, there is no problem. When V2 goes to higher voltages, MOSFET and resistor go to failure. By the way, I'm supplying external to pwm controller. So pwm controller switches in low freq. There is two reasons for failure. First one is when V2 goes higher voltage values, IC starts burst mode and switches at higher frequency. Thus, voltage spikes become bigger than before. Second one is only when V2 (like 140VDC) goes higher voltage values, voltage stresses impact as destructive. But I can't determine.which one is the source of problem.

Like · Reply · 6w



Alain Laprade Bahadır Yıldırım Sorry about that. I was referring to MBR745. Unable to comprehend the description of your technical problems. Best I leave it to others. But do consider the C6 and C7/R2 comments.

Like · Reply · 6w



Bahadır Yıldırım Alain Laprade I will. Thank you.

Like · Reply · 6w



Write a reply...









Tony Salsich Bahadır Yıldırım, there are many app notes on how to solve this. Look at any chip vendor's reference design, but do read the explanations given for the component choices. Look for the term, RCD clamp.

Like · Reply · 6w



Bahadır Yıldırım I tried RCD clamp but didn't work. This one is working better than RCD actually.

Like · Reply · 6w



Tony Salsich This one is very lossy and causes large current spikes for the Mosfet. The RCD clamp is effective if done properly.

Like · Reply · 6w



Bahadır Yıldırım Thank you for your interest. I will recheck that topics.

Like · Reply · 6w



Paul Shepherd Tony Salsich In my experience, the Zener clamp is actually less lossy than RCD snubbers, but of course it depends on the whole circuit.

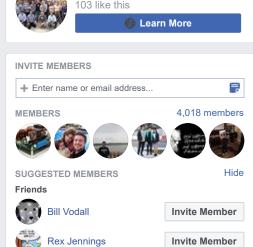
Bahadır Yıldırım, please post a waveform to show the issue. Even better if you can show the waveform before and after the change. IS your problem in simulation, or on a real circuit board?

Like · Reply · 6w



Bahadır Yıldırım Paul Shepherd I did it in practice. Actually I didn't think to take photo of waveform. Sorry for this. This one is nearly similiar to practice by the way.

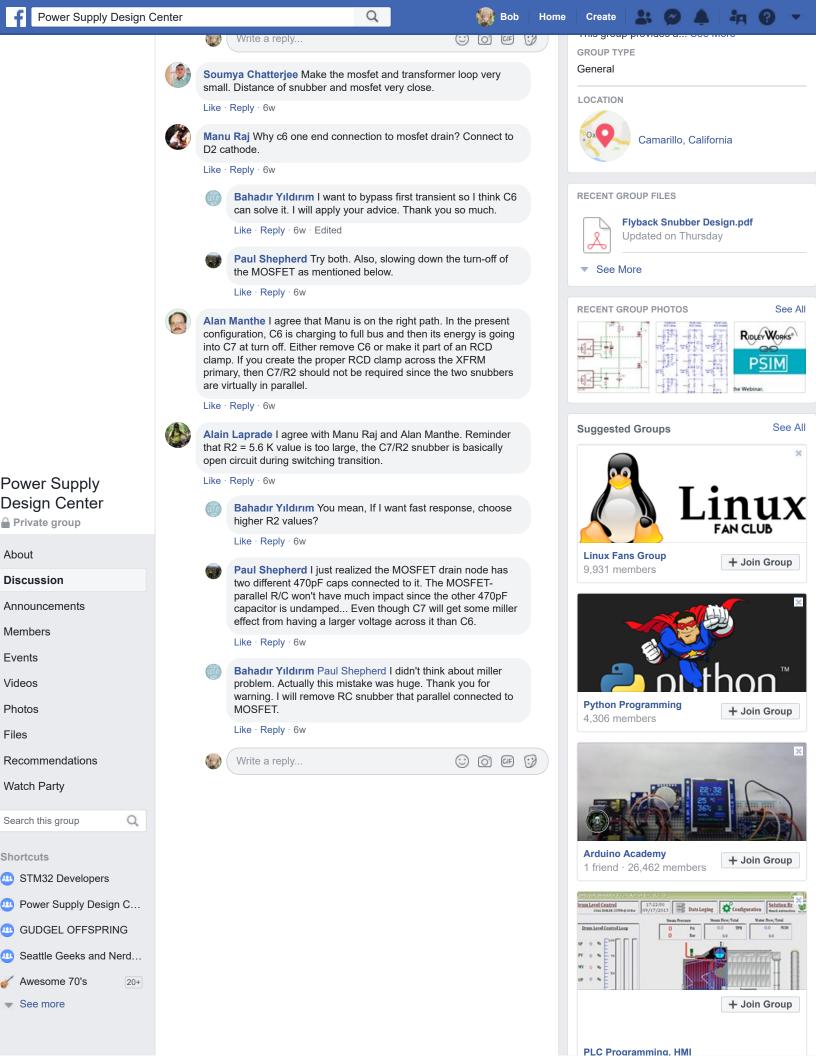




Nicole Eshom-Emmerson

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it switches off. This is because of the very nonlinear gate-to-drain capacitance of the device. At high voltages during the end of turn-off device capacitance nearly disappears. Not only may this be bad for the switching device, but it often causes severe high frequency EMI. What to do?

You can control and linearize the dv/dt by adding a surface mount series RC network physically close as possible between gate and drain of the switching device.

Your existing gate resistor should be between three and ten ohms. Choose the RC network resistor value to be one to three times this value (10 to 33 ohms). Choose the capacitor value to be equal to the drain-gate capacitance value when the device has about fifty volts across it (typically this may be 22pF to 47pF). This RC network will steal drive current and linearize and slow down dv/dt, but only at the end half of the switching transition. It will do so without significantly increasing switching loss if you choose the RC network properly.

The R in the RC network is absolutely required to prevent destructive device oscillations.

Like · Reply · 6w · Edited



Rossano Valsecchi Why don't try to put a 22R in series at the gate?



Bahadır Yıldırım In practice, there are 47 ohm and 10ohm resistor at MOSFET's gate.

Like · Reply · 6w



Alain Laprade Bahadır Yıldırım What?

Like · Reply · 6w



Bahadır Yıldırım Alain Laprade Sorry for my bad English. There are two resistrors which are connected series. First one is 10 ohm which is connected parallel to backward diode ( diode for fast discharging for turn-off). Second one is 47.

Like · Reply · 6w



Write a reply...











Col Johns This is all just a spice model - very different to real world, for example, with the turns ratio shown you get 129V + Vo across the 45V o/p schottky when the fet is on - might work a bit in a sim but in the real world this mistake would quickly show up ... (i.e. bang

Get rid of C6 - and put in an RCD snubber - a snubber on the o/p diode helps too ...

Like · Reply · 6w



Bahadır Yıldırım Yes you are right. I couldn't handle the design as work well. I'm new at power electronics. Trying to get some experience. I will try your advices. Thank you so much.

Like · Reply · 6w



Alain Laprade Bahadır Yıldırım Ah, the wonders of discovery We've all been through it. There was no internet to assist me when I was a newbie. Had to rely on more experienced help in the lab. I recall some liked to keep secrets (and sometimes mislead), very frustrating to work with.

Like · Reply · 6w · Edited



George William Tyler "fast" diodes are often slower to turn on but I doubt that this is your problem. Your snubbers design is suspect.

Like · Reply · 6w · Edited

the output capacitor is too small.

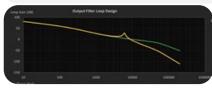
Here is the plot for the filter in the loop out of RidleyWorks (assuming CCM voltage mode, but this doesn't affect the 2nd stage filter)



Like · Reply · 6w



Ray Ridley And here is the current-mode response (or DCM)



Like · Reply · 6w



**Bahadir Yıldırım I** wanted to suppress output ripple. So I used Fcuttof =  $1/(2*pi*(L*C)^0.5)$  filter formula. Formula says If you pick high value capacitor and inductor, you will get low pass filter that has low cut off frequency. I didn't think second stage filter's effects to the primary side. I will recalculate it. Thank you for this detail.

Like · Reply · 6w



Ray Ridley Dahadır Yıldırım read the paper on our design center.

Like · Reply · 6w



David Edwards 5 . Hello Ray Ridley,

After taking a closer look at the schematic it seems that it may be unrealistic in several ways. Besides the questionable output filter values that you noted, the gate drive duty cycle seems that it would lead to very high steady state current that is far beyond the MOSFET's ratings, the transformer leakage inductance is way too high to be practical and the gate series resistance network (not in the schematic, but described in a message) would lead to excessively slow and dissipative switching. If the schematic represents what Bahadir Yıldırım actually is testing, it is not surprising that it fails so easily.

I wonder what the input voltage range requirement is and what the output voltage and current requirements are?

By the way, I commend Bahadır Yıldırım for posting a schematic and making a real effort to describe his problem.

 $\text{Like} \cdot \text{Reply} \cdot 6w \cdot \text{Edited}$ 



Bahadir Yıldırım First of all, thank you for your comments. That can help to find the right way. I want to see circuit's worst state so I set the max value of duty cycle and leakage inductance. Actually I didn't know output stage is disrupting whole harmony in the circuit. I will restudy with your comments and read more for application notes.

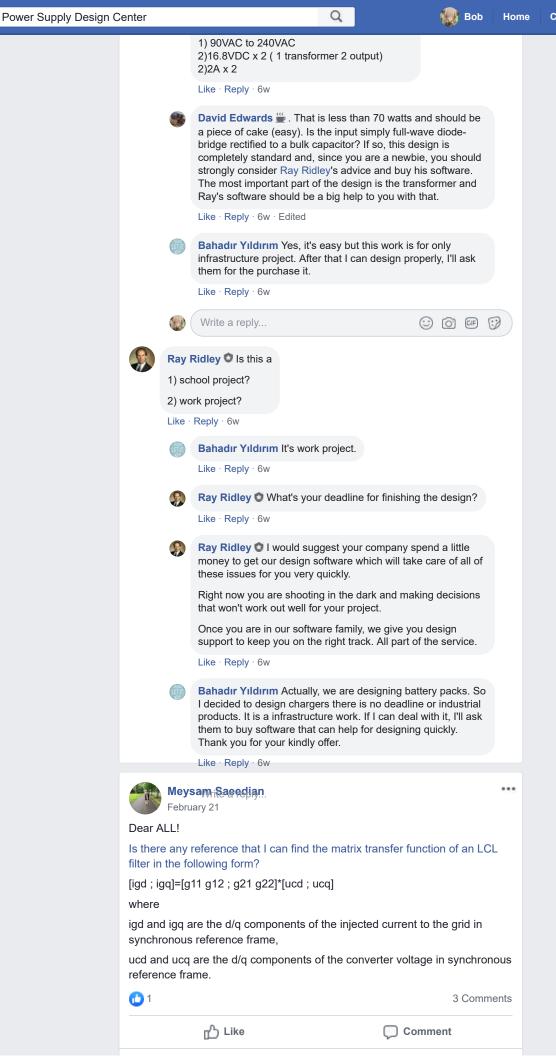
Like · Reply · 6w · Edited



David Edwards . Hello Bahadır Yıldırım,

Please answer the following three questions:

- 1) What is the input voltage range requirement?
- 2) What is the output voltage requirement?
- 3) What is the output current requirement?





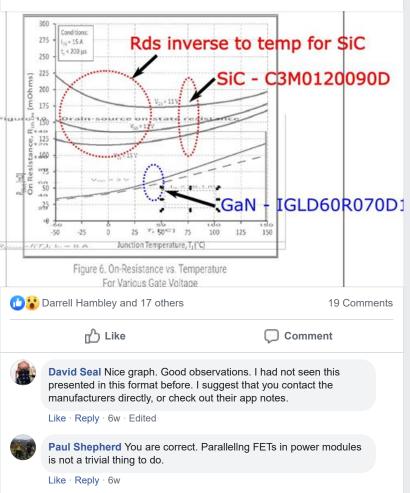
This is something I have never worked on and probably won't get a chance in the pear future but I am year curious about it and want to learn it before I

in the near future but I am very curious about it and want to learn it before I forget about it's importance.

So, in this attached weird looking diagram I took datasheets of a SiC (Cree) and a GaN (Infineon) "RdsON vs Temp" curve and overlaid (and put transparency) them together to match the X (temp axis) and Y (Rds axis) axis (this is why it looks so weird).

The main question I had was --

As temp is in the range (range -50C to 25C), paralleling GaN vs paralleling SiC will behave differently as SiC FET will now have negative thermal coefficient. Are there ready-to-use solutions to design converters which will see both -10C and +30C (like a car driven in Minnesota, and in California) to make sure current sharing is done appropriately ? I can look the solutions up if someone can help me name the "technical terms" I am supposed to look for if there are such terms.



Like · Reply · 6w



Sanchit Mishra That's where I thought about it but they didn't discuss ways to eliminate the issues. The overall ppt was very superficial (but they have to be cos of the time constraint and breadth of topics). My main question here was to find existing solutions that are cold weather designs to alleviate the Rds curve situation (which doesn't seem to exist for GaN switch I chose).

Like · Reply · 6w · Edited



Magnus Rosén No practical problem if correct gate drive voltage. The current sharing at turn on/off parallel WBG devices is a severe problem.

Assuming applications with dominant switch losses, the thermal coefficent value and trajectory is of high interrest...

Like · Reply · 6w · Edited



**Thomas Mathews** I wonder if, for SiC, and after a little warm up time, the operating point would stabilize near the low-point in the Rds graph that appears to be at around 50C? The question would be: if anything bad is going to happen during that warm up? or, during an abrupt turn-on, as there often is.

Like · Reply · 6w



Sanchit Mishra I was thinking along those lines too. The ambient temperature close to the device is what's dictating the temp in the die (junction). So, even for an electric snowmobile after a small usage (or forced warm up where converter dumps all the power without delivery it to load) will bring the operating point of the FET to a nice place like you mentioned. But, I have zero experience with any of the things I just wrote down, and I needed help in determining where to look for.

Like · Reply · 6w



Thomas Mathews Run-away is usually associated with a curve that keeps sloping down. Try contacting your SiC supplier to see if they'll let you talk to their regional SiC FAE or ask your distribution FAE if they know who the supplier's FAE is. This may indeed be stable, but proving it to a design-review full of skeptical peers could be difficult. Of course, you can always build a prototype, test the hell out of it, then later use the up-slope on that curve to explain why it's thermally stable.

Like · Reply · 6w · Edited



**Thomas Mathews** There is probably no closed form proof that the valley will be stable but you could maybe do some simulation or phase-plane diagrams to show that the valley is a stable attractor.

Like · Reply · 6w · Edited



Sanchit Mishra Thomas Mathews Thanks especially for the last comment. That gives me a solid base to begin with.

I'm trying to see if people have plotted their thermo-electrical differential equations and checked for equilibrium points or not. I'll try to find the model in literature (as I think the Rds vs temp is the physics of the heat spreading in the die so there is some thermal model connected to electrical operation/constant heat flux production) and plot the taylor series linearized model as a phase plane.

differential equation. At graduate school I had a class on non-linear control systems and the first thing that the professor said was "Without numerical methods or simulation most non-linear control systems cannot be solved. Many non-linear systems, however, can be shown to be stable if the operating trajectory always tends towards an attractor". The rest of the class, to my disappointment, was about proving stability rather than solving non-linear system equations....which is usually impossible.

Like · Reply · 6w · Edited



Write a reply...











**Col Johns** The curve slopes up at 50 deg C - so runaway unlikely if all on a common heatsink ...

Like · Reply · 6w



**Alex Berestov** Go get the module rated at the current and voltage design requires.

Desire to use cheap discretes and connect a bunch of them in parallel to save money is understandable. But integrated solutions exist for a purpose. Even then some are good and reliable and some are not.

P.S. A while ago I disassembled damaged IPM rated @ 2400A. It consists of 4 HB modules with tens of IGBT chips each. Sure enough they all connected in parallel. Moreover pair of IPMs presents a FB. 4 of the latter were connected in parallel and worked just fine.

That said one can not guarantee equal sharing of current. But it's not the main problem which is sharing during switching transition. Designers of such modules extensively use chip matching by the parameters they would not disclose besides particular layout and heat removal techniques.

Like · Reply · 6w · Edited



Alex Berestov I did not see your affiliation with T company. The latter use discrete IGBTs. Well, vehicle life span is like 100000 miles on average. It's mere 2000 hrs of operation at average speed of 50 mph. It's probably an exaggeration but ballpark number is about right. Most likely thermal cycling would not even kick in. Which is bigger problem than current sharing.

Now compare this to a drive unit of rolling mill operating 24/7. Guess what's employed there.

Like · Reply · 6w



**Dustin Lackey** You might want to note that they recommend driving this SiC device with 15V. At that gate voltage the slope at cold is barely negative. So that combined with the fact that operating at cold you already have lots of margin should alleviate the concern for many applications.

As others mentioned this is all ignoring any possible problems with decreasing threshold voltage with increasing temperature during switching ...

Like · Reply · 6w



**Alex Borisevich** I think it is not very practical to assume that you are going to run it continuously below 30C.

Above 30C devices have a positive slope, so you are fine. It is basically intrinsic negative feedback which prevents thermal runaway (if the devices are on a common heatsink)

Like · Reply · 6w · Edited



**George William Tyler** Another thing to consider is gate threshold match.

Home

Fair to say that only lateral FETs as well as old VDMOS have low enough tempco crossover point for current sharing per say. Bear in mind that SiC MOSFTEs are in reality Baliga pair i.e. cascode. GaN has infinite speed which makes it near impossible to drive. Cheers

 $\text{Like} \cdot \text{Reply} \cdot 6w \cdot \text{Edited}$ 





Nowadays every advanced SMPS controller has frequency jittering feature.

This helps us to reduce EMI filter size and also costs.

New SMPS controllers have lots of features like that:

- HV Startup
- Peak Current Sense Resistor Fault Detection
- Internal Slope Compensation
- Leading-Edge Blanking
- Open Loop Protection
- Green Mode
- Frequency Jittering
- Thermal Protection
- Soft Start

With these features, personally, I don't use UC38xx series for a long time.

So if you want to design Flyback or Forward converter, do you still prefer UC38xx series or new controllers and why?





25 Comments



Like





Col Johns Is this a useful topic ...?

Like · Reply · 6w



Firat Deveci We can share our thoughts about this. Maybe this conversations helps some people to select right controllers.

Like · Reply · 6w



**Col Johns** respectfully - the topic is very very broad - and application specific - usually more focused issues are studied here.

Like · Reply · 6w



Arief Noor Rahman # Mature design procedure...well known IC....and already passed EMI test for many people



application note. Because of all the features, especially protections, it is difficult to go beyond the intended use.

UC3845, L6565 and other oldies are so well known it is easy to use them for multi-kW designs as well as for 50W.

For low power the 'green' issues waiting around the corner so special kind of burst modes are a must. In this case the new controllers are in advantage also because low power is their scope of use.

Like · Reply · 6w



Manu Raj Many QR flyabck controllers with gate voltage clamping are available market with wide operating voltage and internal otp etc. if need to design a power more than 30W. Otherwise UC38xx are more easier to use.

Like · Reply · 6w · Edited



Darrell Hambley More than 30 years ago engineers designing power converters for aircraft tried to use frequency jittering in order to fool the EMI test equipment. Most were successful at fooling the equipment. However, the aircraft system engineers started noticing, and pilots started complaining. Systems issues, like a "ghost" signal on the radar screen would jitter back and forth.

The purpose of "meeting EMI" is not to show a nice plot which is below a limit line on a print out. The purpose of meeting EMI is to filter out noise so that is does not distort other systems.

Like · Reply · 6w



Arief Noor Rahman Thats what i thought about jittering, its just fooling the FFT math, but doesnt necessarily reduce the actual noise

Like · Reply · 6w



Dave Lafferty Darrell Hambley, they are also a nightmare for an AM or FM radio system.

Like · Reply · 6w



Ram Mohan This is similar to what Volkswagen did with their **ECU** 

Like · Reply · 6w



Write a reply...









Stuart Wood For those working in the Areospace industry were we have to use hirel parts we don't get much choice....

Like · Reply · 6w



Chris Merren Sometime in 2000 I designed an IC that uses Spread Spectrum on the clock frequency... It doesn't fool the FFT, it actually lowers the amplitude of the EMI to help meet

requirements...however it increases the bandwidth of the noise... The IC was abandoned..however some of my colleagues moved on to another company and released a similar controller... You can do this with most any SMPS controller, if you have an external clock pin...

Like · Reply · 6w

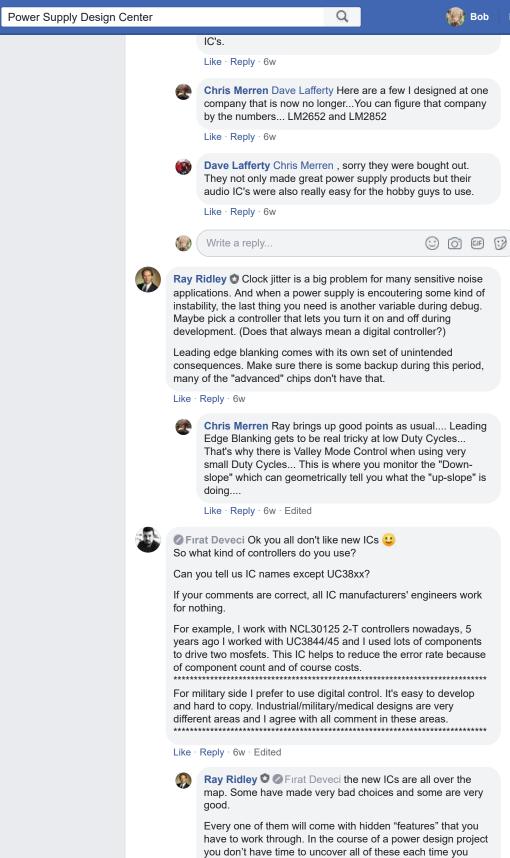


Dave Lafferty Chris Merren, I have tried that but one caution. If the IC has a R/C free running clock it needs to be lower than the min frequency of the spread spectrum.

Like · Reply · 6w



Chris Merren Dave Lafferty On some of the IC's I designed, there is an external clock pin...this feeds into a PLL that will over-ride the internal clock.... As long as the external clock frequency stays ABOVE the internal clock frequency your good...



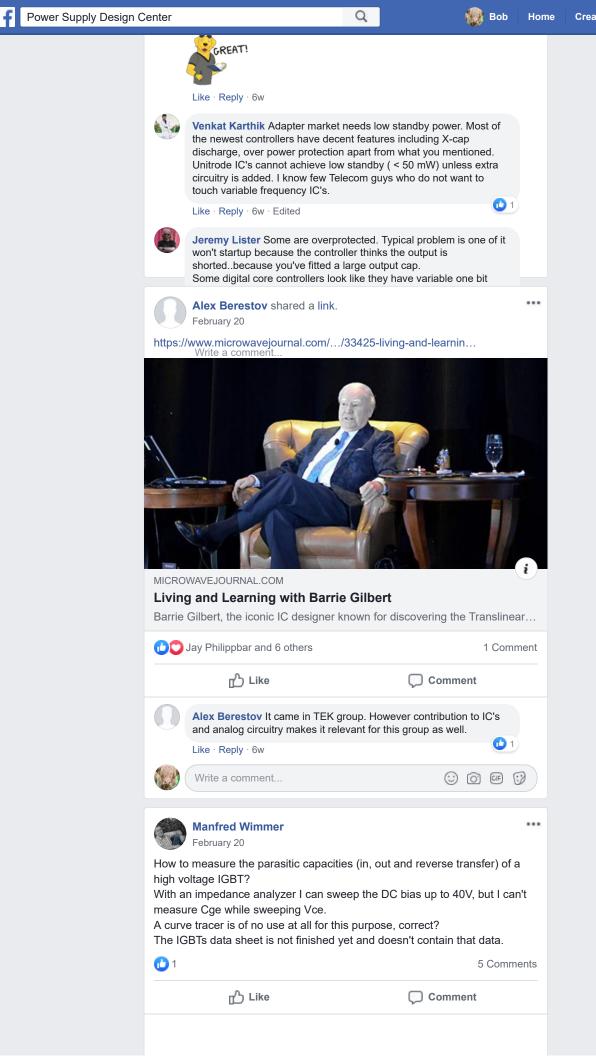
change part type. Hence experienced engineers stick with what they know well.

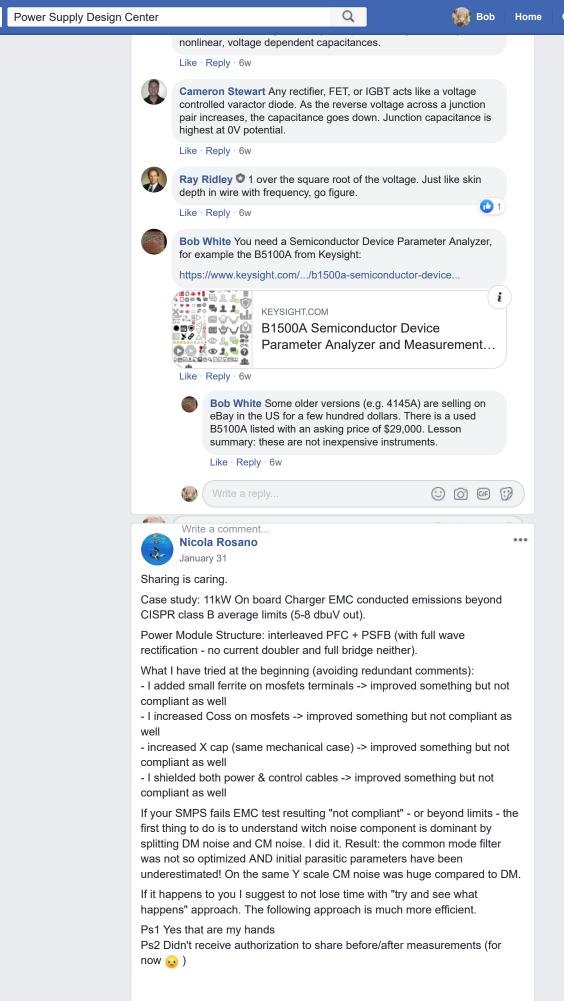
There are so many to choose from now I don't know how they make money from them!

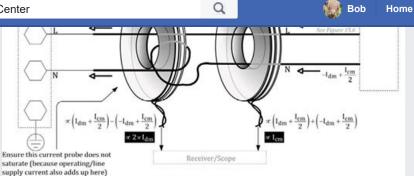
Like · Reply · 6w

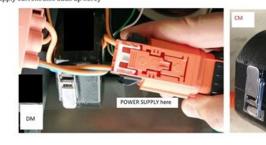


Col Johns For a (typical) resonant power converter the operating freq is always moving and so provides some spectrum spread on its own - you cannot mess with this for increased freg jitter. Simple PWM control - you can - and possibly some PSFB.











You and 40 others

16 Comments



Like



Comment



Luca Di Carlo You didn't solve the root cause of your noise, you just shoot it with a cannon. Anyway the approach you used is absolutely right! Congrats

Like · Reply · 9w · Edited



Nicola Rosano Luca Di Carlo agree. But when the time is running out doesn't matter

Like · Reply · 9w · Edited



Paul Shepherd I agree you have to split CM and DM before you try to solve the problem! If you k ow someone buying LISNs, make sure they invest in one that can separate the two.

Like · Reply · 9w



Venkat Karthik Any specific reason totempole or semi bridgeless topology was not used? I have read they are bad in terms of EMI but improve efficiency in terms of bridge rectifier.

Like · Reply · 9w



Charlie Elliott Wenkat Karthik You probably just answered your own question!

Like · Reply · 9w



Chee How Can consider something in between like dual Boost Bridgeless PFC: No switching node connection to AC line as normal bridgeless PFC, sort of interleaving, but one rectifier diode loss and higher component count

Like · Reply · 8w

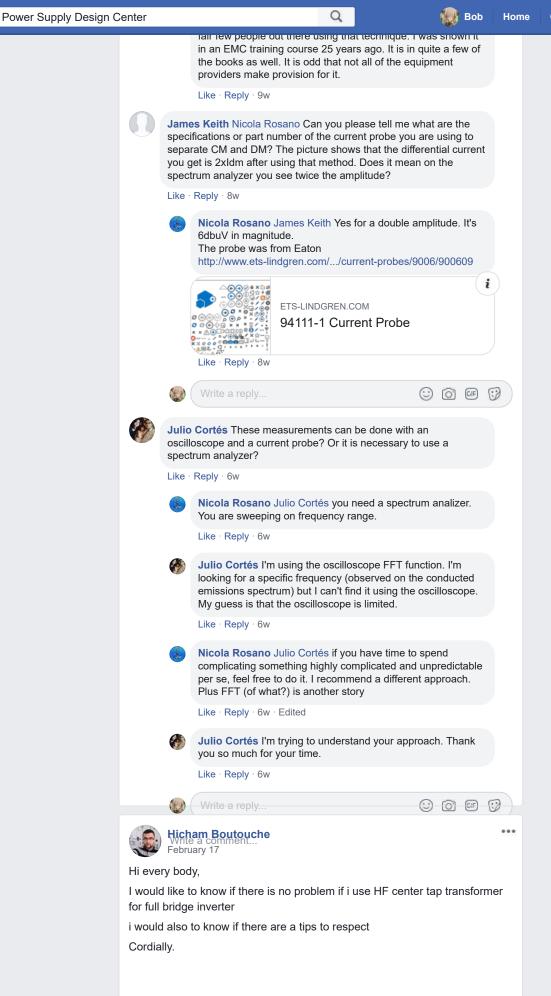


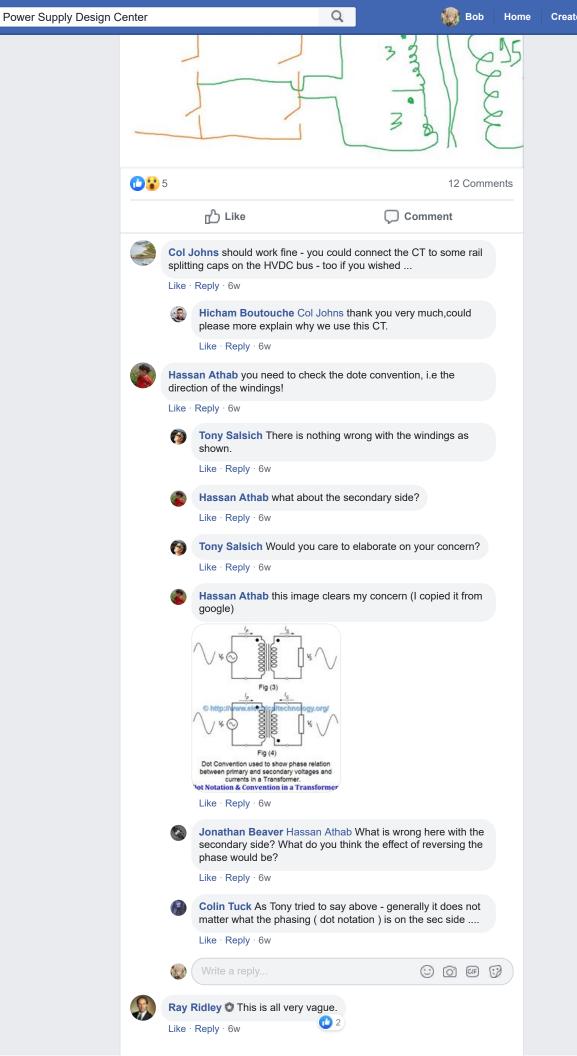
Cameron Stewart When in doubt: Install a faraday shield between primary and secondary of your main power transformer to supress common mode noise. Ground it on the primary side.

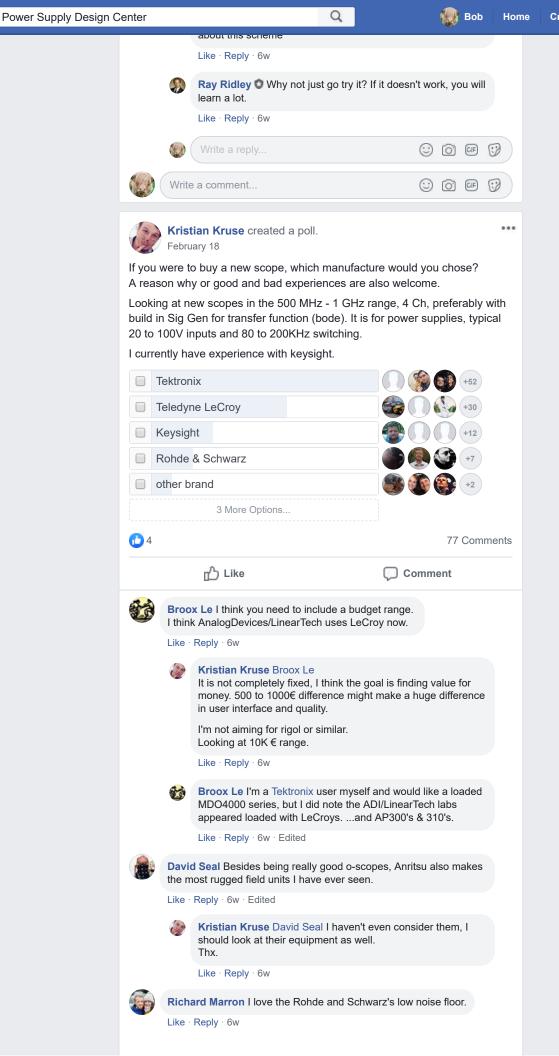
Like · Reply · 9w · Edited



Ray Mayer Finally, somebody using the RF splitter technique I've tried to convince people to use! Without it, how does one fix a noise problem when one doesn't know what type of noise it is?







buttons will be coming to an end in the foreseeable future. ......

Announcement will be at APEC.

One question for you - do you really need 500 MHz for a 200 kHz switcher? You pay a lot for the extra bandwidth, and the first thing many power supply designers do is switch on the bandwidth limit so they can get rid of the switching hash and actually get some work done!

Performance of the Bode features of these scope is of great interest to us, obviously. We have been looking at it for quite some time now. There are gotchas to watch out for......some of them are pretty useless. Still testing....

Like · Reply · 6w



**Jonathan Beaver** I'm going to be keeping an eye on that with great interest.

Personally, the advice I have given recently to a couple of companies that appear to be heavily investing in software based scopes is to keep equal capability around with hardware based units for troubleshooting purposes. This may be personal bias, but from watching other engineers use both types of units (so it's not a lack of familiarity with the interface), there seems to be a noticeable amount of friction to changing timebase/trigger/position settings on the fly with most of the software scopes I've seen, which slows down the 'hmmm, I wonder if that looks correct' loop that I seem to go through when troubleshooting something from scratch. That may be more of a systems or embedded hardware engineering perspective, however.

On the other hand, for the ability to easily save/review captures, save capture and probe settings and do other indepth analysis, it's certainly hard to argue with a software based unit.

Like · Reply · 6w



Ray Ridley Jonathan Beaver thanks for the comments. We have all kinds of scopes in the lab. It is culturally very difficult for people to switch formats I understand that.

It's a challenging time for scope makers that is for sure!

Like · Reply · 6w



**Kristian Kruse** Ray I might be old fashioned, but I like my buttons for horizontal and vertical scale, and I prefer one for each channel.

As for bode features, I only know the one from keysight. I agree, it definitely could improve. It is hard to beat the antique 4195a.

The 500MHz might not be required for most, but it will also allow for new and faster designs.

I rarely use the internal BW limit, as I don't know the exact behaviour. I use passive external ones.

Like · Reply · 6w

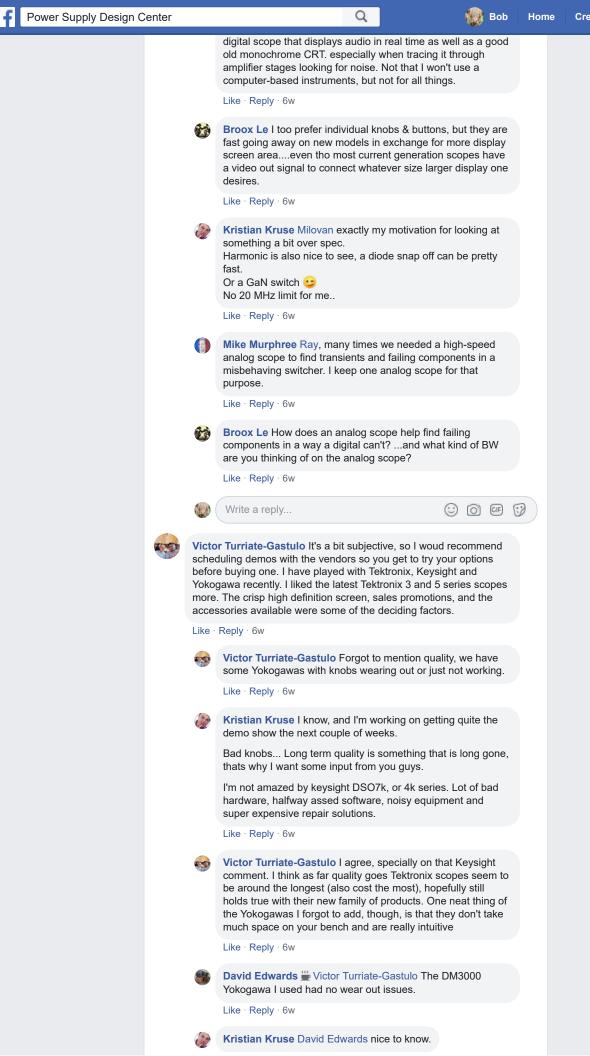


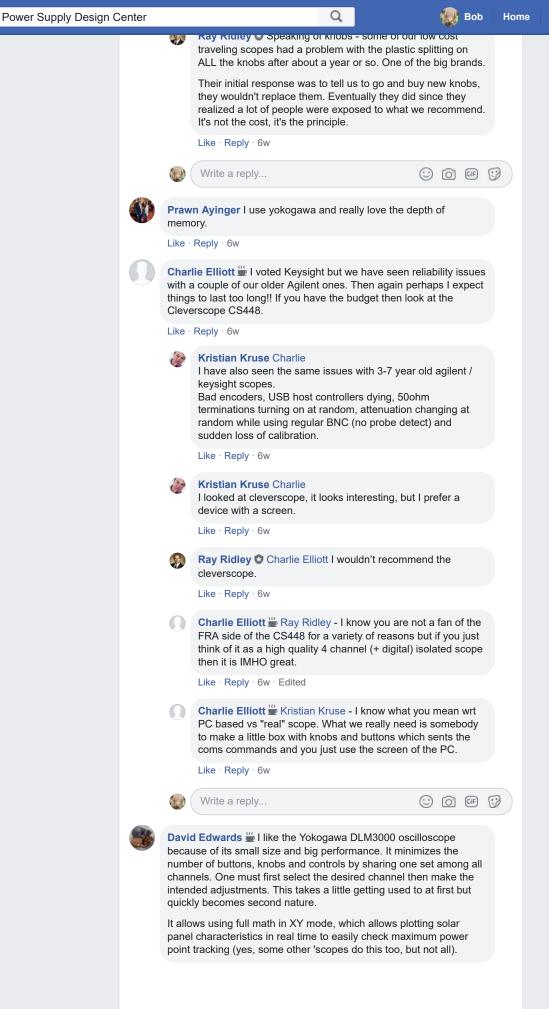
Ray Ridley Kristian Kruse that's pretty old school! The digital filters are pretty amazing for cleanup but you are right, you can't be sure how they work.

Like · Reply · 6w



Milovan Kovacevic 200kHz switcher may actually be 500kHz or 1MHz switcher in a couple of years. Also, dv/dt is not completely independent of the switching frequency, but you know - it kinda is. In addition, signal electronics on the board can totally run at 100+ MHz, and you want to see some harmonics. Depending on what you do, from none to all of these reasons apply to you.





Q



Like · Reply · 6w · Edited



David Seal Nice display resolution, too.

Like · Reply · 6w



Alex Berestov The very option useful in PSU debugging is isolated channels. I've checked LeCroy, Fluke, Schwarz on that regard. Bleak in comparison to Tek. That's said TPS2024 I'm referring to has short memory and mere 8bits without HiRes option. However ability to see control and output simultaneously without AC coupling the two is priceless, for everything else....

If money is not an option there is high end 12 bit TEK, 9 enob, with optically coupled probes @ 500 and 1000 MHz

Moreover you may consider Enertronics GmbH wireless floating wi-fi scope if it still exists.

Like · Reply · 6w



**Kristian Kruse** Alex I think the Tek 9 is a fair bit out of budget, without knowing the exact price. But it sounds nice (and expensive).

Like · Reply · 6w



David Edwards . Hello Alex Berestov,

Tek's new optically isolated probes are truly amazing and unique among such instruments. When properly set up their common mode rejection is unparalleled. However, they cost the Earth. Maybe when competition kicks in the price will come down.



Like · Reply · 6w



Ray Ridley David Edwards looks like something from Star Wars.

Like · Reply · 6w



David Edwards . Hello Ray Ridley,

Here are some of the features and benefits this \$26k measurement system:

Bandwidth from DC to 1 GHz

160 dB Common Mode Rejection from DC up to 1 MHz

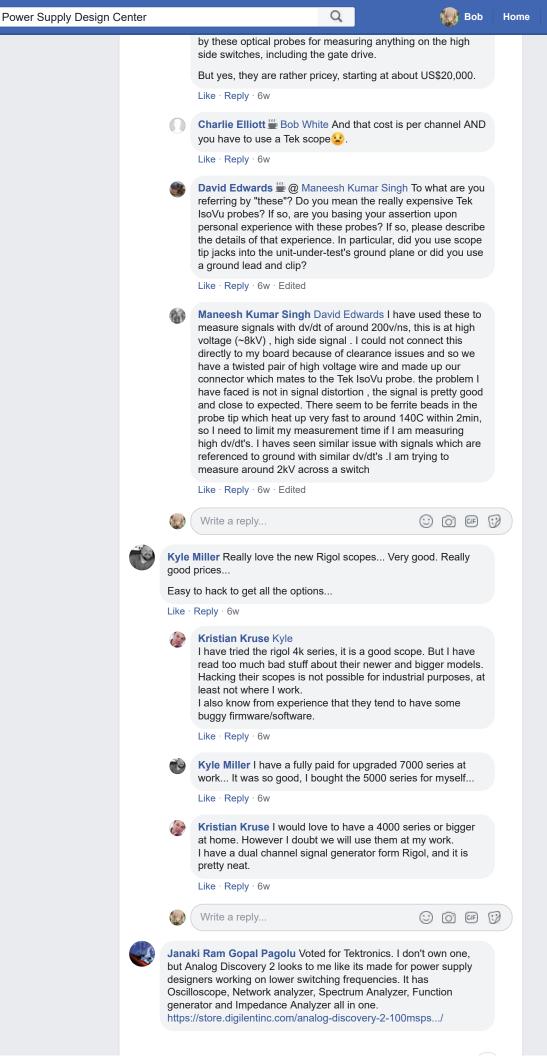
. 80 dB Common Mode Rejection at 1 GHz

. 60 kV peak Common Mode Voltage

Cable length of 3 or 10 meters (identical performance) Maximum input amplitude of either +/-50V or +/-2500V (depending on the test head)

The cable has five fiber optic lines (one for power). The tripod serves to minimize stray capacitance to maximize common mode performance. Full performance requires a scope tip jack into the unit under test's ground plane.

Like · Reply · 6w · Edited



















Analog Discovery 2: 100MS/s USB Oscilloscope, Logic Analyzer and...

Like · Reply · 6w · Edited



## Kristian Kruse Janaki

It is an interesting device, but in my opinion only for educational and hobby purpose.

It will not work for our line of business, and I wouldn't like to show this kind of equipment if we had customers visit..

Do not get me wrong, it is a neat instrument, and I have considered it as part of my private lab.

Like · Reply · 6w





Janaki Ram Gopal Pagolu I agree what you said, it's more for a hobbiest than for a professional. But imagine a top tier company releasing a single product with all those features with added reliability and ruggedness.

Like · Reply · 6w



Ray Ridley We have this in the lab too. Strictly for students and people with time on their hands.

Like · Reply · 6w





Broox Le I was thinking something along that line. What do you think of the more professional 'tools that use a laptop for control' like the PicoScope series?

Like · Reply · 6w



Kristian Kruse I have made a few test of the FRA (frequency analysis) function of a few Keysight scopes, and I will soon have the possibility to compare with Rohde & Schwarz.

I did some conducted sucebtibility (PSRR) measurements with a HP4195A to get a baseline of a dual output DC/DC.

I then tested keysight 1k series, 4k series and 6k series.

Generally the noise floor of the scopes is around -80 to -90 dB from 100 Hz to 100 KHz.

The scopes had a deviation from the HP4195A which was generally less than 1 dB @ 63dB.

The injection level was 1Vrms.

I will add some more measurements to the log once I have my hands on R&S, then I will share some actual measurements.

Like · Reply · 6w

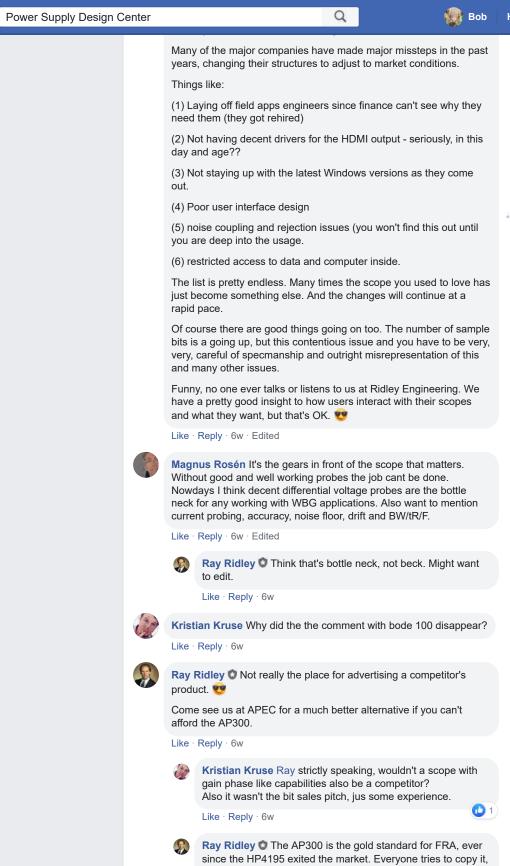


Mark Reinders I like Rigol for the value. Great features. Also have high end Agilent for high speed digital work such as SPI and I2C

Like · Reply · 6w

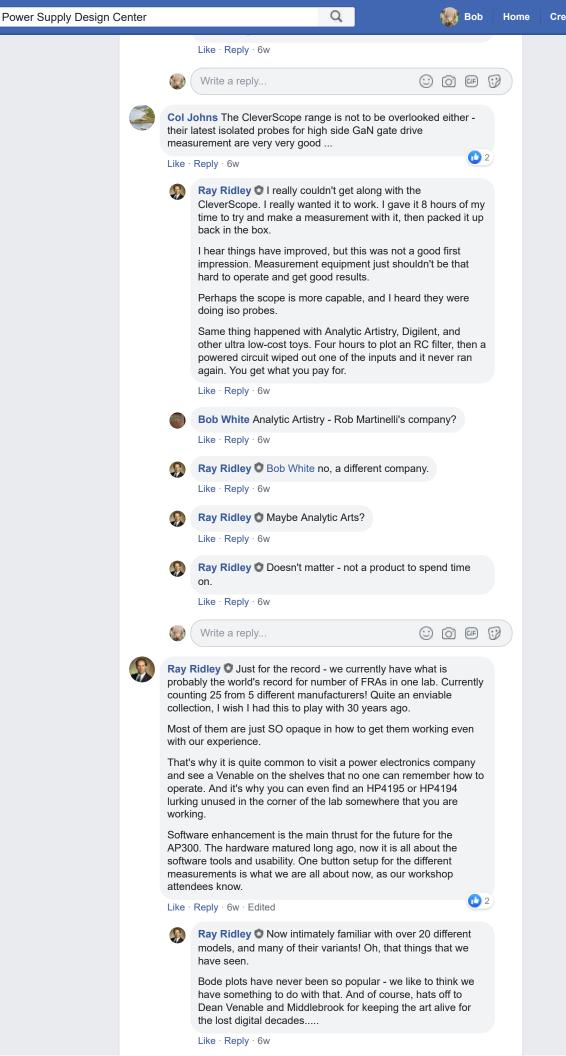


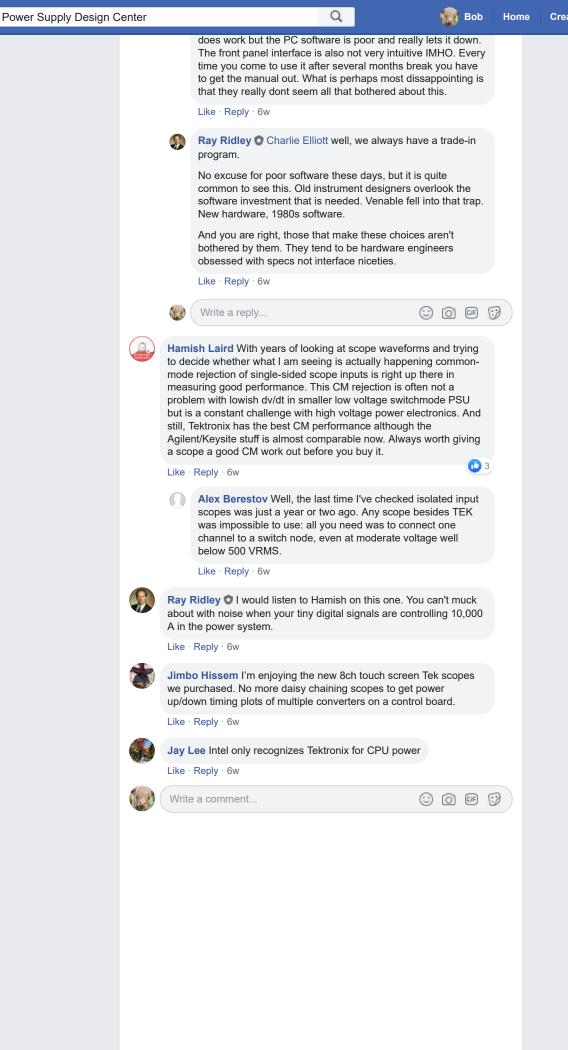
Bruno Torremans Tektronix MDO4000 and PicoScope 5000 series



Like · Reply · 6w · Edited

but a scope can never offer the dynamic range, channel separation, noise rejection, and calibration/certification capabilities of the AP products. The hardware architecture is just different. We are not worried about the scopes coming into our space, if anything our sales have gone up since they have raised awareness in the marketplace. If I were the maker of the 100, I would be very worried about them. At least when the scope can't do everything you wanted it to, you still have a scope for your money.



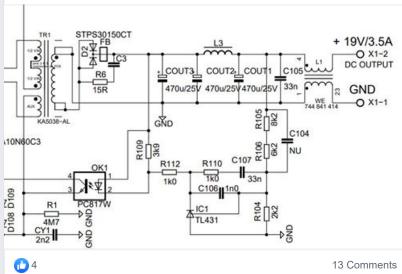




In the attached flyback design, the output common mode choke is rated for 4 Amps. CM choke only sees common mode noise currents and not the differential current ( atleast when placed on the input AC line.) What about on the DC side. Should it be rated for DC current? Can anyone please advise? The attached screenshot is from On semiconductor's schematic page.

Q

Part number: https://www.digikey.com/product-detail/en/w-rthelektronik/744841414/732-1459-ND/1638864

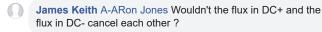






A-ARon Jones How does the choke not see differential input current? Seems to violate KCL

Like · Reply · 6w



Like · Reply · 6w

Like



A-ARon Jones James Keith I believe we are talking about the difference between rated current and saturation current. From a flux and impedance perspective yes, but the power rating is differential.

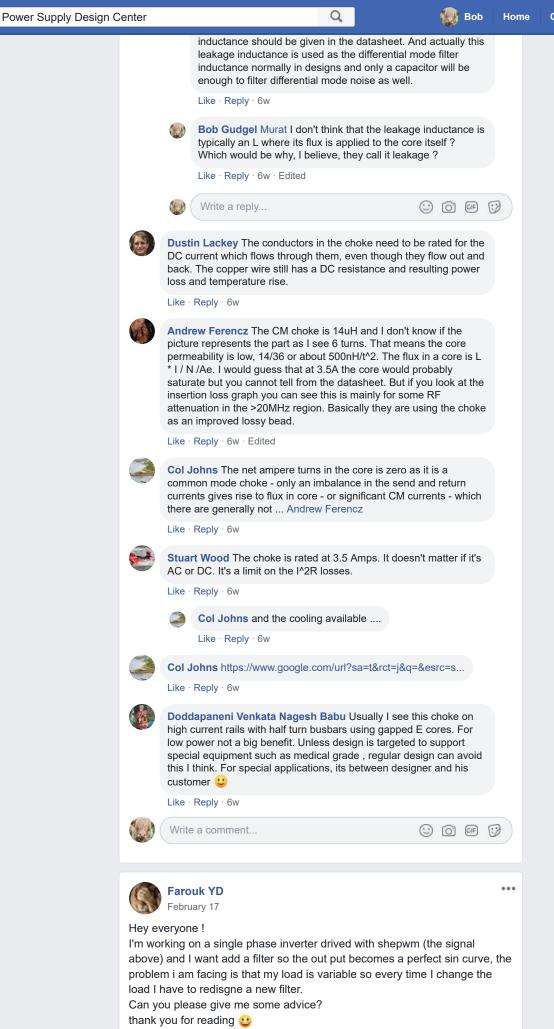
Like · Reply · 6w · Edited



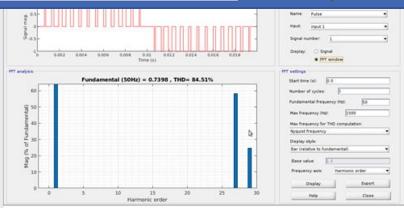
Comment

Charlie Landino A-ARon Jones The flux in the core is in opposite directions and cancels in the CM choke. The ohmic loss is the same, though - KCL not violated!





Home



Q

🚹 You, Jay Philippbar and 6 others

18 Comments







Paul Shepherd If I understand your question correctly, you need the output impedance of the filter to be much lower than your load, or you need a faster current control loop.

Like · Reply · 6w



John MacLeod For normal load range, only voltage control should be in play, so no effect from current control loop. The filter needs to be LC low-pass, with cut-off between modulating frequency and switching frequency but avoiding odd harmonics of mod frequency. Device deadtime injects odd harmonics of the modulating waveform so you don't want any of those hitting the resonant frequency of the filter.

Like · Reply · 6w · Edited



John MacLeod ...once you're in current limit, you don't really care about waveshape being sinusoidal any more.

Like · Reply · 6w



Cameron Stewart This is what corrective feedback and gain phase plots are for.

The corner frequency on an inverter output filter will always change with loading. So you have to plot the gain and phase at the loading extremes, then design the best combination of output filter and loop compensation to work in your application.

I don't recommend running your inverter open loop unless load regulation and distortion are not an issue.

If you are doing pure digital control you have another layer of complexity to deal with: The power output filter is in the 'S' domain and the digital control loop is in the 'Z' domain.

Like · Reply · 6w



Hide 12 Replies



Farouk YD Cameron Stewart hey thanks for your reply, have you any references doc article book about it ?!

Like · Reply · 6w



## Cameron Stewart Farouk YD

Most of what I know about inverters I learned through a combination of time and frequency domain simulation with LT Spice and working with hardware in the lab.

Dr Ridley offers training courses, books, and on-line papers on the subject. He also offers analyzer equipment and software for bode plotting.

Dr Hamish Laird teaches digital control loop principles.

It sounds like you are new to this and just starting out.

wondering is it impossible to do it on a open loop system?

Like · Reply · 6w



**Cameron Stewart** You need to define your specification goals first:

- 1) Nominal output voltage
- 2) Output frequency
- 3) Maximum output power
- 4) Load power factor, min/max, leading / lagging.
- 5) Load regulation, min/max from nominal output voltage.
- 6) Maximum distortion.
- 7) Target switching frequency.
- 8) Minimum efficiency.
- 9) Proposed power switching devices: IGBT's vs Silicon Carbide vs ?
- 10) Input DC rail voltages

Until now you haven't provided any detailed specifications or a starting schematic. So the question is too vague to answer properly.

Like · Reply · 6w



## Farouk YD Cameron Stewart

Vout = 230v

f = 50hz

S = 2kva

THD < 5%

And I'm using mosfet.
But I don't know the load it's an ups so load is totally unknown

Like · Reply · 6w



**Cameron Stewart** If you are using mosfets, how will you handle reverse recovery of the mosfet internal body diodes in your totem pole bridge?

During the pwm dead time, the main output inductor voltage will fly into the body diode, opposite the mosfet that just turned off. That body diode must then go through a reverse recovery, typically when that second mosfet turns off and the original mosfet turns back on.

The body diode reverse recovery problem is serious enough on pwm inverters that most applications end up using IGBT's for the application.

The IGBT's in turn limit the switching frequency due to storage time issues during turn-off.

Adding anti-paralleling diode networks with conventional mosfets ends up being too space intensive to package easily.

But there are other alternatives, such as Silicon Carbide mosfets are Gallium Nitride devices. Each has it's design trade-offs as well.

So again, what is your proposed switching frequency?

Like · Reply · 6w · Edited



**Farouk YD** Cameron Stewart Aagh I forgot about it thank you, For the switching frequency it's 1,3kHz

Like · Reply · 6w

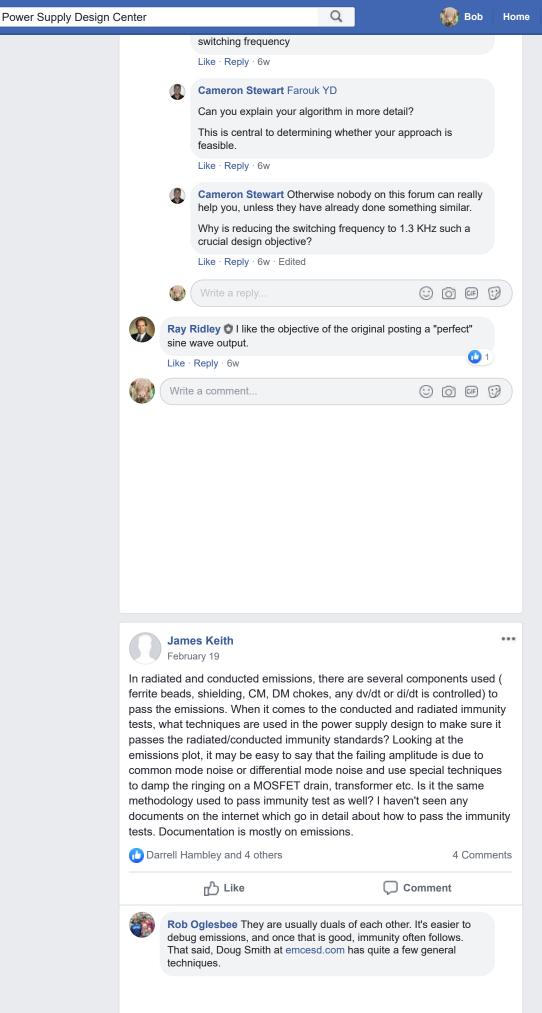


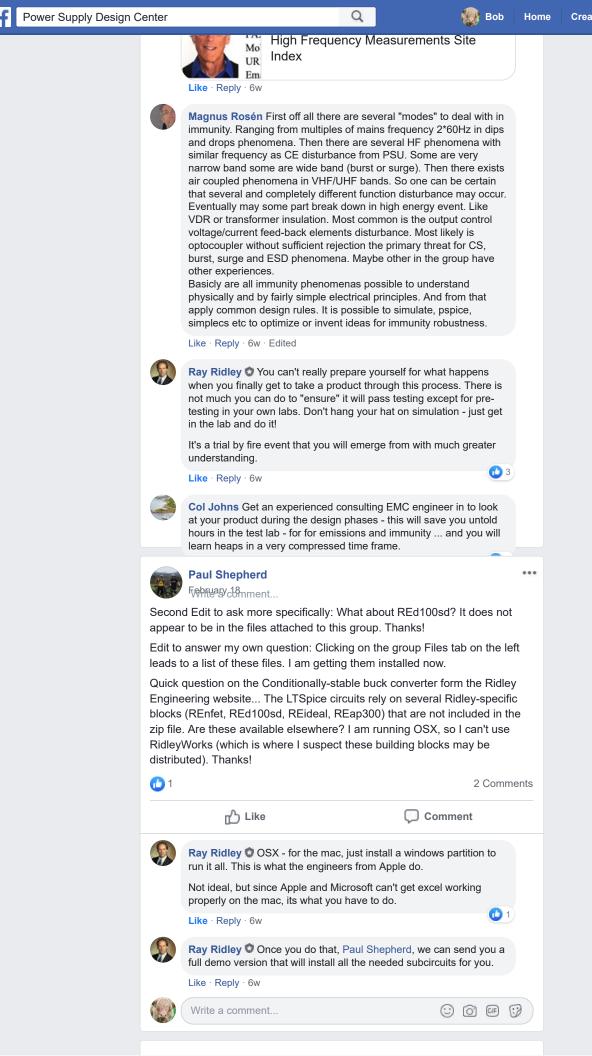
Cameron Stewart I'm sorry: Is that 13 KHz or 1.3 KHz?

Like · Reply · 6w



**Cameron Stewart** 1.3 KHz is too low a switching frequency for 50 Hz. The switching frequency should be at least 100 times the AC output frequency.



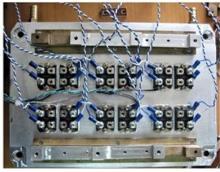


This is my first project from 2011 for private company: 48V 300A BLDC Motor Driver with water cooling.

Mechanical placement is very important if you want to decrease the leakage inductance. Nowadays I don't design motor drives (personally, not prefer to design) maybe it will help designers who curious about. This is mosfet voltage measurements at full power.







firatdeveci.com

You and 12 others

17 Comments







Colin Tuck What mosfets are you using ...?

Like · Reply · 6w



Fırat Deveci IXFN230N20T

Like · Reply · 6w



John MacLeod Is that a bit of a lift in Vds prior to turn-off?

Like · Reply · 6w



Firat Deveci This is Turn off signal.

Like · Reply · 6w



Petrica Barbieru Seem slowly first phase of turn-off... losses are normal?!

Like · Reply · 6w



Firat Deveci Those days, I'm using 300mA (yes, sad but true) mosfet driver to drive 2 parallel mosfets. It isn't normal of

But nowadays I'm using 20Apeak gate drivers 🙂

Like · Reply · 6w · Edited



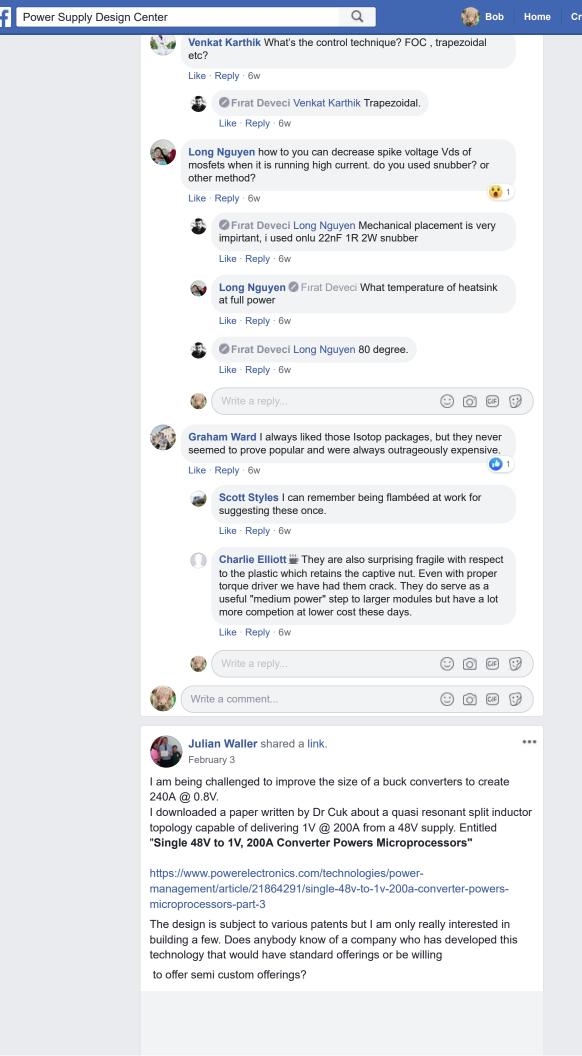
Petrica Barbieru Pirat Deveci BLDC motor use in encoder loop control system or sensorless? In sensorless may have sensing problems with so low Vds overshoot.

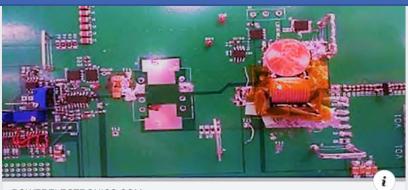
Like · Reply · 6w



Fırat Deveci Sonsored control

Like · Reply · 6w





Q

POWERELECTRONICS.COM

## Single 48V to 1V, 200A Converter Powers Microprocessors (Part 3)



📆 💟 You and 6 others

33 Comments





Comment



Col Johns That is a great challenge - only 192 watts but 240A continuous - presumably multi phase? Can you share some of the regulation specs? i.e. 90 - 5% load change Vout must be within ...? 5% to 90% load step - Vout must be within ...?

Like · Reply · 8w



Julian Waller +/-3% voltage, still figuring out the transient. Multi phase solution with LTM4700. The above technology seems to be the only challenger to get the size down.

Like · Reply · 8w



Col Johns Having studied the ckt a little - no doubt it could get the size down - but a fair bit of engineering effort to get one working well - controlling load steps my well require non linear control techniques

Like · Reply · 8w



Julian Waller I see it for what it is just hoping to leverage off someone else who has done it. I don't have time for a full blown development although I would certainly be up for the challenge.

Like · Reply · 8w



Ray Ridley Look at Vicor's products.

There is a huge amount of work to move a breadboard like that shown to a working product. Many are trying multiple approaches to it, and have invested huge resources. I don't know what "building a few" really means, but there is no short cut to it all.

Like · Reply · 8w



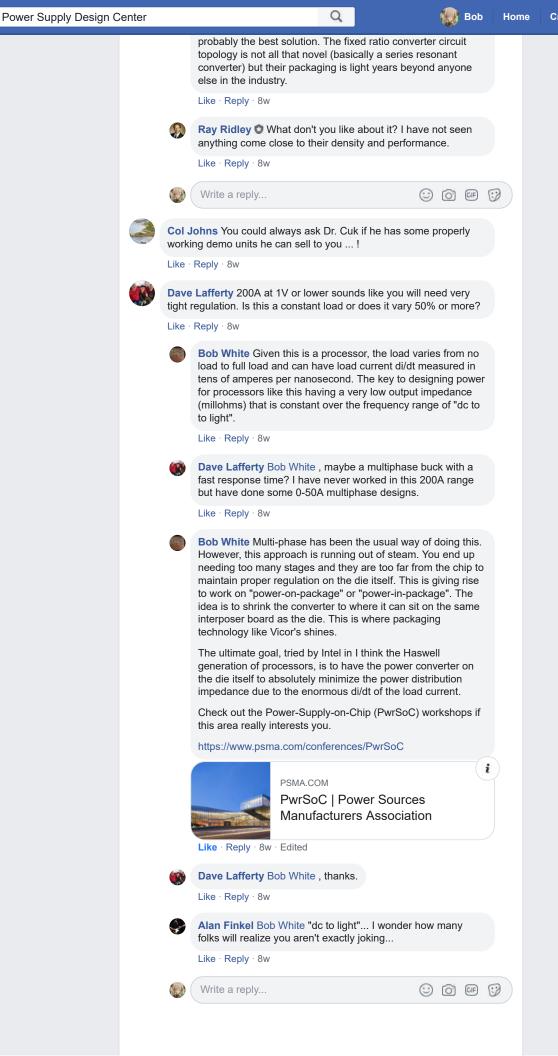
Julian Waller I hope to buy one from someone has gone through the pain barrier already and has some commercial offerings. At this stage I would probably be looking at about 10 pc.

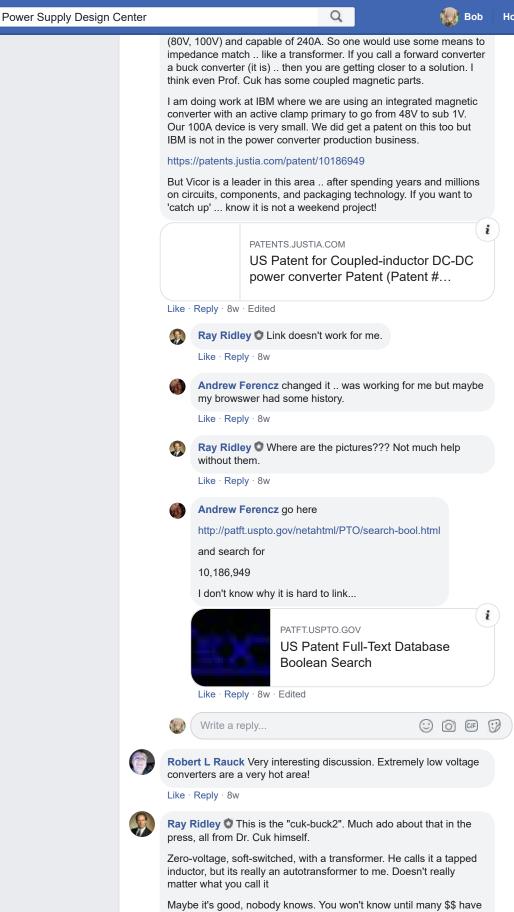
Like · Reply · 8w



Julian Waller I am familiar with Vicor's wares particularly their new bus converters which are pretty cool if you are prepared to design mechanical heatsinks to extract heat from both sides of the package. I can look again however with ore focused questions.

Like · Reply · 8w

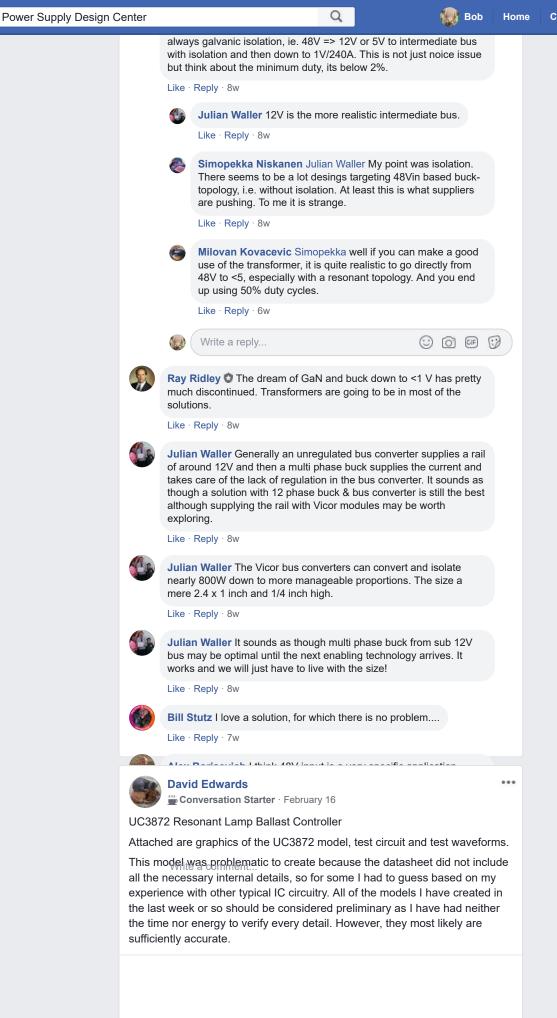


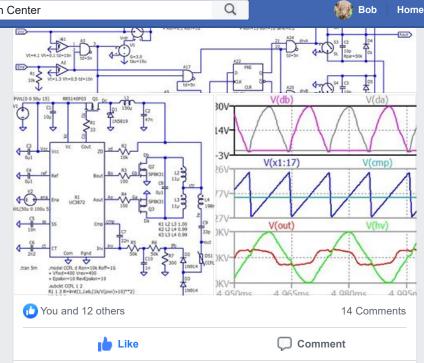


Maybe it's good, nobody knows. You won't know until many \$\$ have been invested in trying it out properly. And then, it is a packaging exercise and you will be 20 years behind Vicor.

We are all waiting to see if anyone takes this further, but there are 20 different ways to get there that people are exploring.

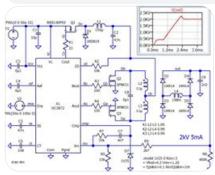
Like · Reply · 8w







David Edwards # Here is the UC3872 reconfigured as a voltage regulator. It needs a TL431 on the Comp pin to limit windup and control voltage overshoot.



Like · Reply · 6w



Clive Harvey What would you say is the advantages using this approach compared too the more simple flyback?

I assume it will have the same high voltage issues in the transformer.

Like · Reply · 6w



David Edwards . Hello Clive Harvey,

This controller is fairly old (20+ years) and expensive (\$3.63 each for a 2k reel). It's future lifetime depends on its market. CCFLs may not be on the way out, but they are receiving serious competition from

Soft start must be set to be very long (a good fraction of a second) or anti-windup measures for the error amplifier must be implemented to prevent large overshoot.

If used to generate a voltage output, one may need to add short circuit protection (not sure - needs looking into).

On the plus side it is set up to detect zero crossing, which is key for a reliable resonant sinewave topology. If it looks interesting enough, you should perform extensive simulations and/or experiments with it and decide for yourself.

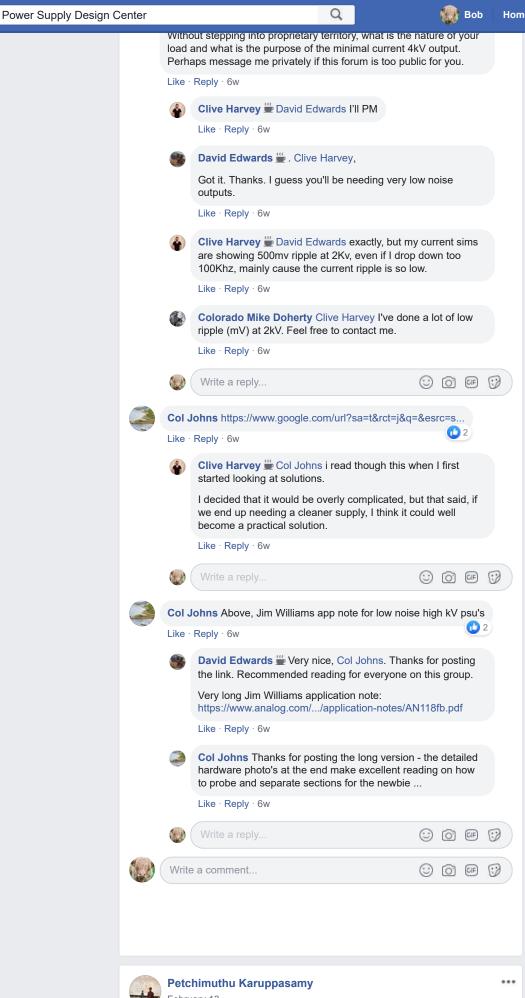
Like · Reply · 6w



Clive Harvey David Edwards for my current automotive application I don't think it seems practical.

But for personal interest, I definitely want to learn more about resonate topologies.

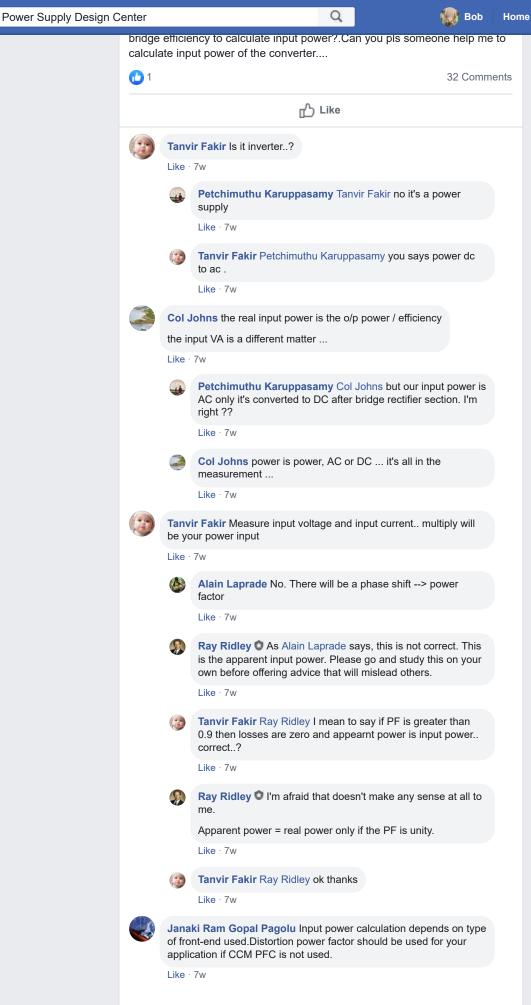
Like · Reply · 6w





Hello everyone...

My flyback converter output is 46W. I need to calculate the input power of







'power' that matters is the DC current. If your source is AC, the only 'power' that matters is the in-phase AC component. If your source is AC and you have current that is out of phase or contains harmonic frequencys, you have a power factor less than 1 and you need to do lots of measurements and math to compute it. Some oscilloscopes with voltage/current proves can do a reasonable job too.

Like · 7w · Edited



Ray Ridley There are fundamental misunderstandings about this field in your question.

Input power is output power + losses in the circuit. Very simple.

Power factor is included if you want to know the apparent input power. That is different. Please go and study by yourself the meaning of real power and apparent power.

Also in your question, are you trying to calculate the input power from measurements, or by theory alone? it is not clear what you are trying to do.

Like · 7w



Tanvir Fakir Ray Ridley yes ..lossses may be in term of mA..and if your converter has good pfc then nothing losses

Like · 7w



Ray Ridley Good heavens......Losses are in Watts, not

Please - be careful with your terminology.

Like · 7w



Graham Ward Tanvir Fakir I'll also add that you can have perfect (unity) PFC but I guarantee you will still have some losses. Optimum PFC merely means you have minimized or ideally eliminated reactive power (losses) in your power supply, however you are still drawing real power to (A) support your load and (B) compensate for losses in the power supply itself. When your switching transistor/s, bridge rectifier, transformer and output rectifier heats up, those losses have to come from somewhere, and they do: your input supply.

Like · 7w



Oliver Sedlacek If you've built it, why don't you measure it. If you've simulated, what does the simulation say?

Like · 7w



Colin Tuck A ball park eff would be 80% therefore input power is in the ball park of 57.5 watts - of course the input VA will be higher than this as the typ PF of rectified mains with cap filter is 0.6 - 0.65, so the input VA will be in the order of 88.5, @ 230Vac rms the mains current will be 88.5 / 230 = 385mA ...

Like · 7w



David Seal Start with the bridge rectifier: on the input side, if there is a bridge rectifier, the "power factor" seen by the AC input is unity, or "1", by definition. The "power efficiency" is different: that is the total input power, minus the major losses from the forward voltage drop of the diodes in the bridge, times 2, and several other minor losses as well. This is usually expressed as a percentage.

Like · 7w · Edited



Col Johns Dear David Seal - unfortunately a bridge rectifier does not guarantee unity power factor as you seem to imply above, it does not shape the input current to be the same shape as the voltage - which is what is required for UPF - the cap input B rectifier generally draws high peaks of current near the mains voltage peak

Like · 7w · Edited



power factor. The diodes only conduct when the voltage on the load side is exceeded by the input voltage, and only during the central portion of each sine wave ceasing as the input voltage falls below the load. This is phase-matching, and the lowest harmonic distortion point. There may be specific exceptions, yes, but as a general rule, this action holds true.

Like · 6w



**Col Johns** Respectfully, David Seal, matching the phase of the fundamental is only part of the issue - do a quick Spice of a cap input filter with load and then compare the current to a BRect with resistive load only - the difference is the harmonics - 0.65 PF vs 1.0 ....

Like · 6w



Ray Ridley So how does everyone feel about these posts?

On the one hand, you can feel good about knowing all the fundamentals of power. On the other, it is pretty scary that offline power is being designed with such a lack of the basics.

managers that assign these jobs probably can't tell the difference, but the measurements will certainly know.

I like to help newcomers, as do many of you, but when power is expressed in mA, it is quite alarming. Not just a language barrier I think.

Like · 6w · Edited



Col Johns It is the old story of Shakespeare's sonnets being (perhaps) written by a million primates on a million typewriters - Ray if you go to India or China and see how power electronics is done .... it 'tis quite unbelievable ....

Like · 6w



Janaki Ram Gopal Pagolu Col Johns I have seen very good power supplies made in India. "unbelievable" in good way or bad way. Just curious :

Like · 6w · Edited



**Col Johns** Let's just be polite and say it is overwhelmingly impressive at what can be achieved with trial and error and very little test gear or formal training. I am sure it is a different story for electronics used in the space programs of the major Asian powers...

Like · 6w



David Edwards . Hello Ray Ridley,

I am sorry if this comes across as bigoted, but such abject ignorance as presented by the thread starter makes me want to slap my forehead very hard while holding a sharply pointed pencil up to it.

In my opinion, someone who doesn't do their homework before posting is spamming the group. Yes, most fresh engineers start out their career journey devoid of experience and perhaps with a store of education that they yet don't intuitively understand, but this is not a beginner's forum. Wangling to get others to one's work is lazy, rude and abusive in my opinion. One should generally make a good attempt at problem solving first before posting (and show what one has tried that has failed).

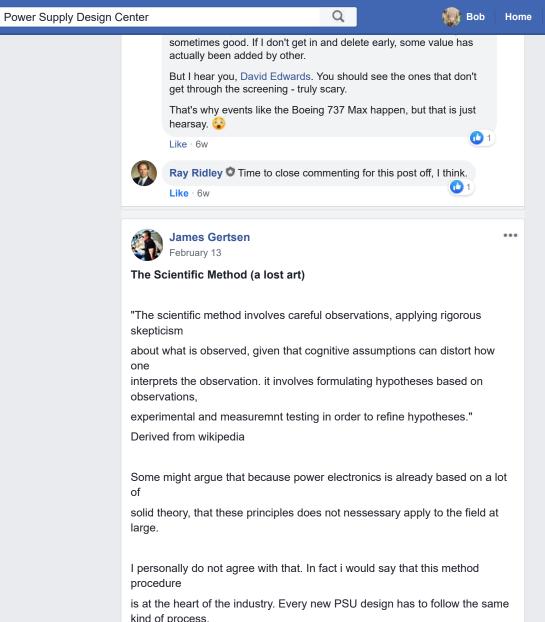
Your forum, your choice (but you asked for feedback).

Like · 6w



Phil Lane Pout / 83%

Like · 6w



kind of process.

first by setting the specifications and deriving the relevant theory. This would be analogous

to formulating the hypothesis. The hypothesis being would the topology and thought up design

solve the task. The next phase is the prototyping and testing, which is analogous to the

experimental and measurement phase. The purpose in both cases are the same, to refine the

hypothesis (that the design works as intended).

Many people have a general assumption that these principles is something everybody in the

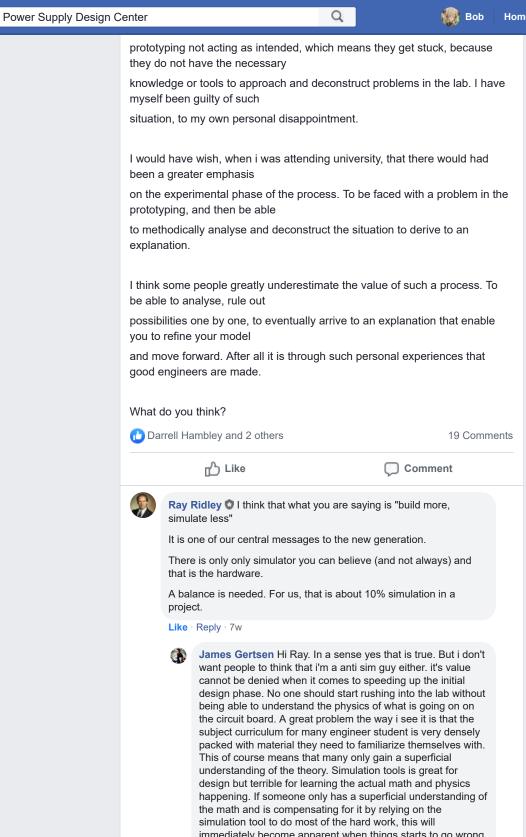
academic world is familiar with. My own experience sadly concludes otherwise, hence the title

of a lost art.

As stated in the top, cognitive assumptions and poor scientific pratice often happens in many

fields of research and engineering. As i have written earlier in this forum, an increasing

overreliance on what computer simulations is capable of, often means that engineers will have less



immediately become apparent when things starts to go wrong in the lab. So i am still a firm believer in that one should be able to have a solid fundamental understanding of the theory on a mathematical and physical level. But to learn that one has to study it in a much longer, more deep and thorough way. The result should be that an engineer understand all of the math that is going on in the simulator, so that it only acts as a tool for doing the calculations faster than one could do on pen and paper or on a calculator.

Like · Reply · 7w